

# Lub A language for Dynamic Context Oriented Programming

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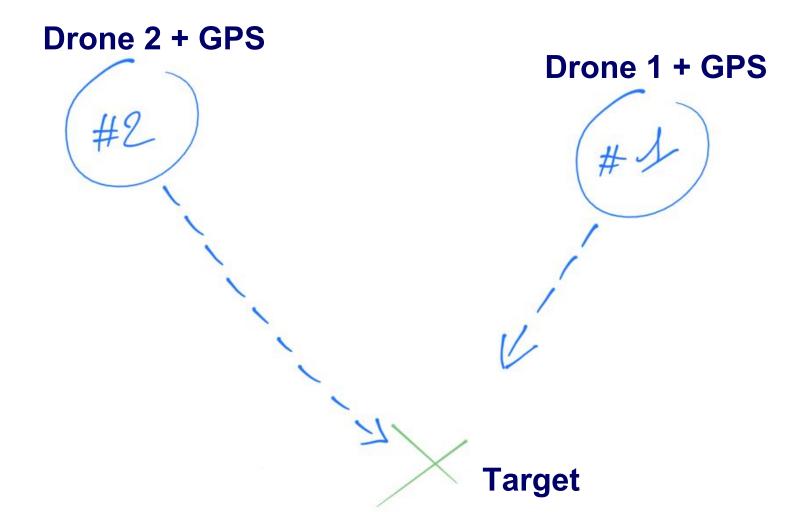












#### Drone 2 NO GPS



Drone 1 + GPS



#### Unanticipated

### Unanticipated

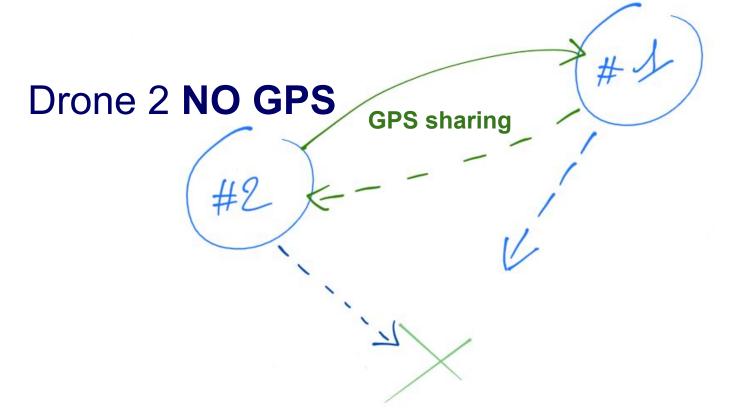
Not foreseen at design time

#### Unanticipated

Not foreseen at design time

The behavior we need was not expected

#### Drone 1 + GPS



## Unanticipated behavior adaptation at runtime

#### Minimal anticipation

### Minimal anticipation

Anticipate the need to face unanticipated adaptation

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Anticipate the need to face unanticipated adaptation

Build Support (frameworks)

## Dynamic context oriented programming (COP)

## What we adapt: Objects

Instance based adaptation

 Adapted object preserve their identity

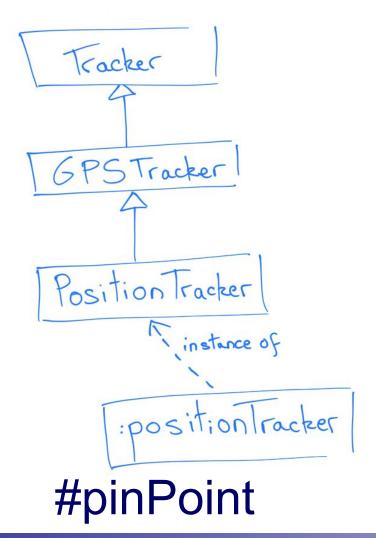
#### How do we adapt?

