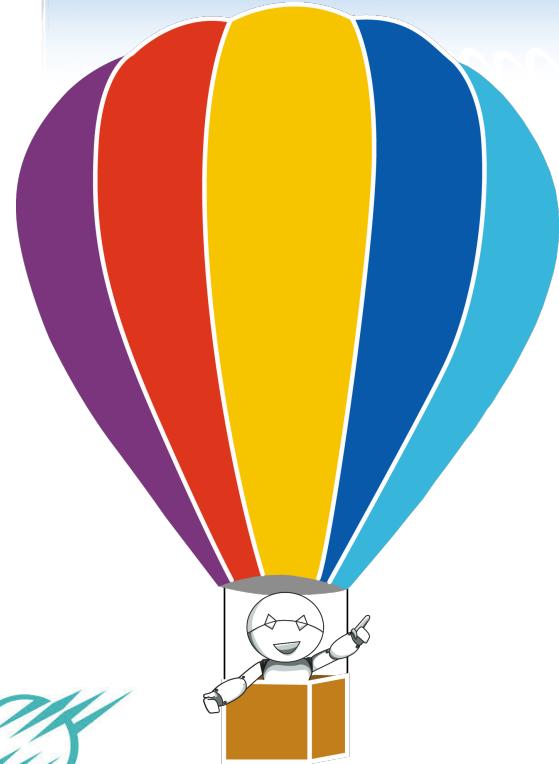


phratch

visual programing for grow up

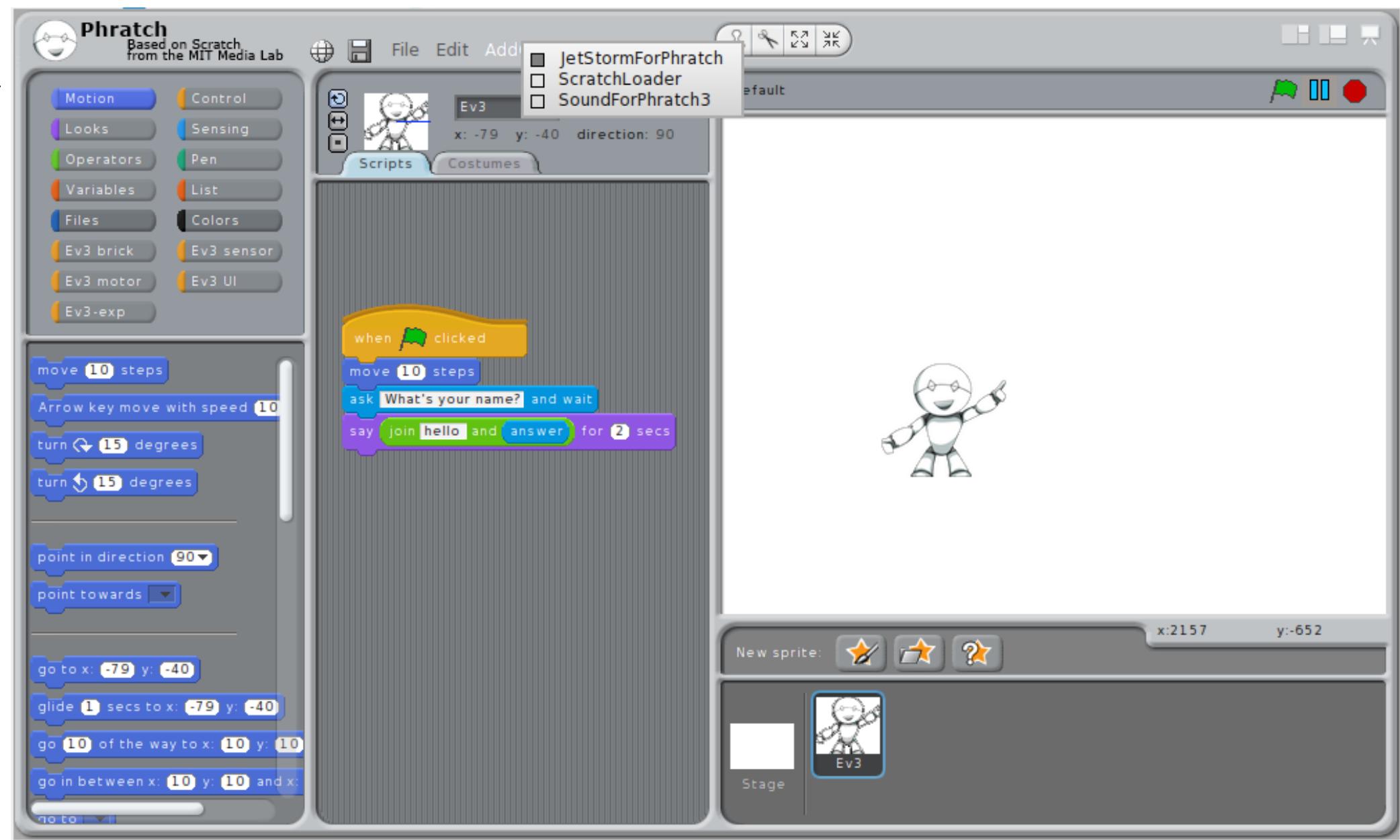


Jannik LAVAL
jannik@phratch.com

<http://www.phratch.com>



You know phratch !



You know phratch !

SCRATCH

on top of
Pharo

<https://code.google.com/p/scat/>

You know phratch !



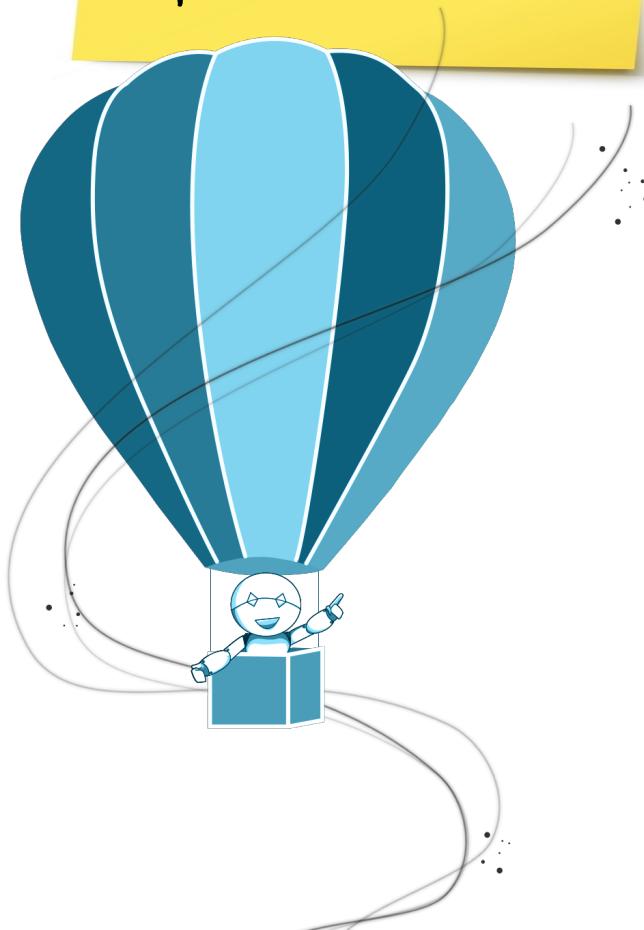
You know phratch !



What is new since ESUG 2013?

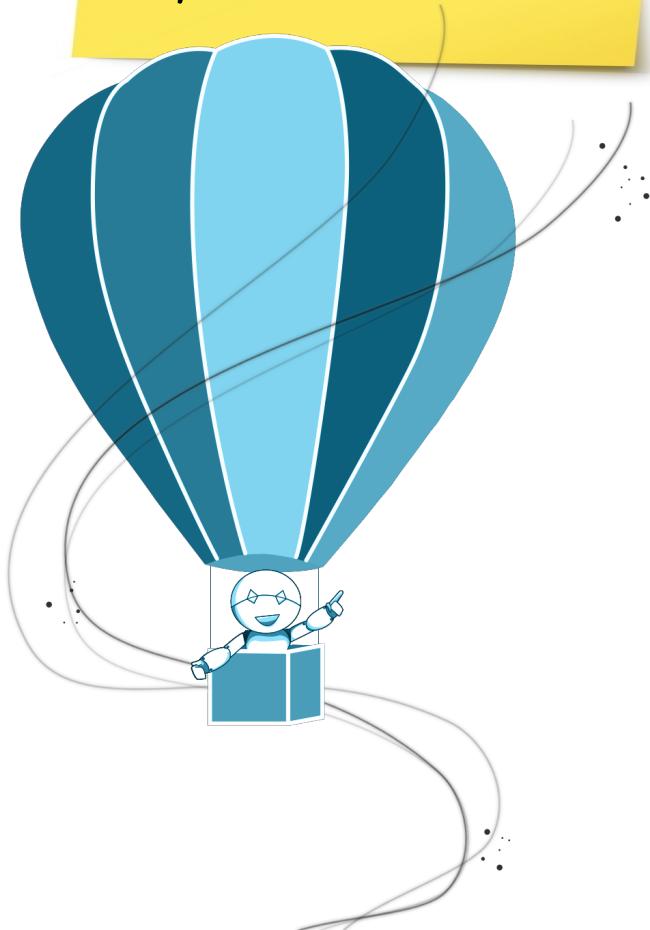
What is new since ESUG 2013?

phratch.com

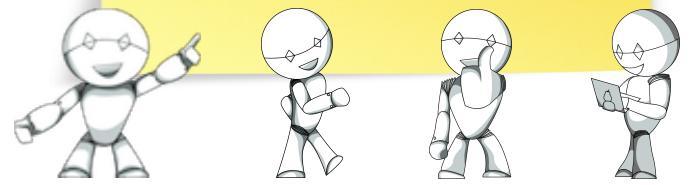


What is new since ESUG 2013?

phratch.com



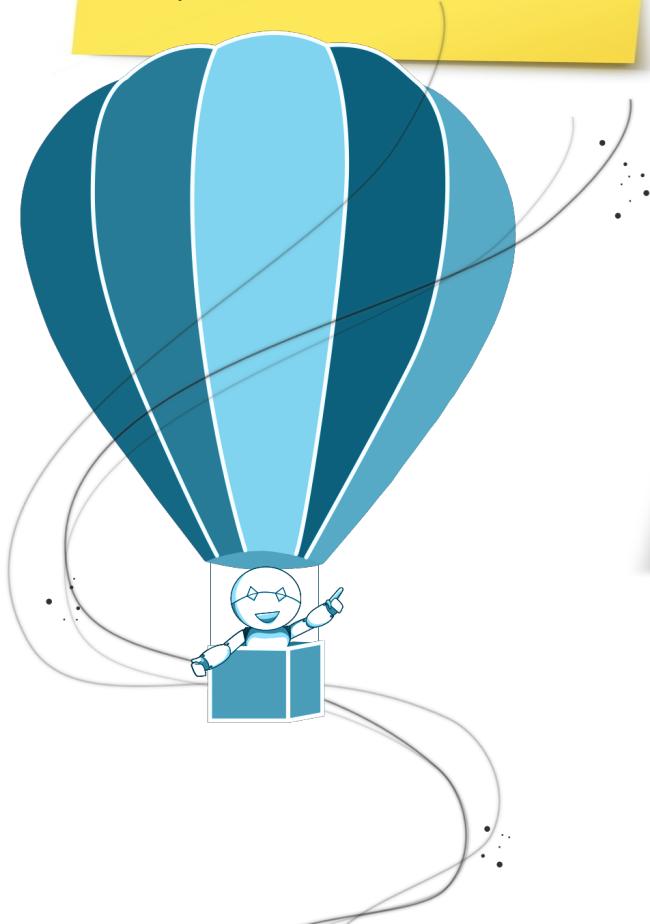
smart icons



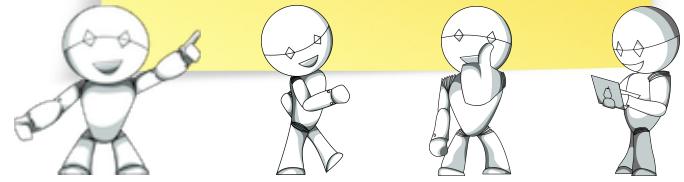
What is new since ESUG 2013?



phratch.com



smart icons

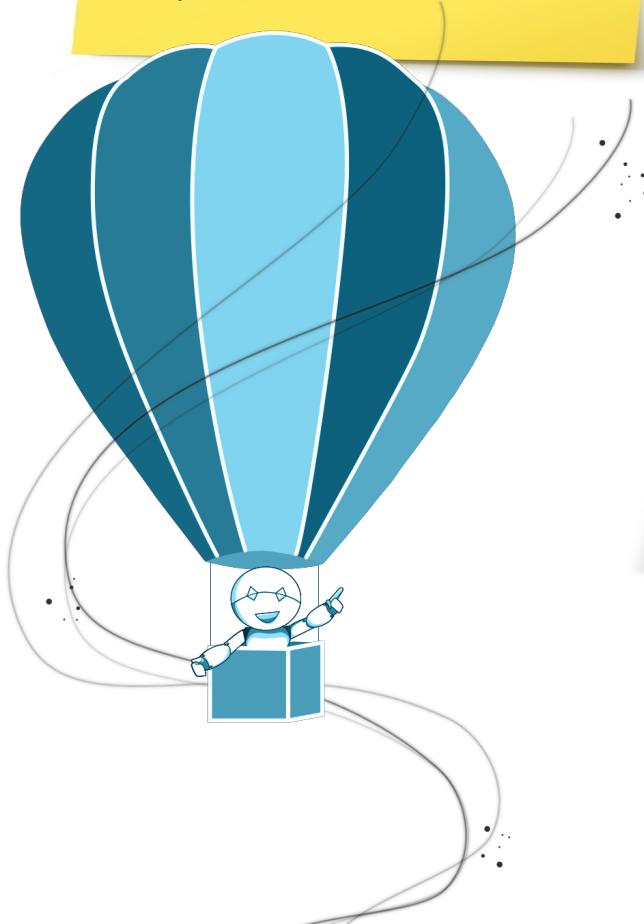


Jenkins

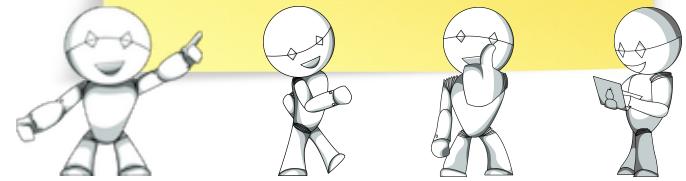
		Phratch-image
		Phratch-OneClick
		Phratch-OneClick-RPi

What is new since ESUG 2013?