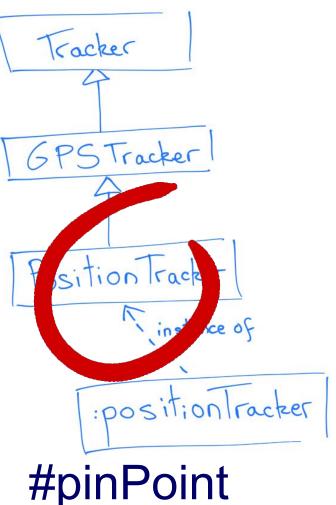
Free adaptation strategy

 Easy and controlled behavior selection

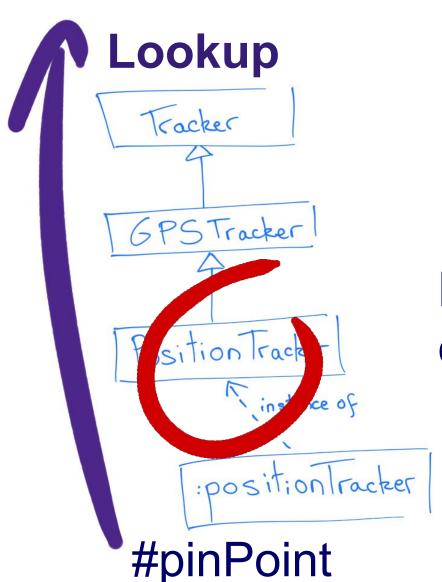
### LUB An extension of Pharo

## Behavior adaptation through dynamic lookup control





Lookup base



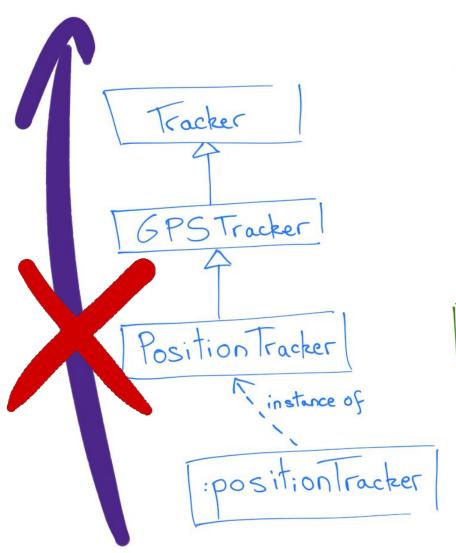
Lookup starts in the object's lookup base