phratch.com



smart icons



Jenkins

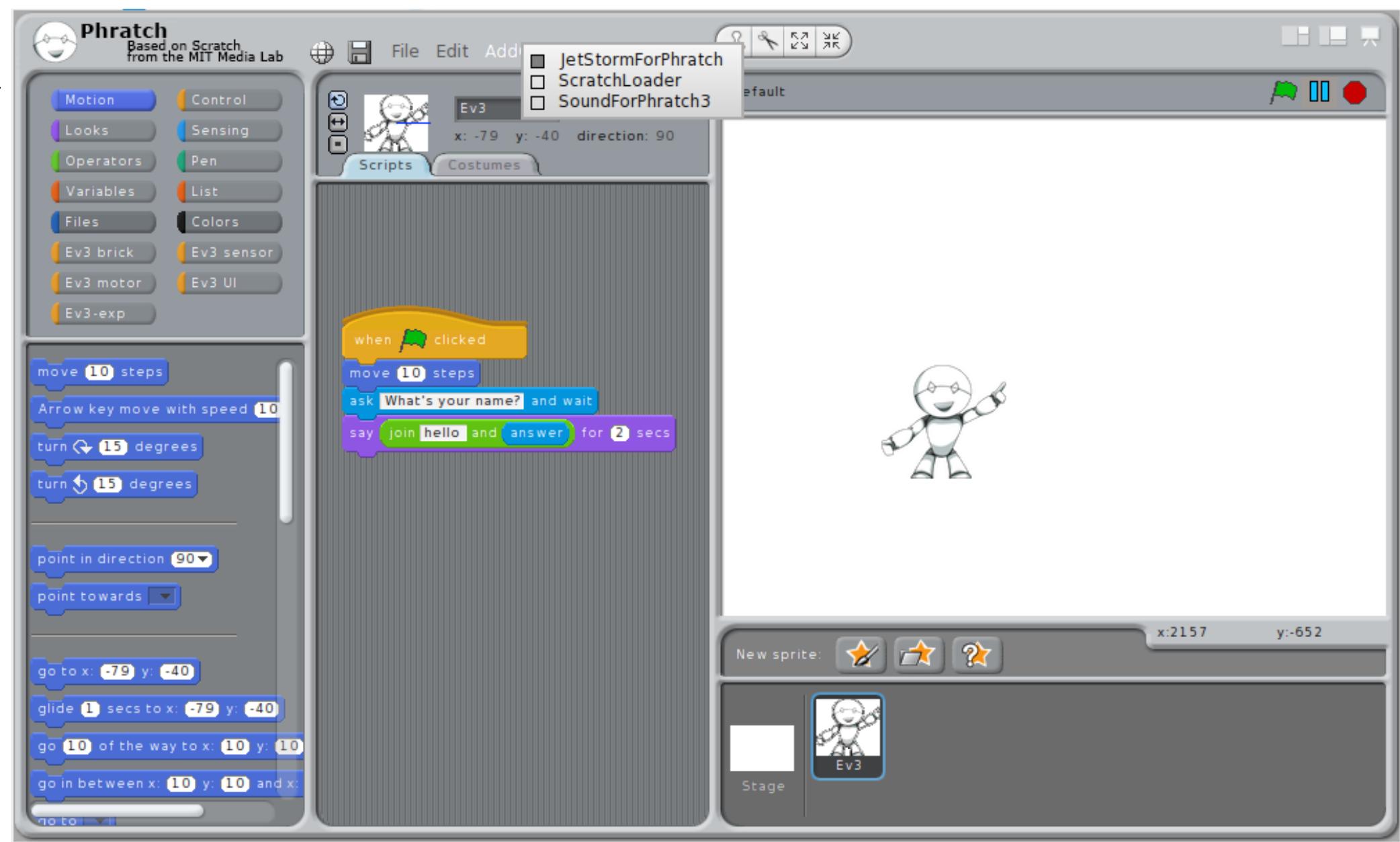
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		Phratch-OneClick
		Phratch-OneClick-RPi

jetstorm -
robotics

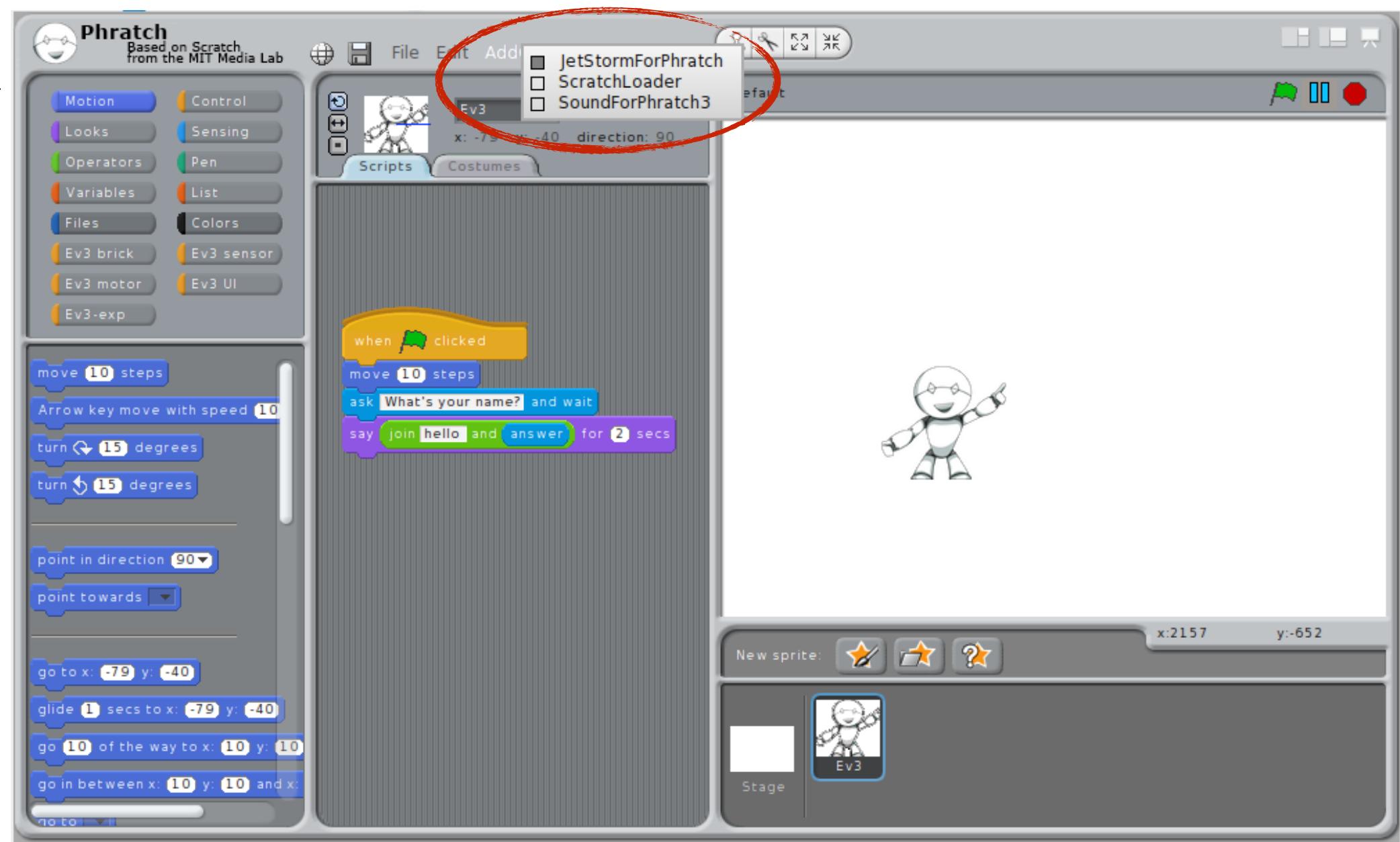


New features: Add-ons

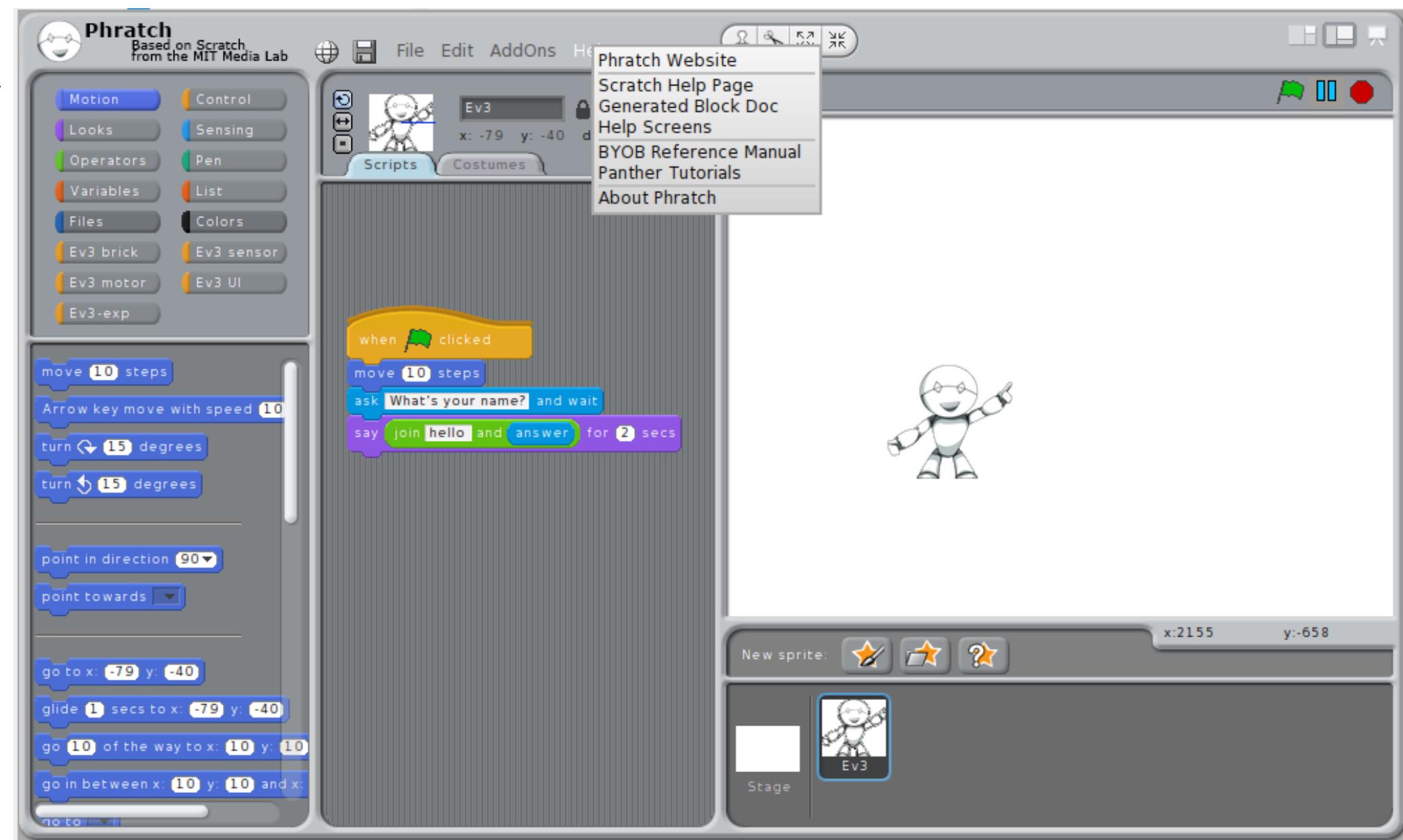
New features: Add-ons



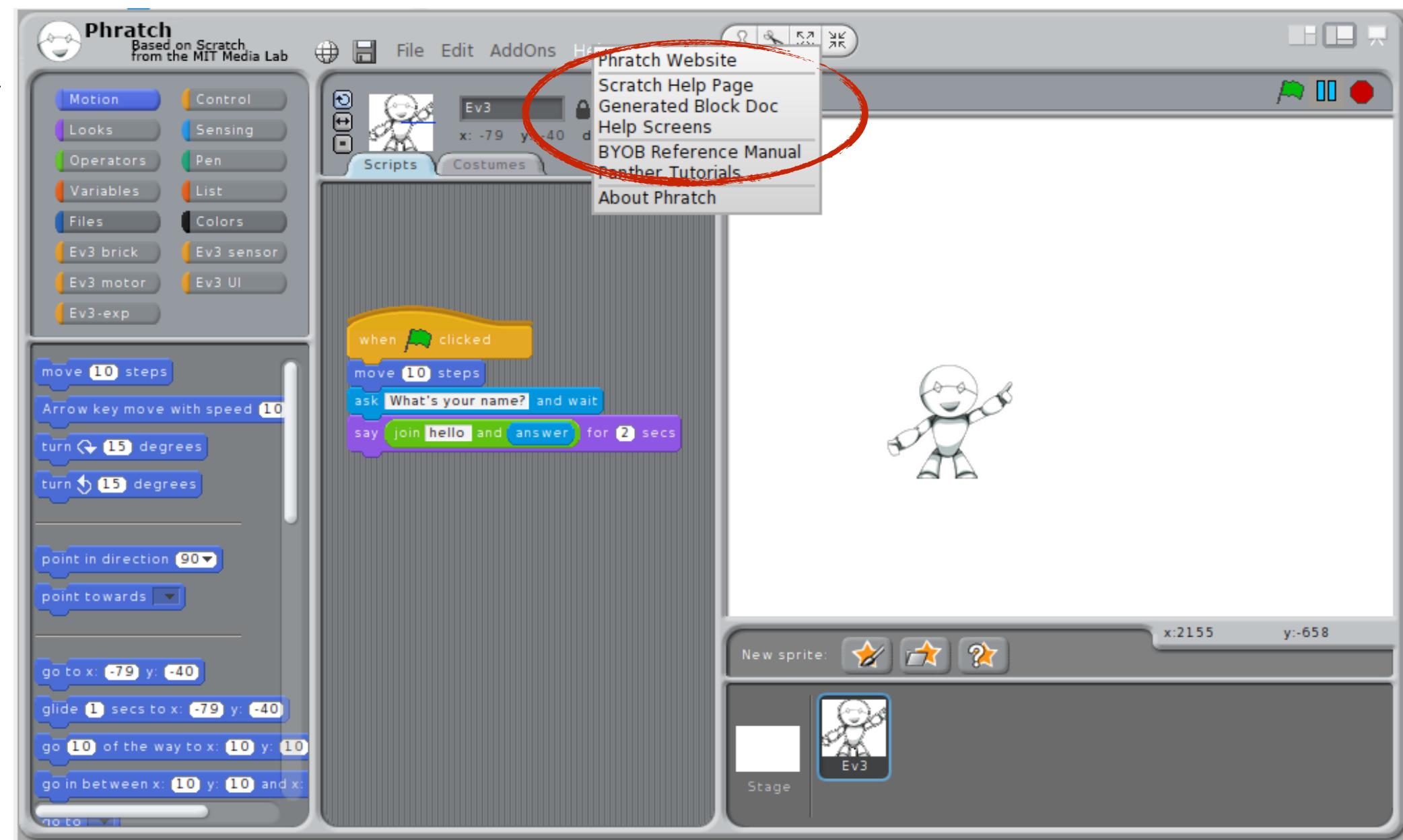
New features: Add-ons



New features: documentation



New features: documentation



New features: documentation

Blocks documentation

Categories



control

	Call the given block with the given args.
	Return the given block without executing it
	Run the given block with the given list of args.
	Return myself
	Send a broadcast message and wait for all receivers finish their work.