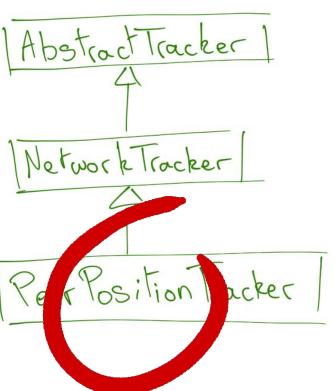
Tracker GPS Tracker :positionTracker

Abstract Tracker

Network Tracker

Peer Position Tracker



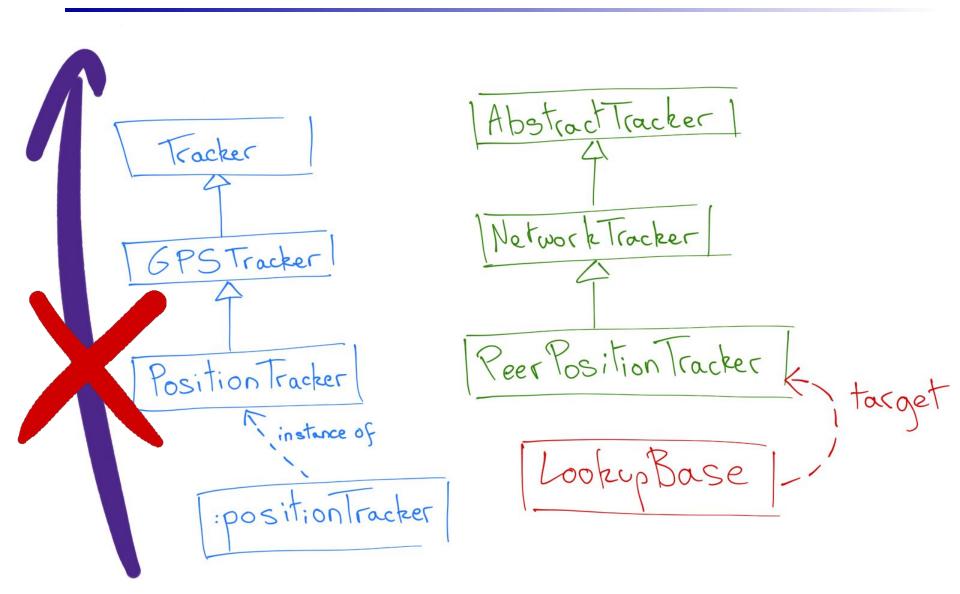


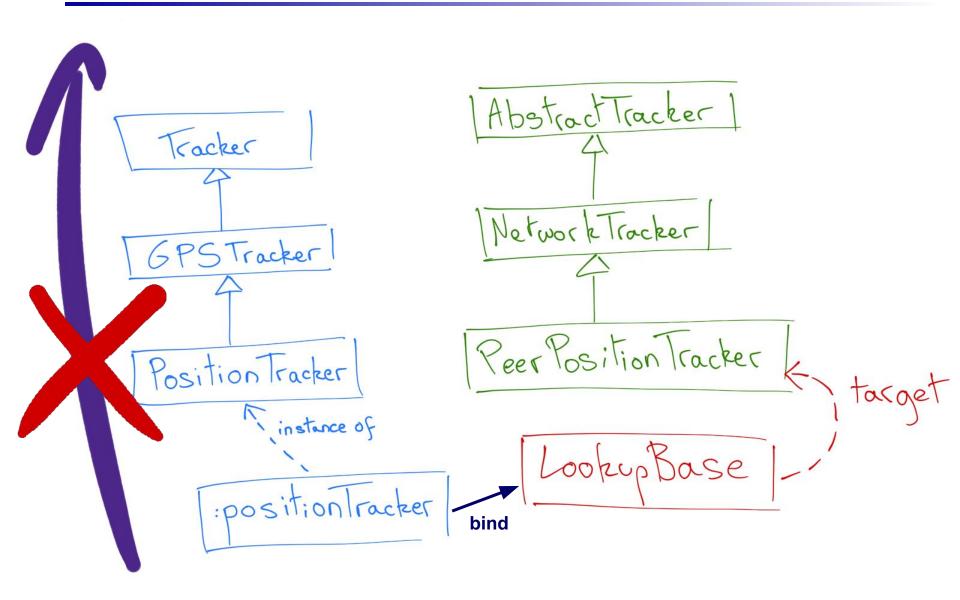
New lookup base

lub := LookupBase

named: 'PeerTrackerLookupBase'