New features: documentation

Blocks documentation

Categories

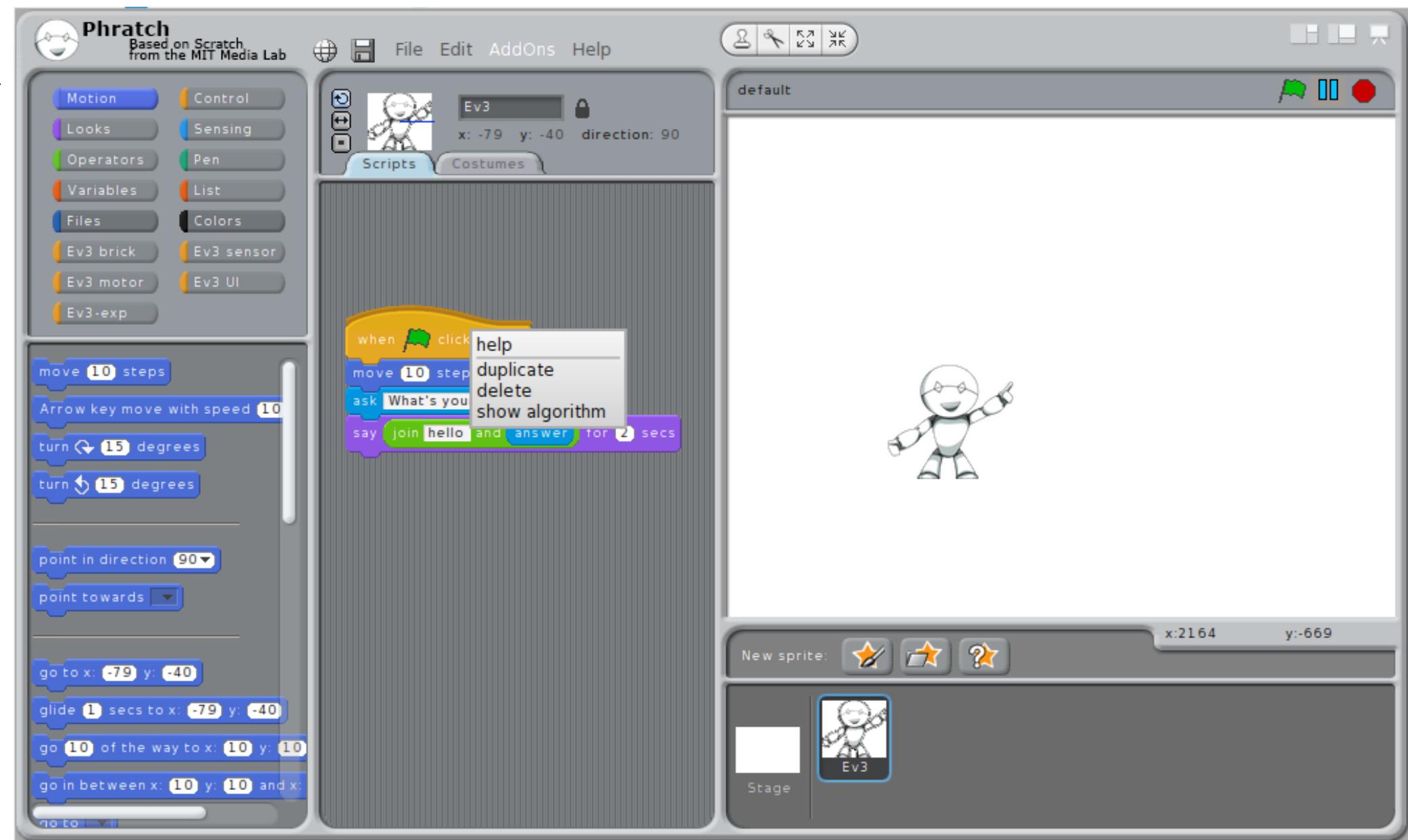


control

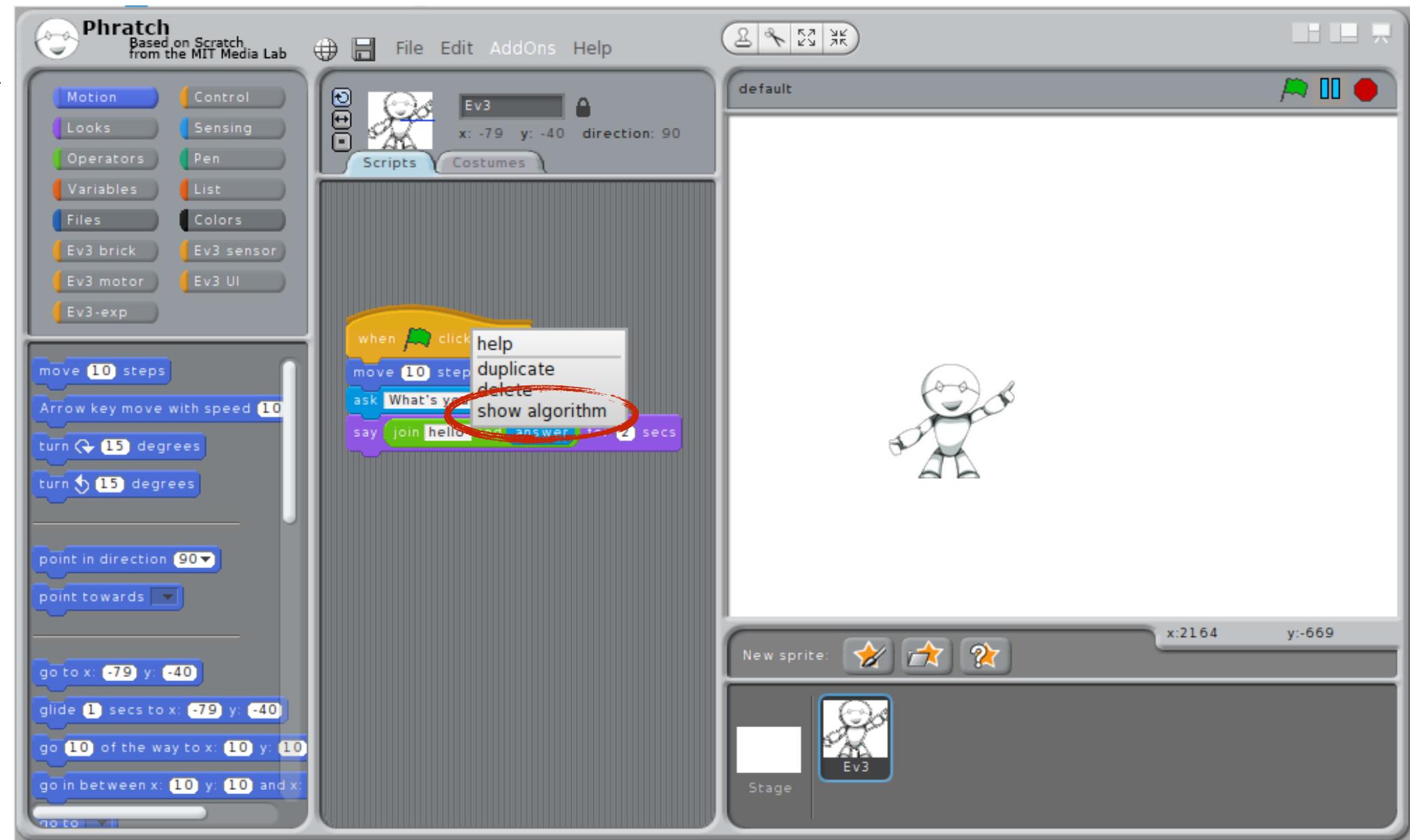
	Call the given block with the given args.
	Return the given block without executing it
	Run the given block with the given list of args.
	Return myself
	Send a broadcast message and wait for all receivers finish their work.

available on
phratch.com

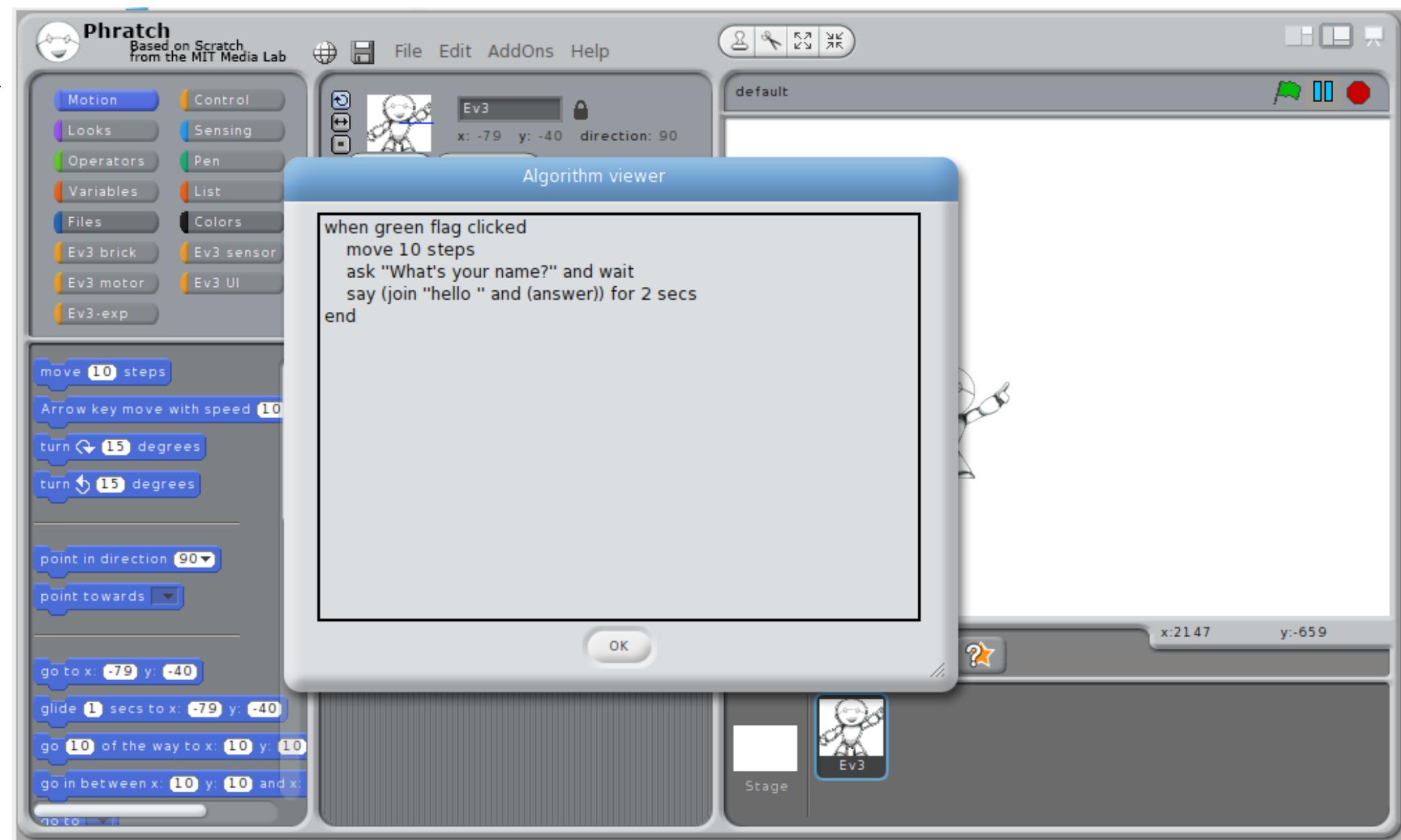
Code accessibility



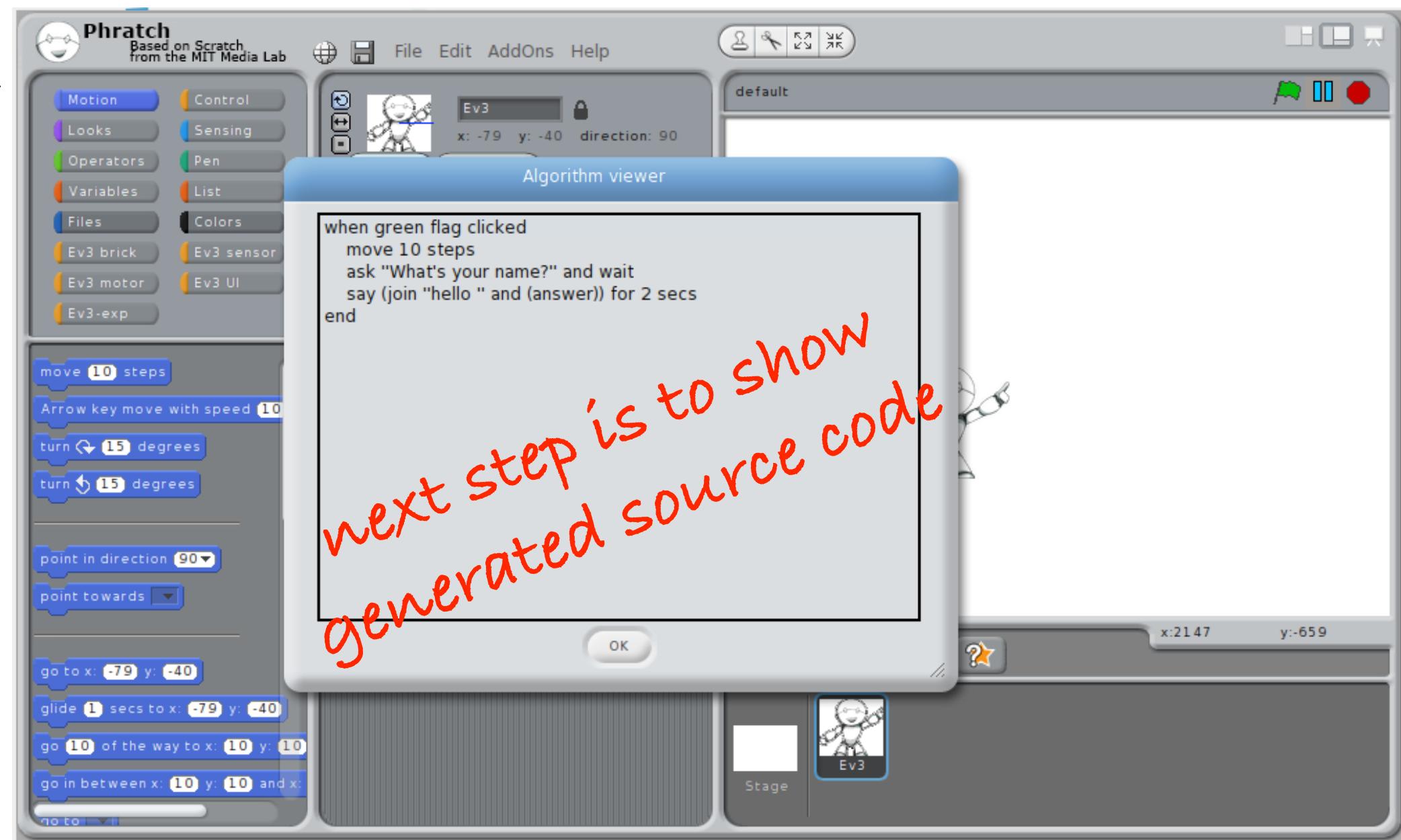
Code accessibility



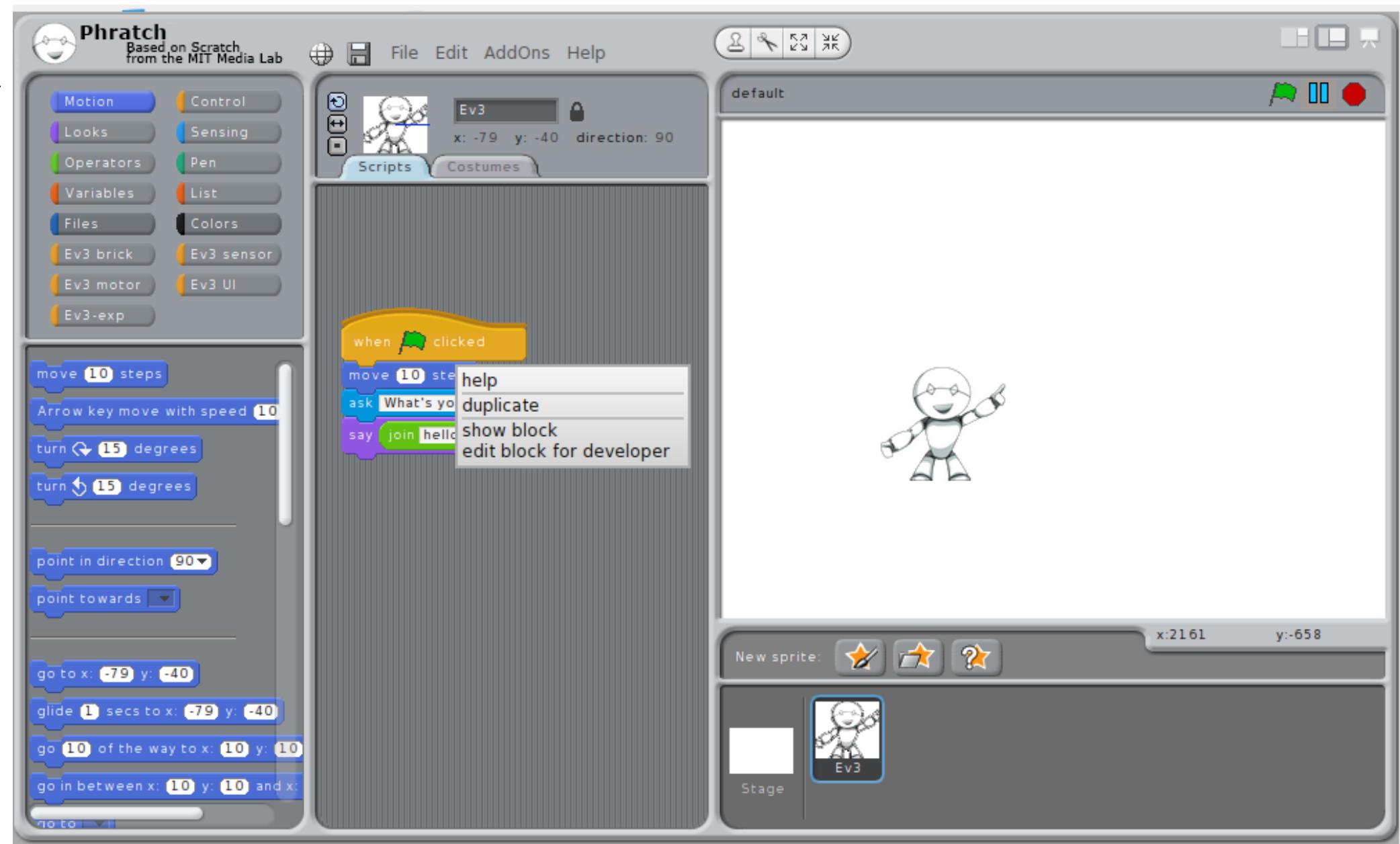
Code accessibility



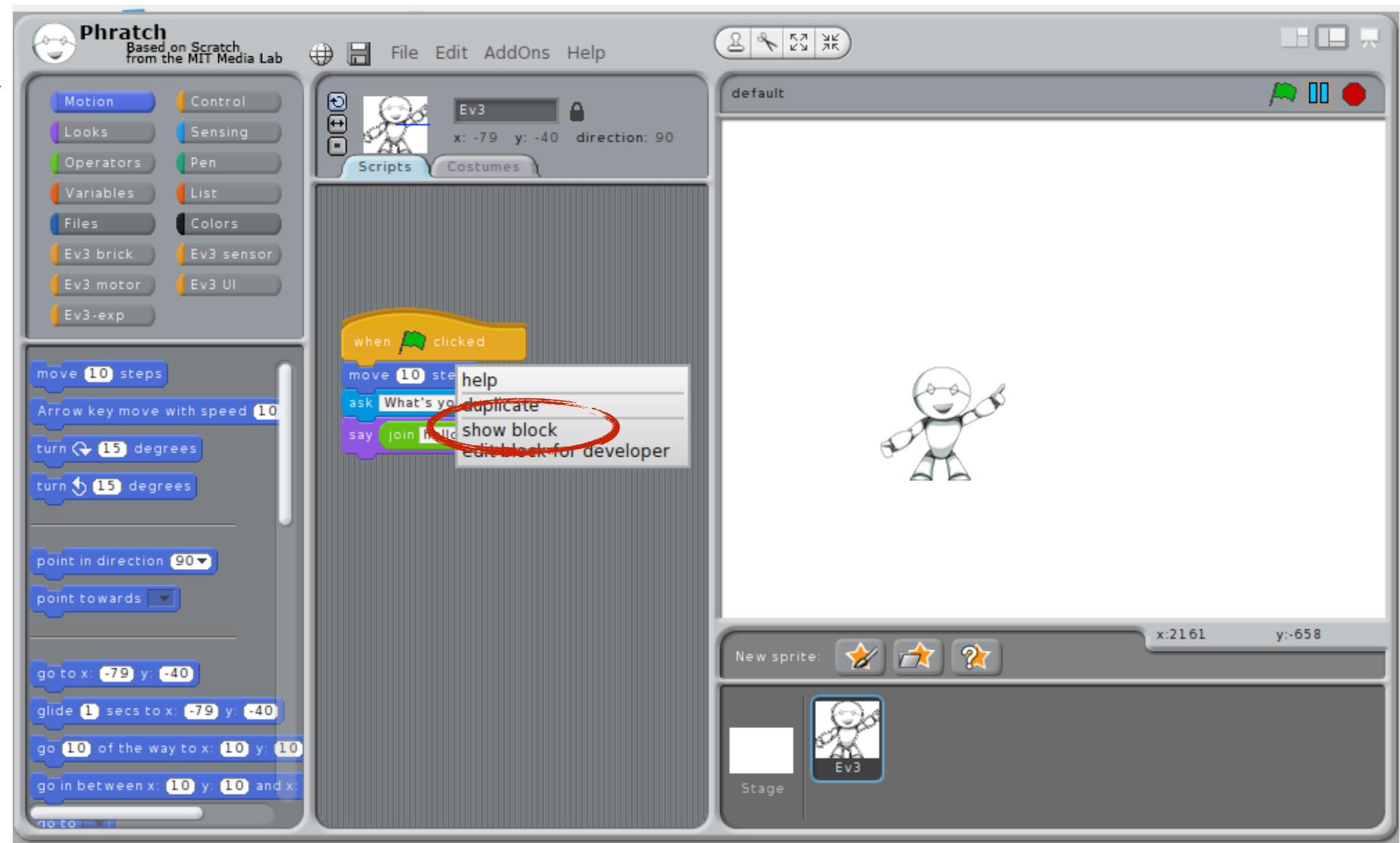
Code accessibility



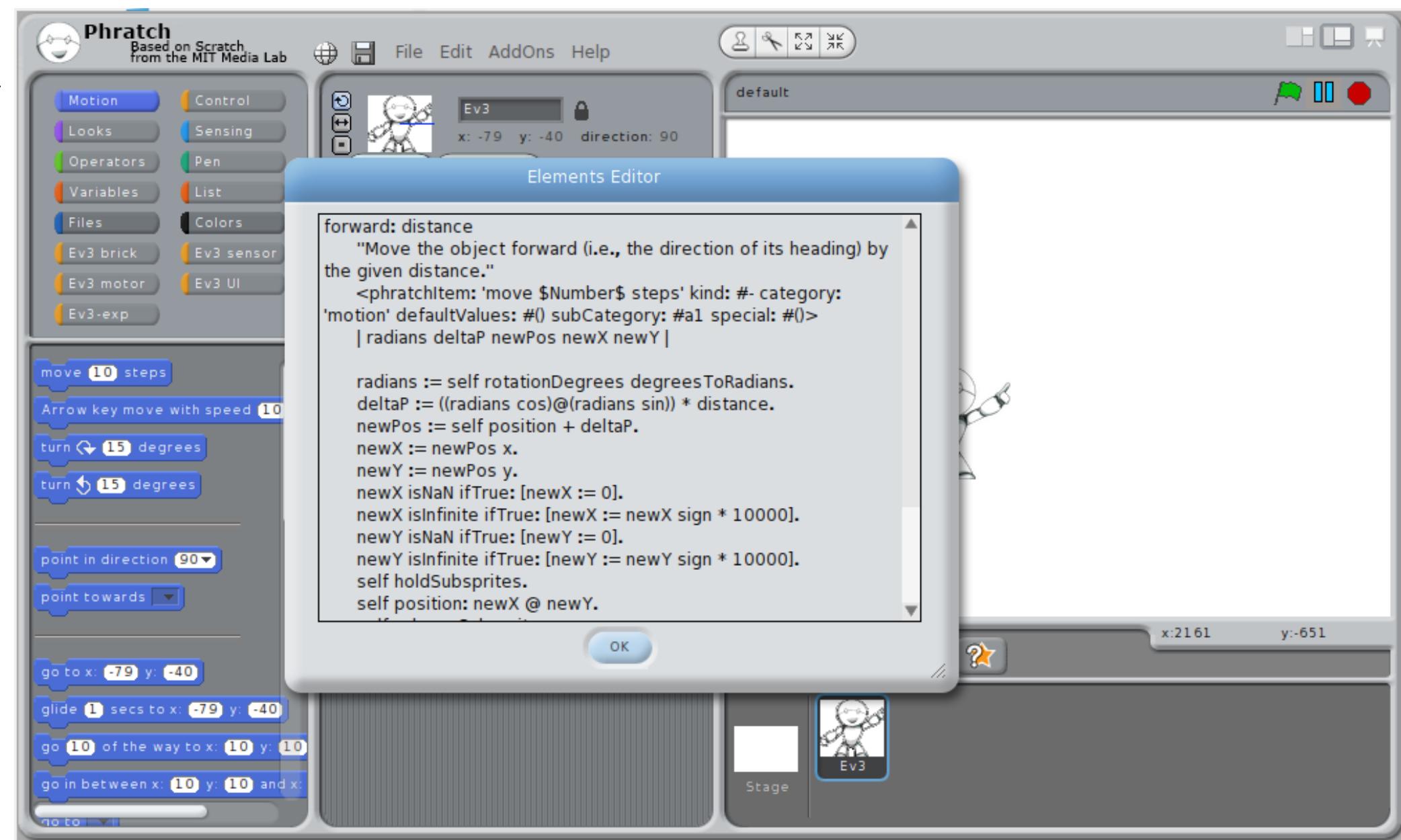
Code accessibility



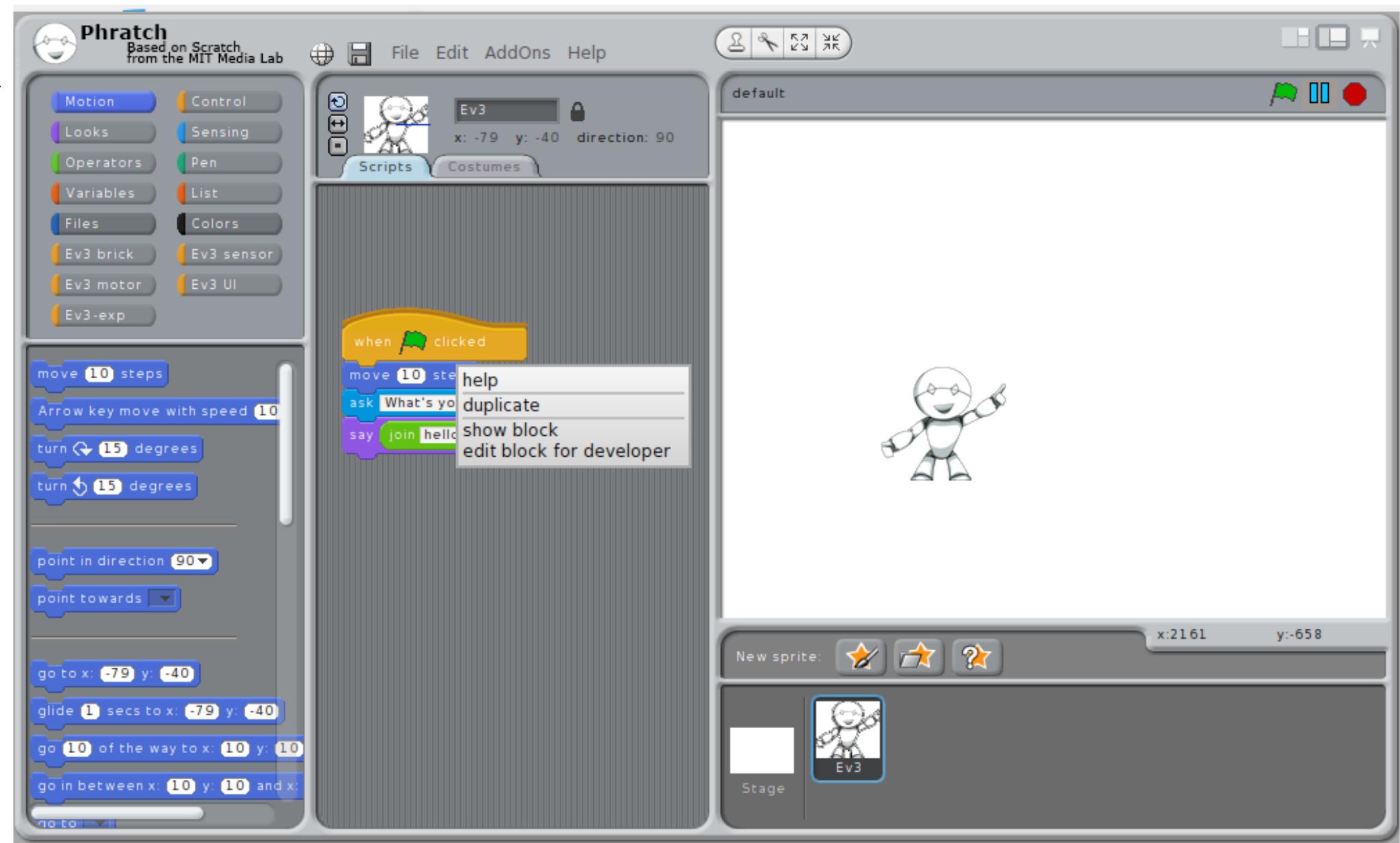
Code accessibility



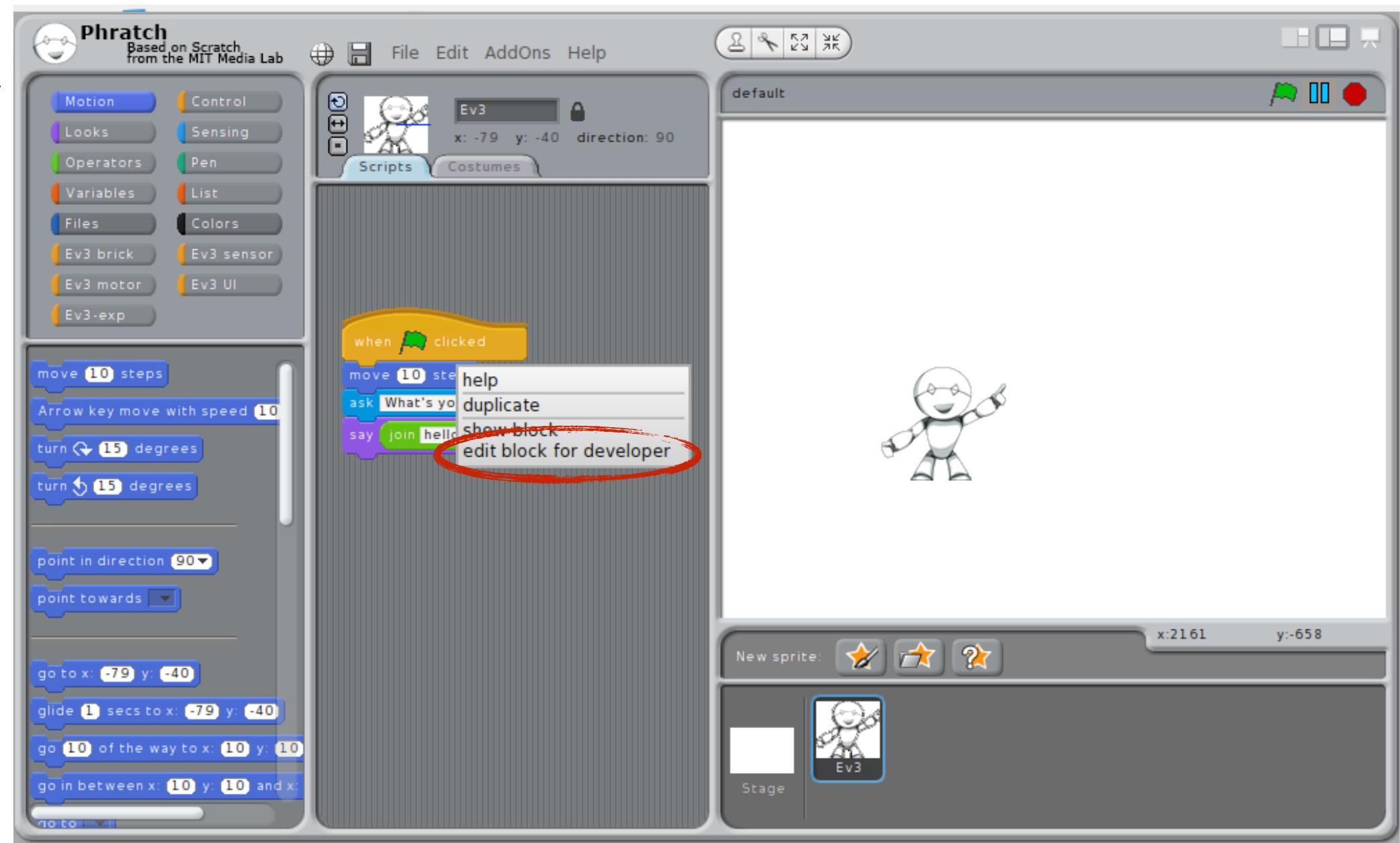
Code accessibility



Code accessibility



Code accessibility



Code accessibility

The screenshot shows the Pharo Smalltalk IDE's class browser for the `PhratchSpriteMorph` class. The browser has several panes:

- Object Browser (left):** Shows a tree of objects under `Type: Pkg1|Pkg2|Pk.*Core$`. The `Objects` node is selected.
- Category Browser (top center):** Shows the category `PhratchSpriteMorph>>#forward:`.
- Category Tree (center):** A tree view of categories including `handle ops`, `initialization`, `looks ops`, etc.
- Method List (right):** A list of methods starting with `arrowMove:`, `betweenX:Y:X:Y:`, `bounceIfBoolean:`, etc.
- Code Editor (bottom):** The `forward: distance` method definition.

Method Definition:

```
forward: distance
"Move the object forward (i.e., the direction of its heading) by the given distance."
<phratchItem: 'move $Number$ steps' kind: #- category: 'motion' defaultValues: #() subCategory: #a1 special: #()>
|radians deltaP newPos newX newY|
radians := self rotationDegrees degreesToRadians.
deltaP := ((radians cos)@(radians sin)) * distance.
newPos := self position + deltaP.
newX := newPos x.
newY := newPos y.
newX isNaN ifTrue: [newX := 0].
newX isInfinite ifTrue: [newX := newX sign * 10000].
newY isNaN ifTrue: [newY := 0].
newY isInfinite ifTrue: [newY := newY sign * 10000].
self holdSubsprites.
self position: newX @ newY.
self releaseSubsprites.
self keepOnScreen.
```

High extensibility !

The screenshot shows the Pharo Smalltalk Inspector interface. The top bar displays the class name: **PhratchSpriteMorph>>#forward:**. The left pane shows the class hierarchy under the heading **Type: Pkg1|Pkg2|Pk.*Core\$**, with **Objects** selected. The right pane lists various message categories and the implementation of the **#forward:** method.

Message Categories:

- handle ops
- initialization
- looks ops
- motion ops
- movie ops
- nesting
- panther actions
- pen ops
- private
- right button menu
- sensing ops
- stepping
- *EV3Phratch
- *PhratchColor
- *PhratchLooks
- *PhratchMotion

Implementation of #forward: distance

"Move the object forward (i.e., the direction of its heading) by the given distance."

```
<phratchItem: >move: #Number! steps! kind: # category: 'motion' defaultValues: #() subCategory: #a1 special: #()>
| radians deltaP newPos newX newY |
radians := self rotationDegrees degreesToRadians.
deltaP := ((radians cos)@(radians sin)) * distance.
newPos := self position + deltaP.
newX := newPos x.
newY := newPos y.
newX isNaN ifTrue: [newX := 0].
newX isInfinite ifTrue: [newX := newX sign * 10000].
newY isNaN ifTrue: [newY := 0].
newY isInfinite ifTrue: [newY := newY sign * 10000].
self holdSubsprites.
self position: newX @ newY.
self releaseSubsprites.
self keepOnScreen.
```

The code is annotated with a red circle around the first few lines and the category header, highlighting the extensibility of the message definition.

High extensibility !

The screenshot shows the Pharo Smalltalk Inspector interface. The top navigation bar indicates the current class is `PhratchSpriteMorph>>#forward:`. The left pane displays a tree view of objects under `Type: Pkg1|Pkg2|Pk.*Core$`, with `Objects` selected. The center pane shows the category browser with categories like handle ops, initialization, looks ops, motion ops, etc. The right pane shows the list of methods for the `#forward:` message, including `arrowMove:`, `betweenX:Y:X:Y:`, `bounceIfBoolean:`, `bounceOffEdge`, etc. A red oval highlights the method definition for `forward:`.