targetClass: PeerPositionTracker





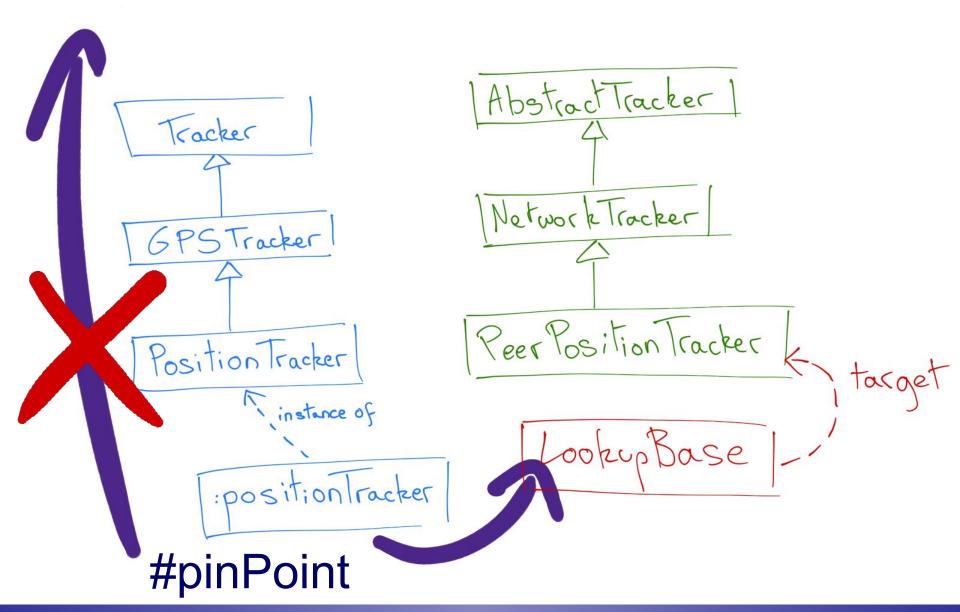
lub := LookupBase

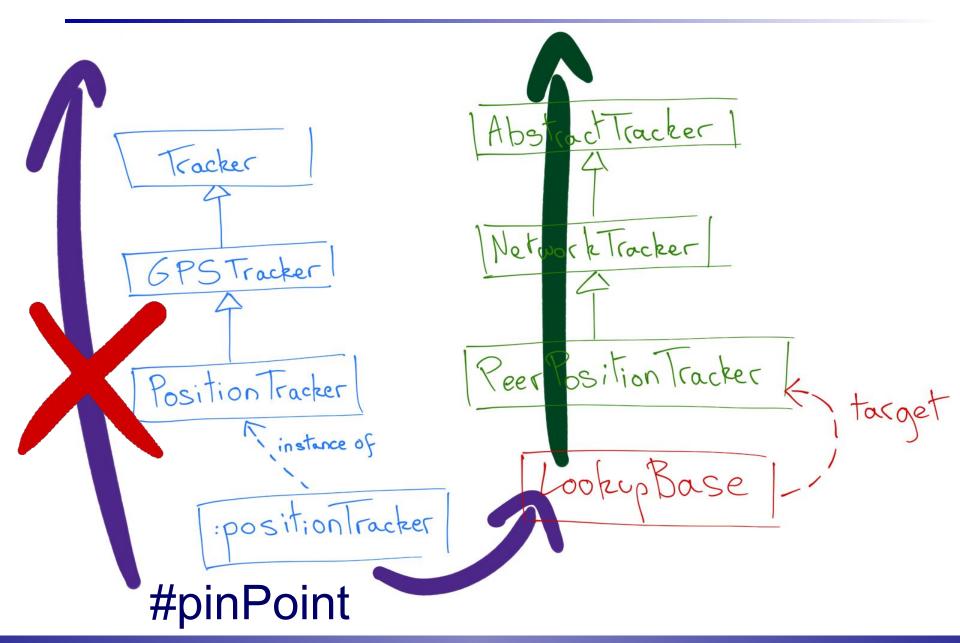
named: 'PeerTrackerLookupBase'

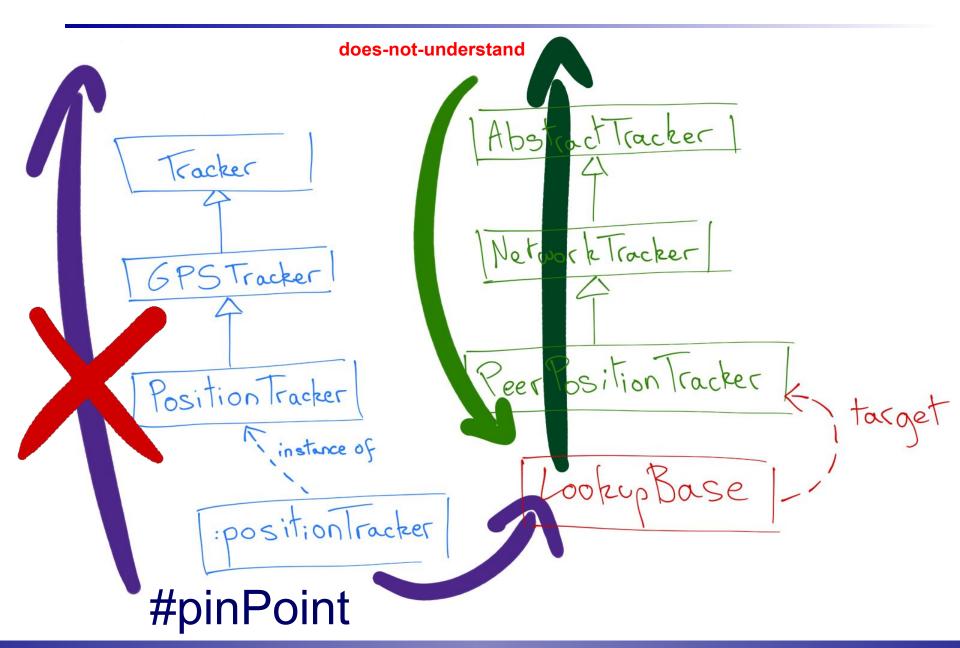
targetClass: PeerPositionTracker

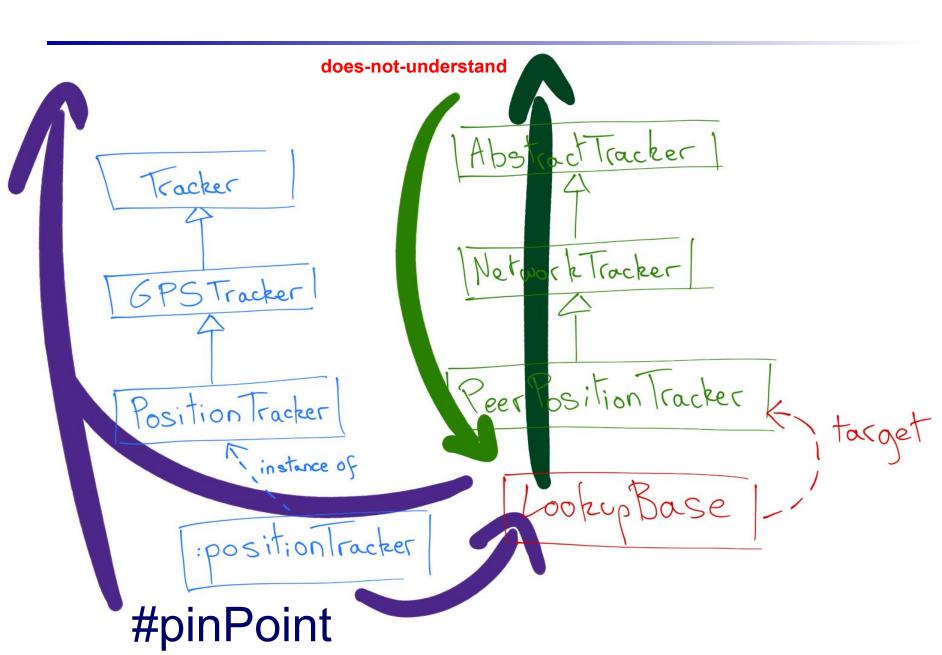
#### positionTracker lookupBase: lub.