forward: distance
"Move the object forward (i.e., the direction of its heading) by the given distance."
<`phratchItem: 'move $Number$ steps' kind: #- category: 'motion' defaultValues: #() subCategory: #a1 special: #()`>
| radians deltaP newPos newX newY |

```
radians := self rotationDegrees degreesToRadians.  
deltaP := ((radians cos)@(radians sin)) * distance.  
newPos := self position + deltaP.  
newX := newPos x.  
newY := newPos y.  
newX isNaN ifTrue: [newX := 0].  
newX isInfinite ifTrue: [newX := newX sign * 10000].  
newY isNaN ifTrue: [newY := 0].  
newY isInfinite ifTrue: [newY := newY sign * 10000].  
self holdSubsprites.  
self position: newX @ newY.  
self releaseSubsprites.  
self keepOnScreen.
```

496

High extensibility !

The screenshot shows the Pharo Smalltalk Inspector interface for the class `PhratchSpriteMorph`. The left pane displays the class hierarchy under the type `Pkg1|Pkg2|Pk.*Core$`, with `Objects` selected. The right pane shows the category `#forward:` and its implementation.

Category: PhratchSpriteMorph>>#forward:

Implementation:

```
! PhratchList
! PhratchMedia
! CameraMedia
! ImageMedia
! PhratchTranslator
ScriptablePhratchMorph
PhratchSpriteMorph
PhratchStageMorph

handle ops
initialization
looks ops
motion ops
movie ops
nesting
panther actions
pen ops
private
right button menu
sensing ops
stepping
*EV3Phratch
*PhratchColor
*PhratchLooks
*PhratchMotion

arrowMove:
betweenX:Y:X:Y:
bounceIfBoolean:
bounceOffEdge
changeXposBy:
changeYposBy:
distance:X:Y:
forward:
glideSecs:toX:y:elapsed:from
gotoSpriteOrMouse:
makeDrag
makeNoDrag
pointToX:y:
pointTowards:
randxypos
```

Method: `forward: distance`

"Move the object forward (i.e., the direction of its heading) by the given distance."

```
<phratchItem: 'move $Number$ steps' kind: #- category: 'motion' defaultValues: #() subCategory: #a1 special: #()>
|radians deltaP newPos newX newY|
move 10 steps
radians := self radiansFromDegrees degreesToRadians.
deltaP := ((radians cos)@(radians sin)) * distance.
newPos := self position + deltaP.
newX := newPos x.
newY := newPos y.
newX isNaN ifTrue: [newX := 0].
newX isInfinite ifTrue: [newX := newX sign * 10000].
newY isNaN ifTrue: [newY := 0].
newY isInfinite ifTrue: [newY := newY sign * 10000].
self holdSubsprites.
self position: newX @ newY.
self releaseSubsprites.
self keepOnScreen.
```

A red circle highlights the message `move 10 steps` in the code editor.

High extensibility !

Type: Pkg1|^Pkg2|Pk.*Core\$

Categories

- DefaultArguments
- Error-Management
- Execution Engine
- Installation
- Object IO
- Objects
- Paint
- Plugins
- Tests
- Type
- UI-Dialogs
- UI-Panes
- UI-Support
- UI-Watchers
- PhratchColor
- PhratchDebugger
- PhratchFile
- PhratchList
- PhratchLooks
- PhratchMotion
- PhratchPen
- PhratchSensing

PhratchCategory class>>#label

ProtoObject

Object

PhratchCategory

PhratchCategoryColors

PhratchCategoryControl

PhratchCategoryCustom

PhratchCategoryEv3Brick

PhratchCategoryEv3More

PhratchCategoryEv3Motor

PhratchCategoryEv3Sensor

PhratchCategoryEv3UI

PhratchCategoryFiles

PhratchCategoryList

PhratchCategoryLooks

PhratchCategoryMotion

PhratchCategoryNone

PhratchCategoryOperators

PhratchCategoryOther

PhratchCategoryPen

PhratchCategorySensing

PhratchCategoryVariables

-- all --

accessing

drawing

blockColorFor:

- color
- initialize
- label
- objectInterface
- order
- viewerPageFor:
- visible
- visible:

Groups Flat Class side Comments PhratchCategory class >>#label

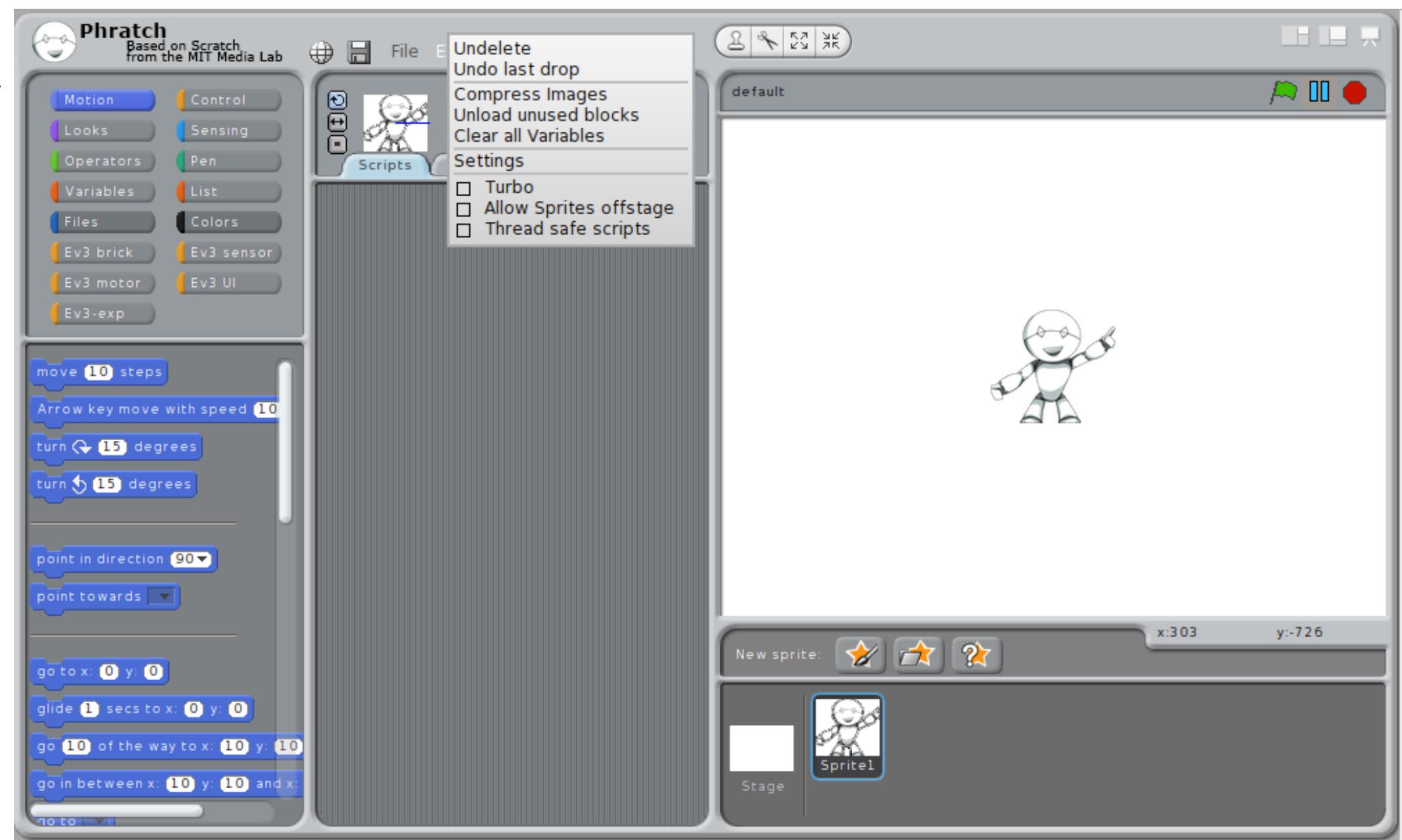
label

^'Generic Category'