positionTracker pinPoint







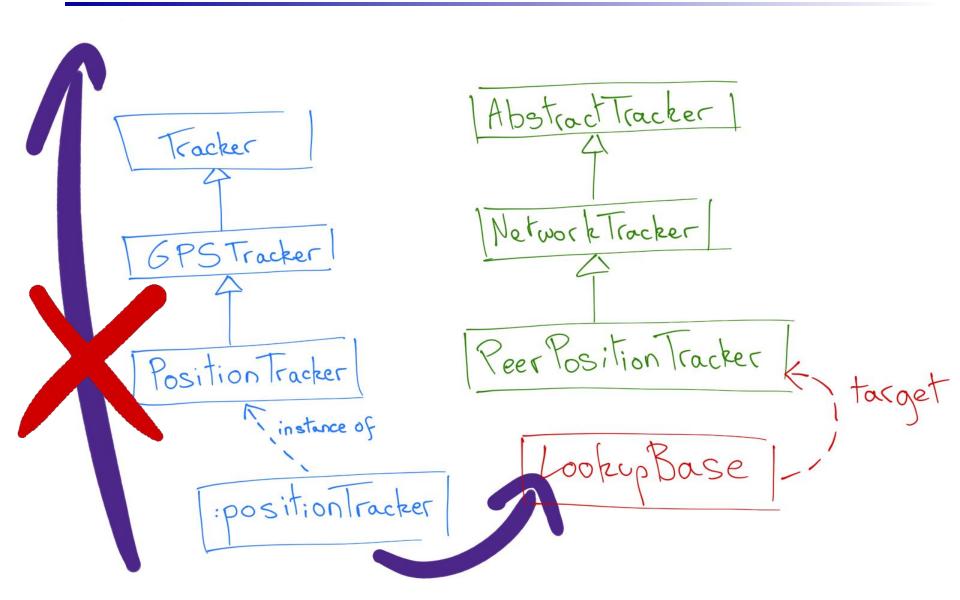


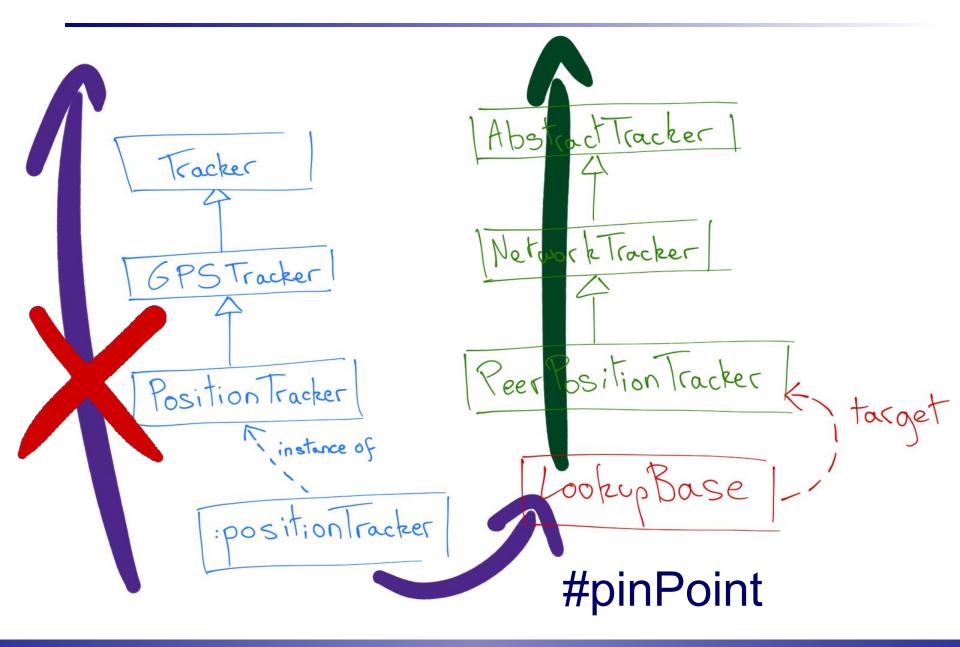
### Selection of the behavior to adapt?