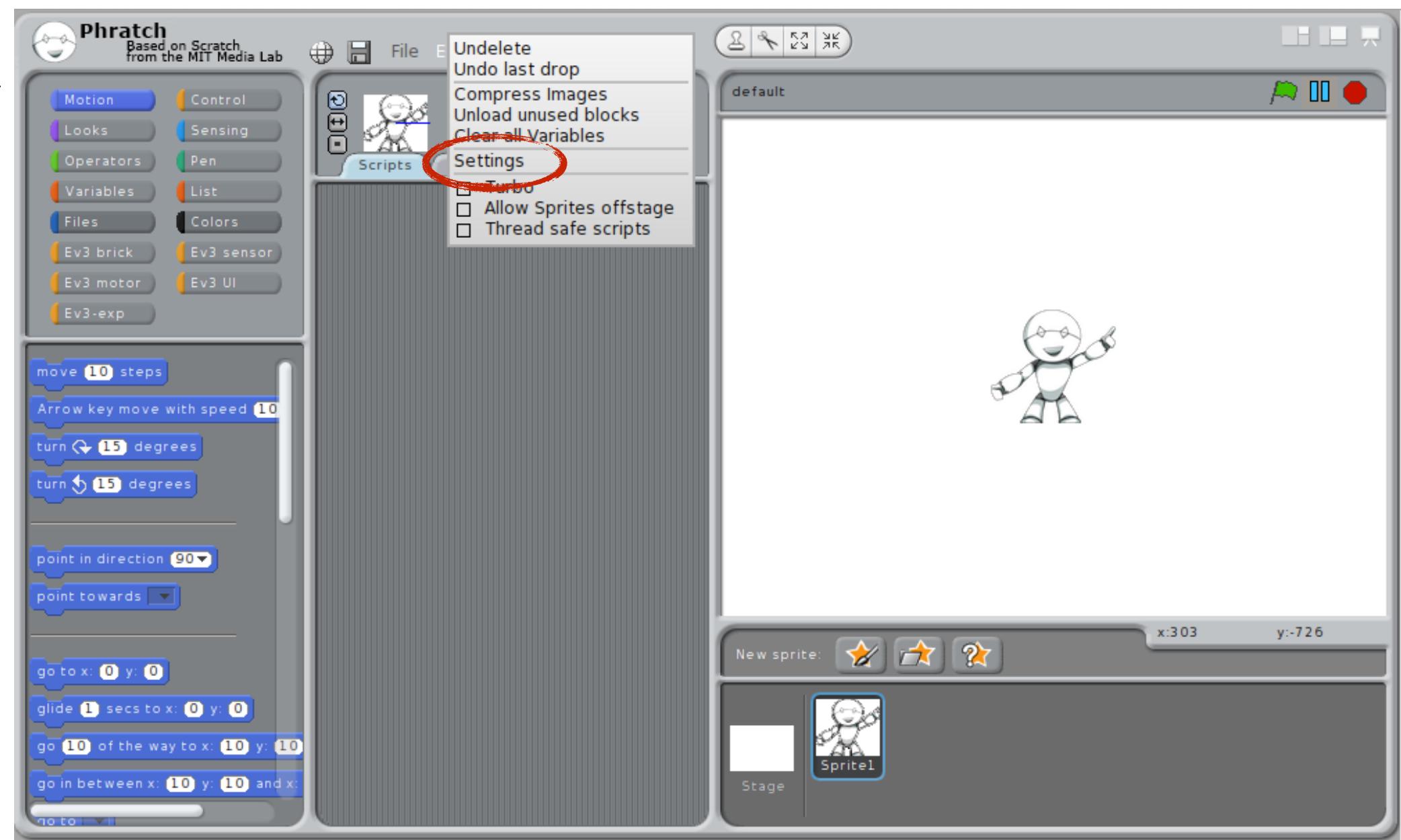
21

The screenshot shows a software interface for managing categories. On the left, there's a sidebar with various category names like 'DefaultArguments', 'Error-Management', etc. Below that is a tree view with nodes like 'PhratchColor', 'PhratchDebugger', etc. In the center, there's a main pane titled 'PhratchCategory class>>#label'. This pane has three columns: 'Categories' (listing 'ProtoObject', 'Object', and 'PhratchCategory'), '-- all --' (listing 'accessing' and 'drawing'), and 'blockColorFor:' (listing 'color', 'initialize', 'label', 'objectInterface', 'order', 'viewerPageFor:', 'visible', and 'visible:'). At the bottom, there are tabs for 'Groups', 'Flat', 'Class side' (which is selected), and 'Comments'. A status bar at the bottom right shows the number '21'. On the far right, there's a vertical toolbar with icons for lock, file, info, and copy.

Customization



Customization



Customization

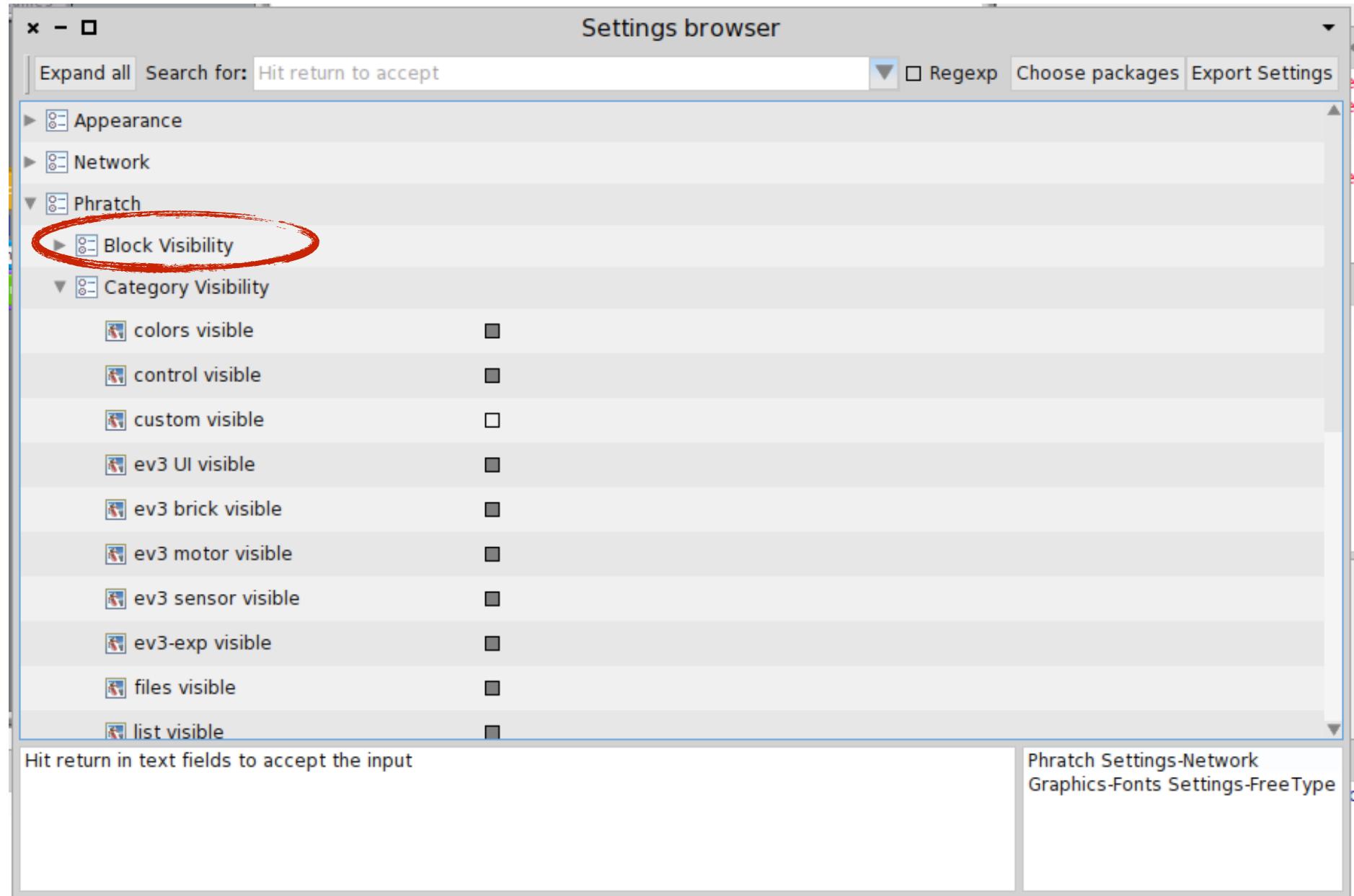
Settings browser

Expand all Search for: Hit return to accept ▾ Regexp Choose packages Export Settings

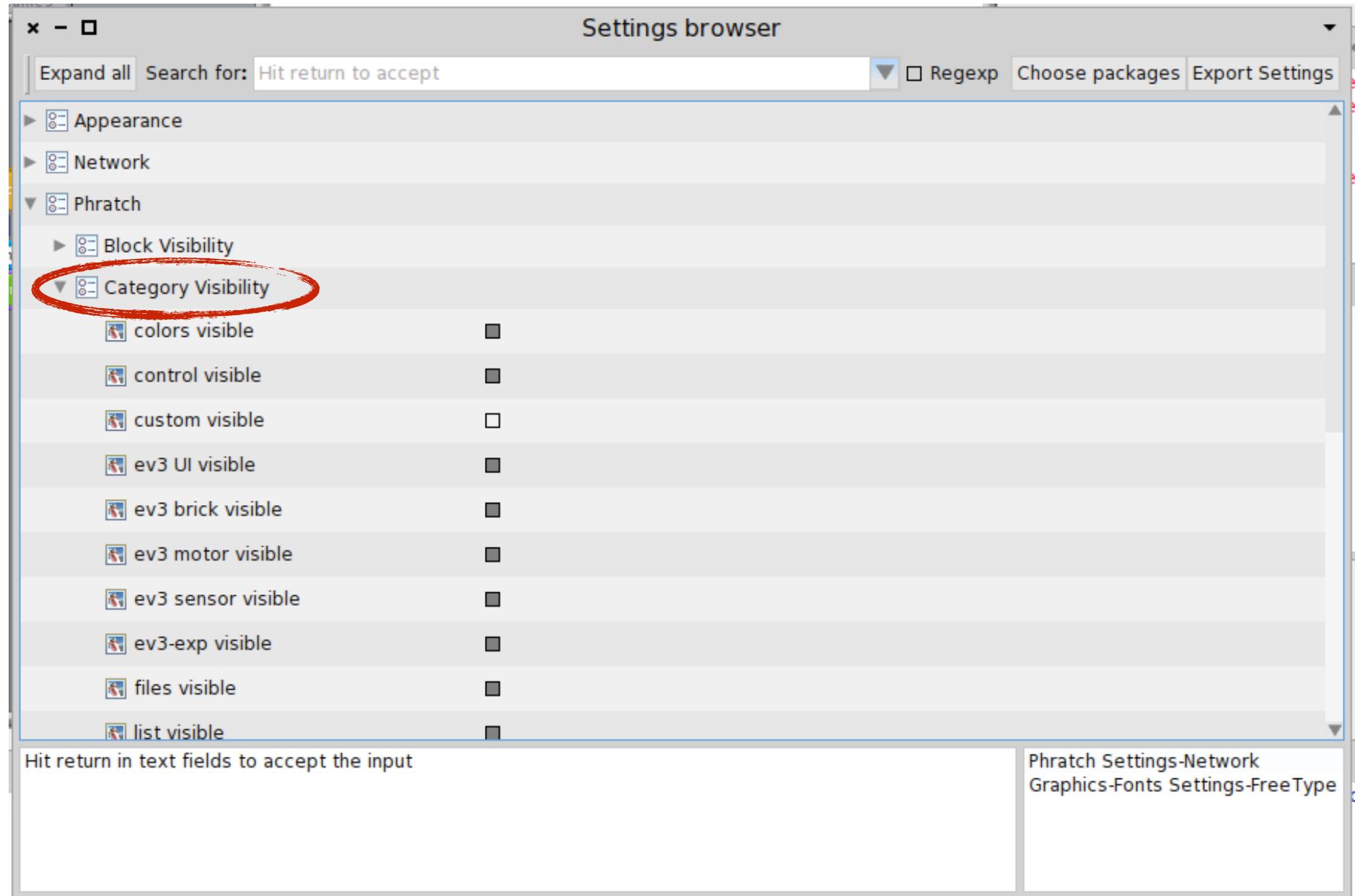
- ▶ Appearance
- ▶ Network
- ▼ Phratch
 - ▶ Block Visibility
 - ▼ Category Visibility
 - colors visible
 - control visible
 - custom visible
 - ev3 UI visible
 - ev3 brick visible
 - ev3 motor visible
 - ev3 sensor visible
 - ev3-exp visible
 - files visible
 - list visible

Hit return in text fields to accept the input

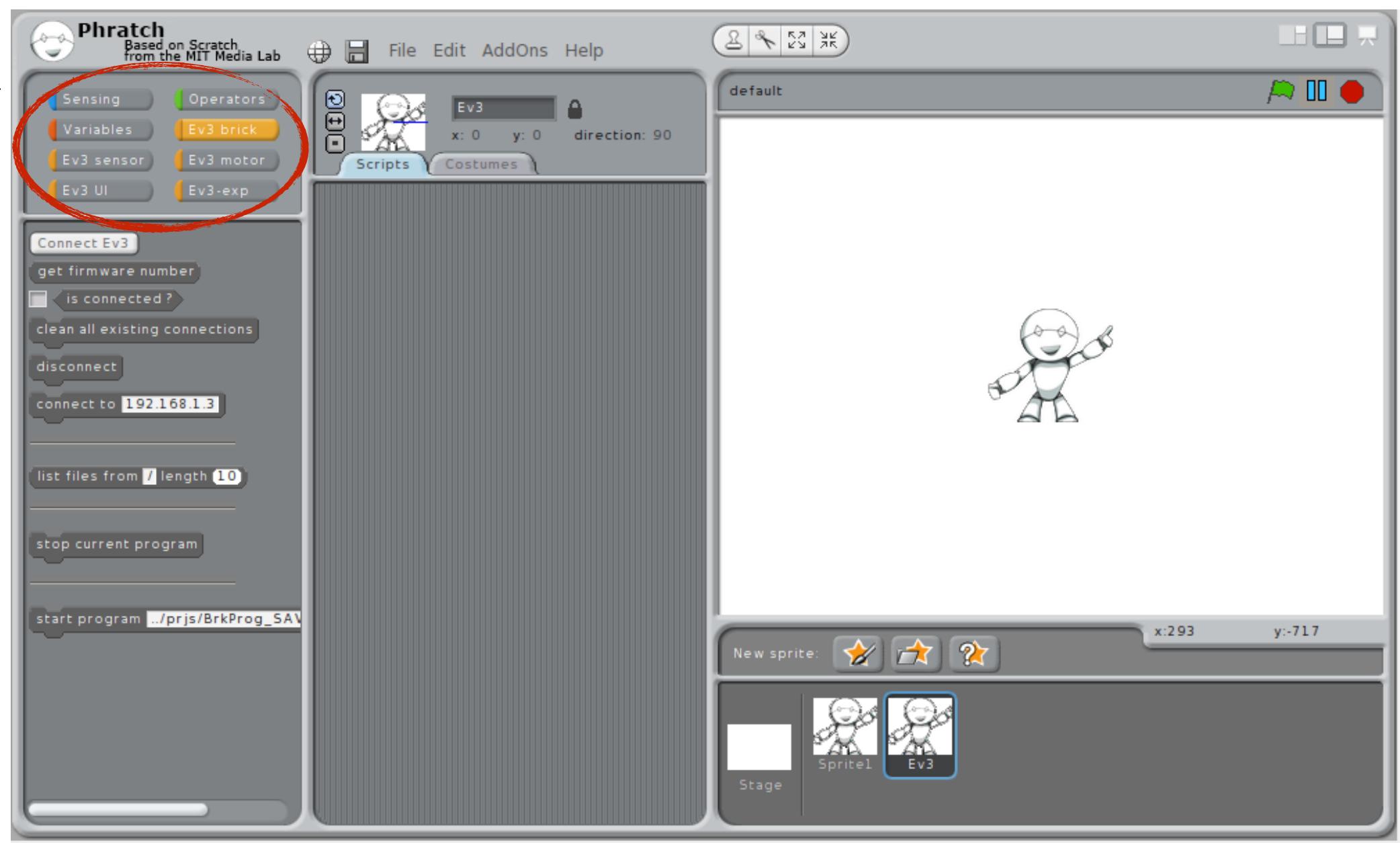
Phratch Settings-Network
Graphics-Fonts Settings-FreeType



Customization

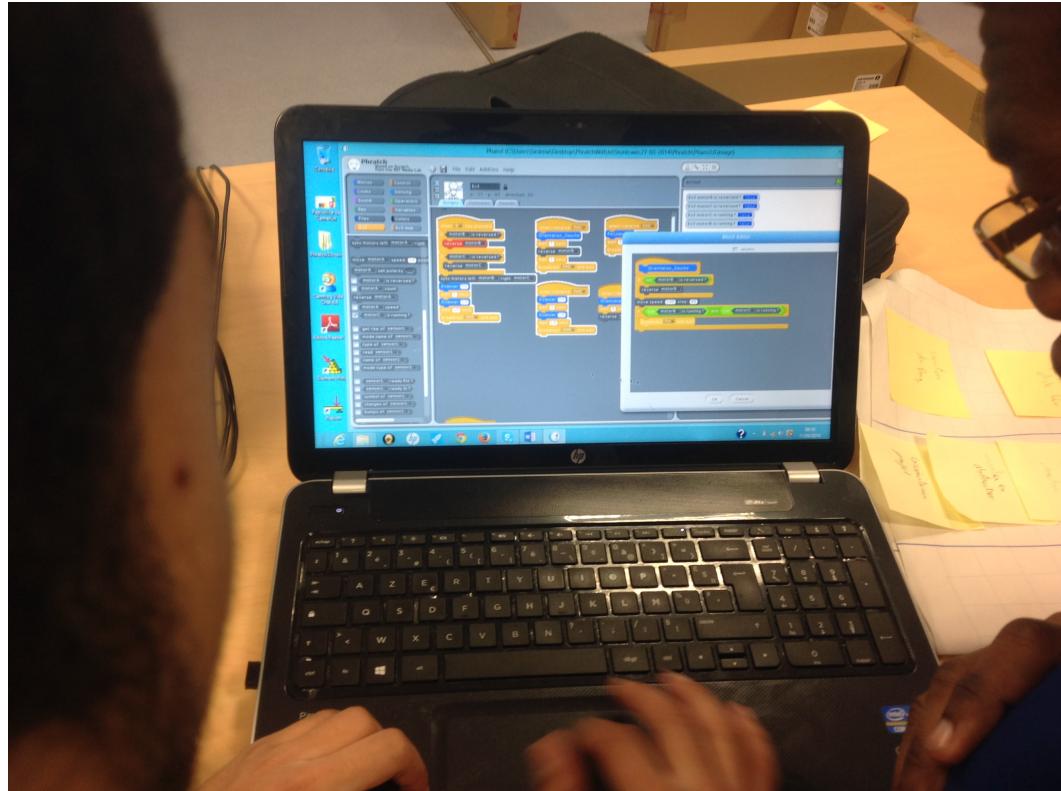


Customization

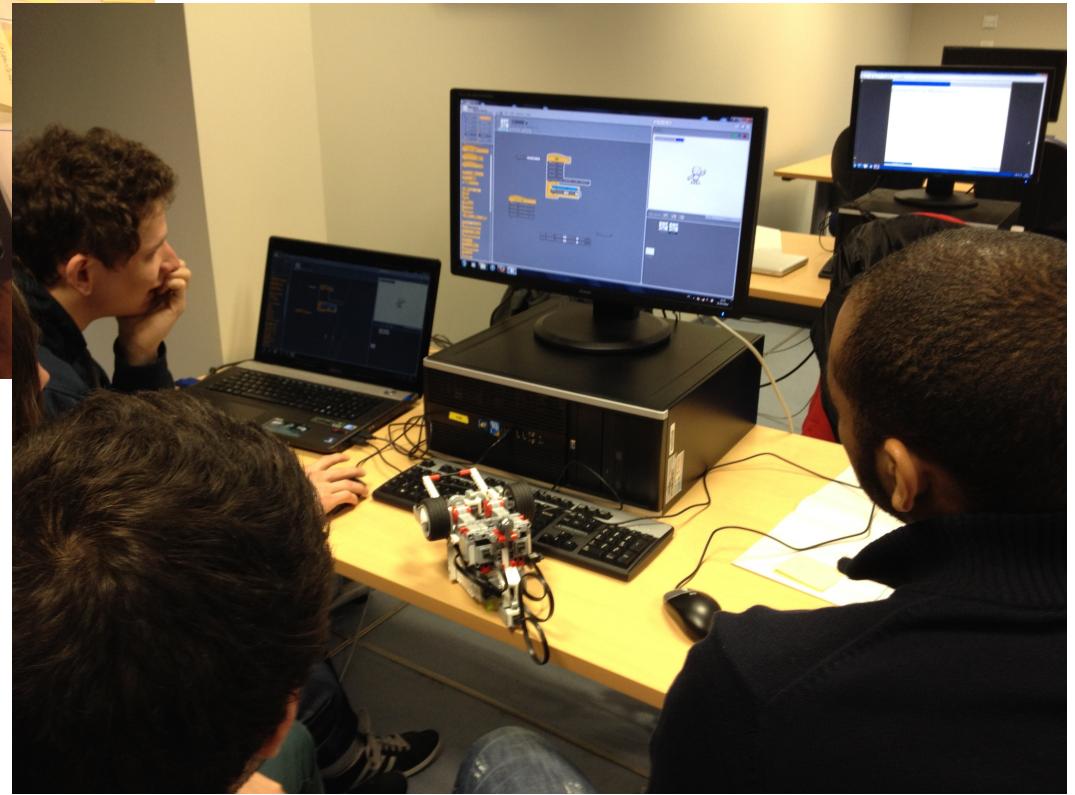
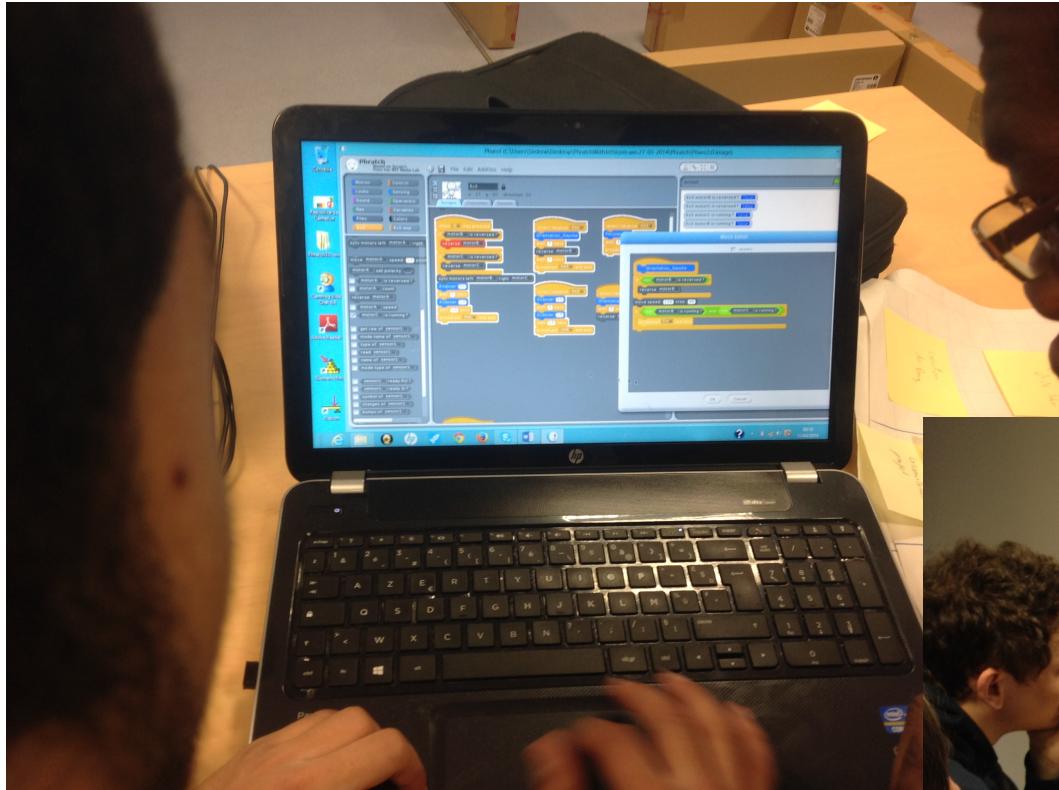


Used for real !

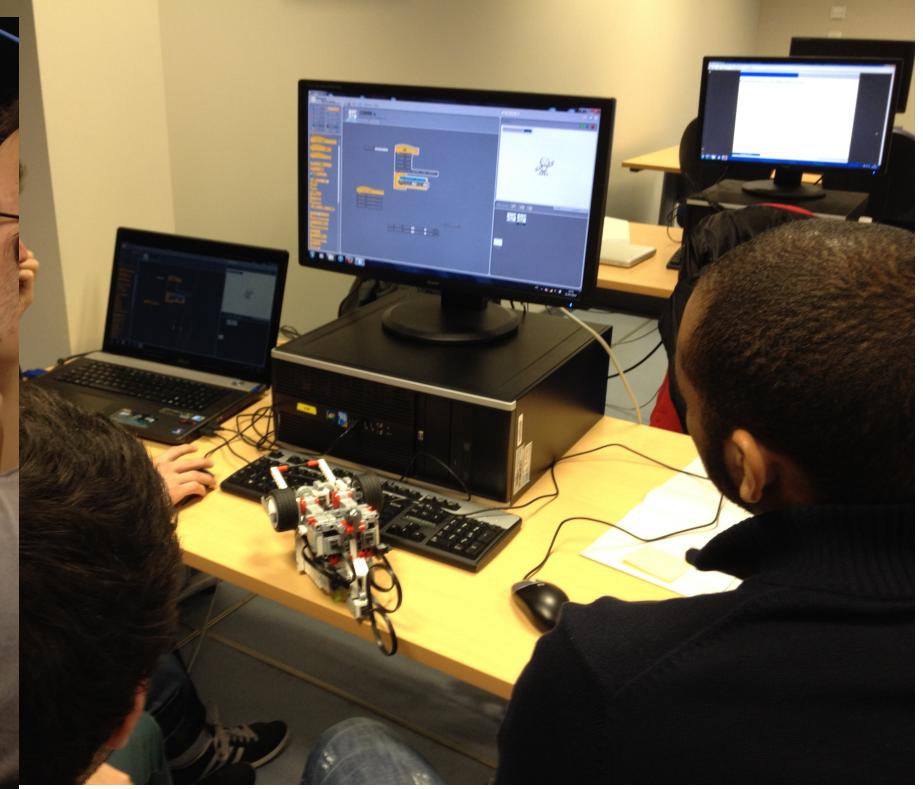
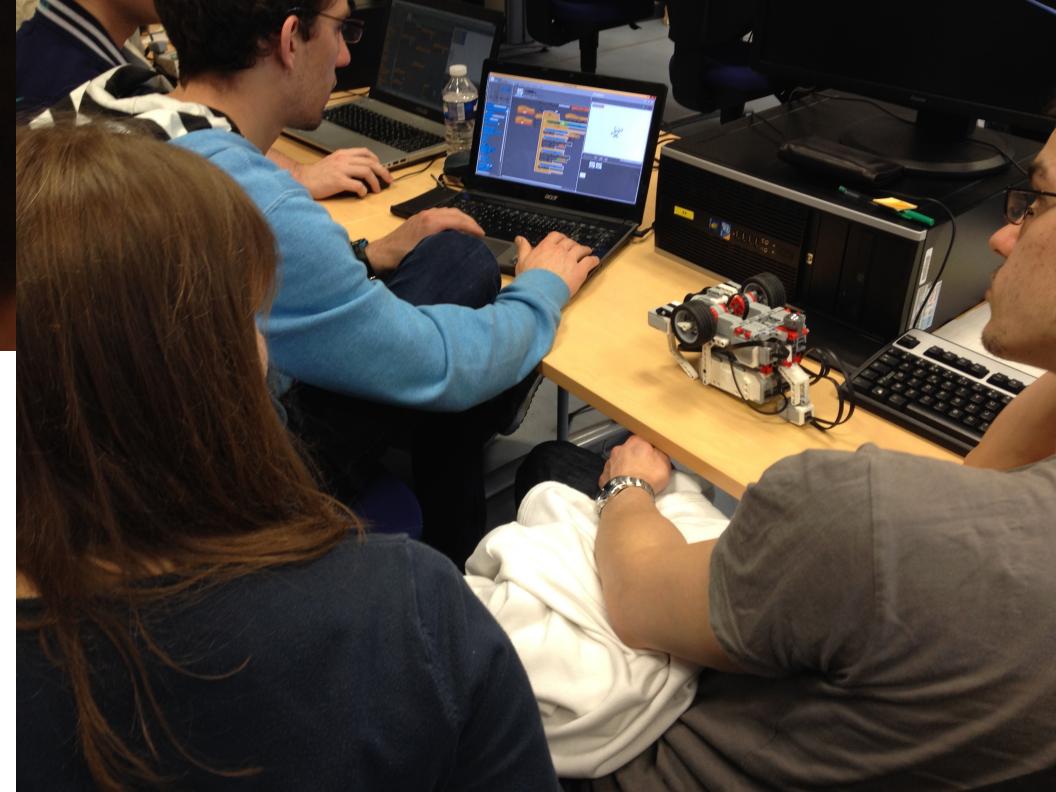
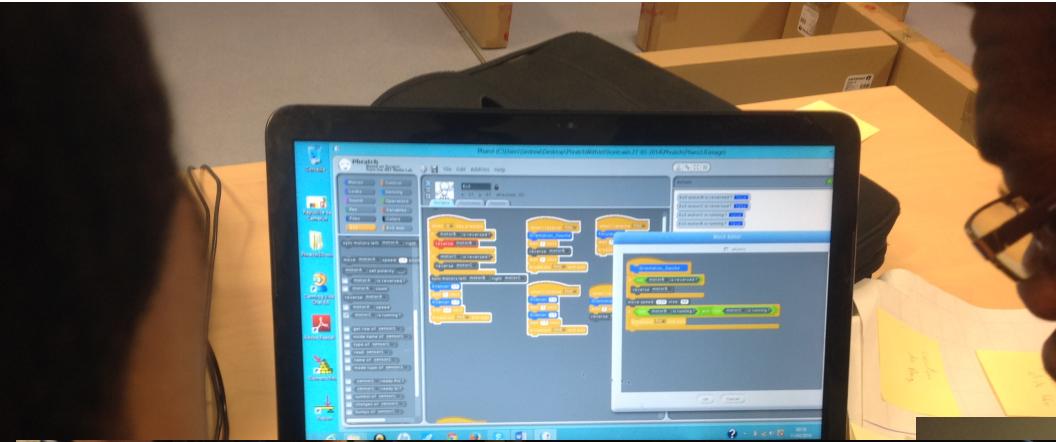
Used for real !