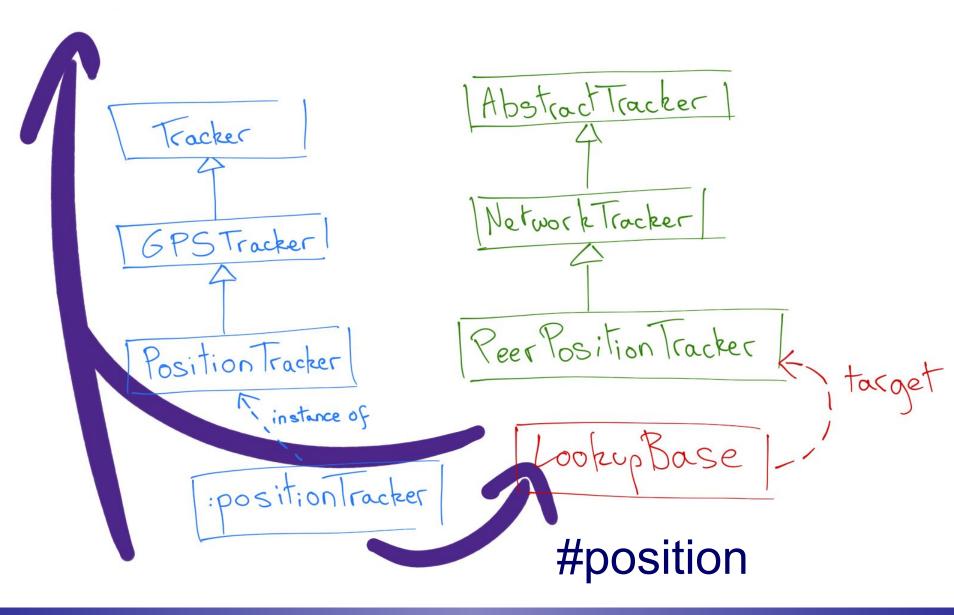
lub := LookupBase
 named: 'PeerTrackerLookupBase'
 targetClass: PeerPositionTracker
 with: #(#pinPoint).

positionTracker lookupBase: lub.

positionTracker pinPoint. positionTracker position.





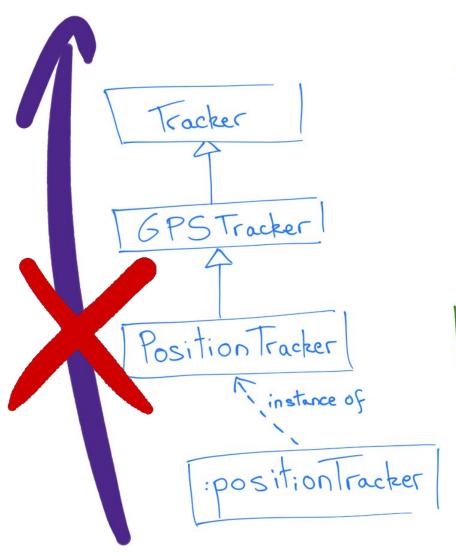


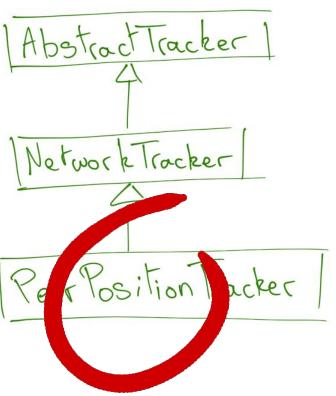
## Binding an object to a meta object that controls the lookup

- Instance based adaptation
- Adapted object preserve their identity
- Free adaptation strategy
- Easy and controlled behavior selection

#### Issues?

### States consistency with an adaptation?





pinpoint
 ^peerTracker pinPoint

### Validation and consistency of the adapted behavior?

### Experiments on a physical device ?



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