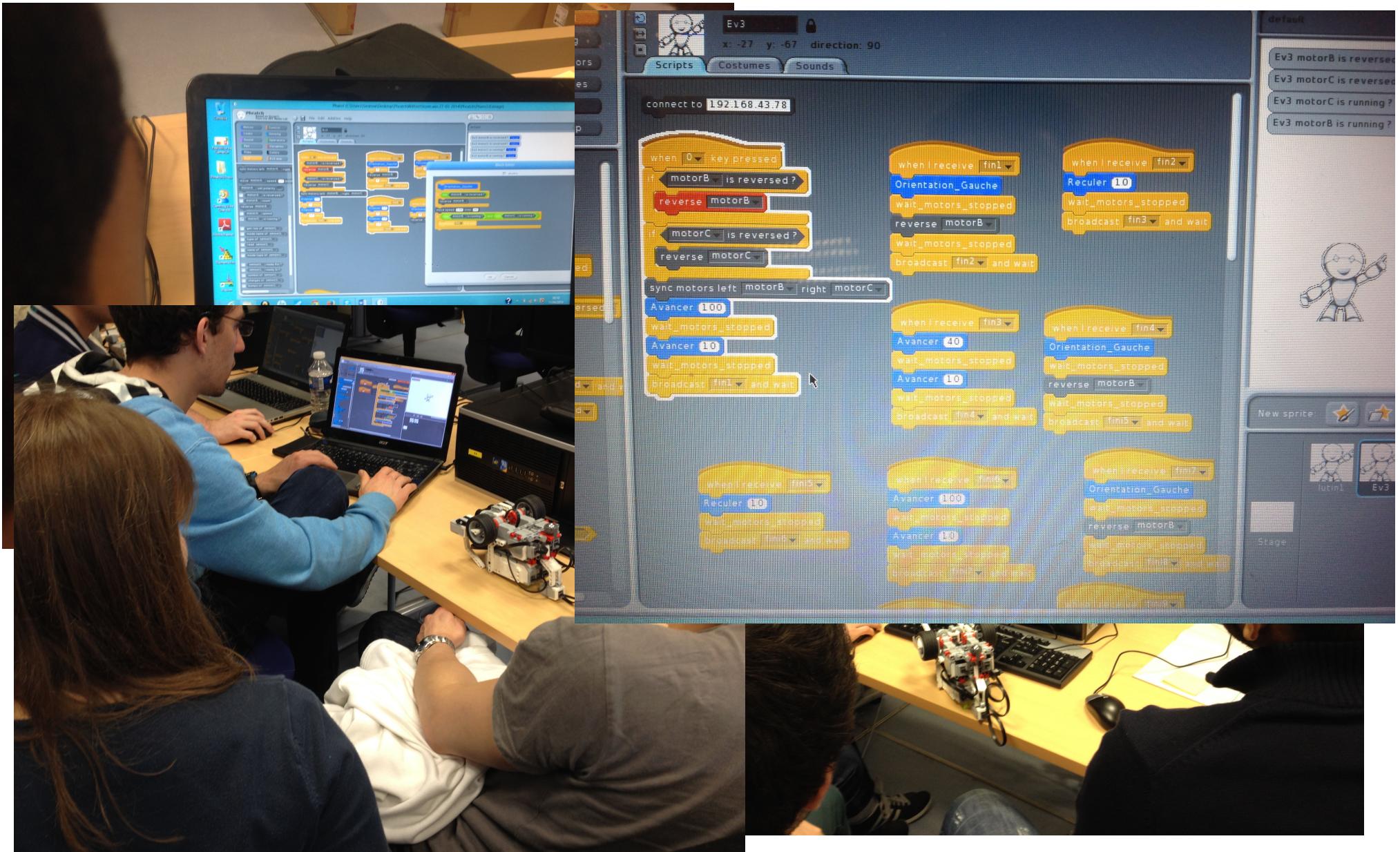
Used for real !



Used for real !



Used for real !



Next steps

Raspberry-Pi

Next steps

Raspberry-Pi

Arduino

Next steps

Raspberry-Pi

Arduino

Android



Next steps

Raspberry-Pi

Modularity

Arduino

Android



Next steps

Raspberry-Pi

Modularity

Arduino

Integration
with Pharo

Android



Next steps

Raspberry-Pi

Modularity

Arduino

Integration
with Pharo

Android

web interface



Next steps

Raspberry-Pi

Modularity

Robotics

Arduino

Integration
with Pharo

Android

web interface



Next steps

Raspberry-Pi

Modularity

Robotics

Arduino

Integration
with Pharo

Community

Android

Web interface



Next steps

Raspberry-Pi

Modularity

Robotics

Arduino

Integration
with Pharo

Community

Android



web interface

...
Cloud integration
Mobile integration
...
...

The road is long...

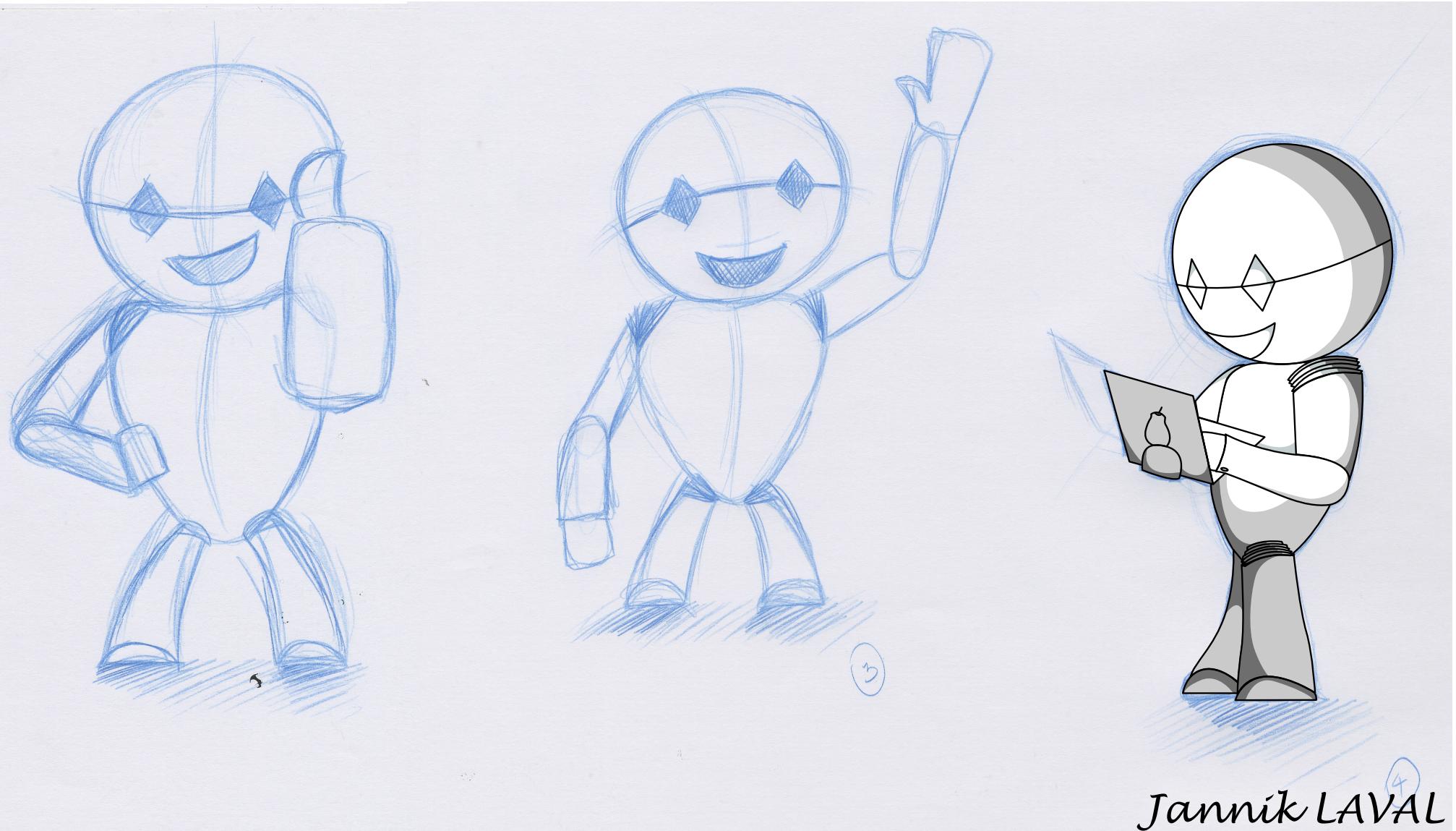


The road is long...



but we have the
lighthouse

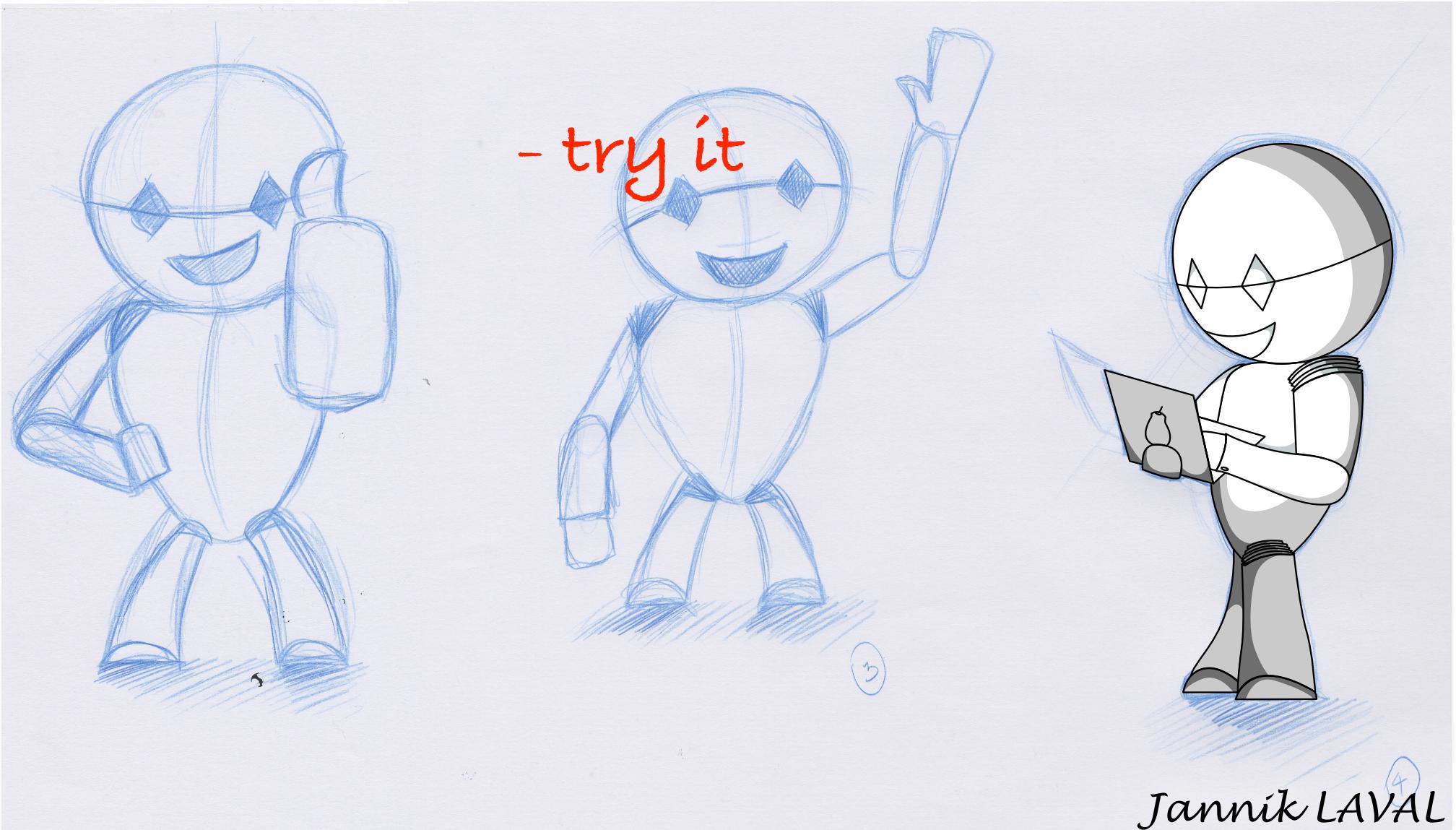
We need you



Jannik LAVAL

<http://www.phratch.com>

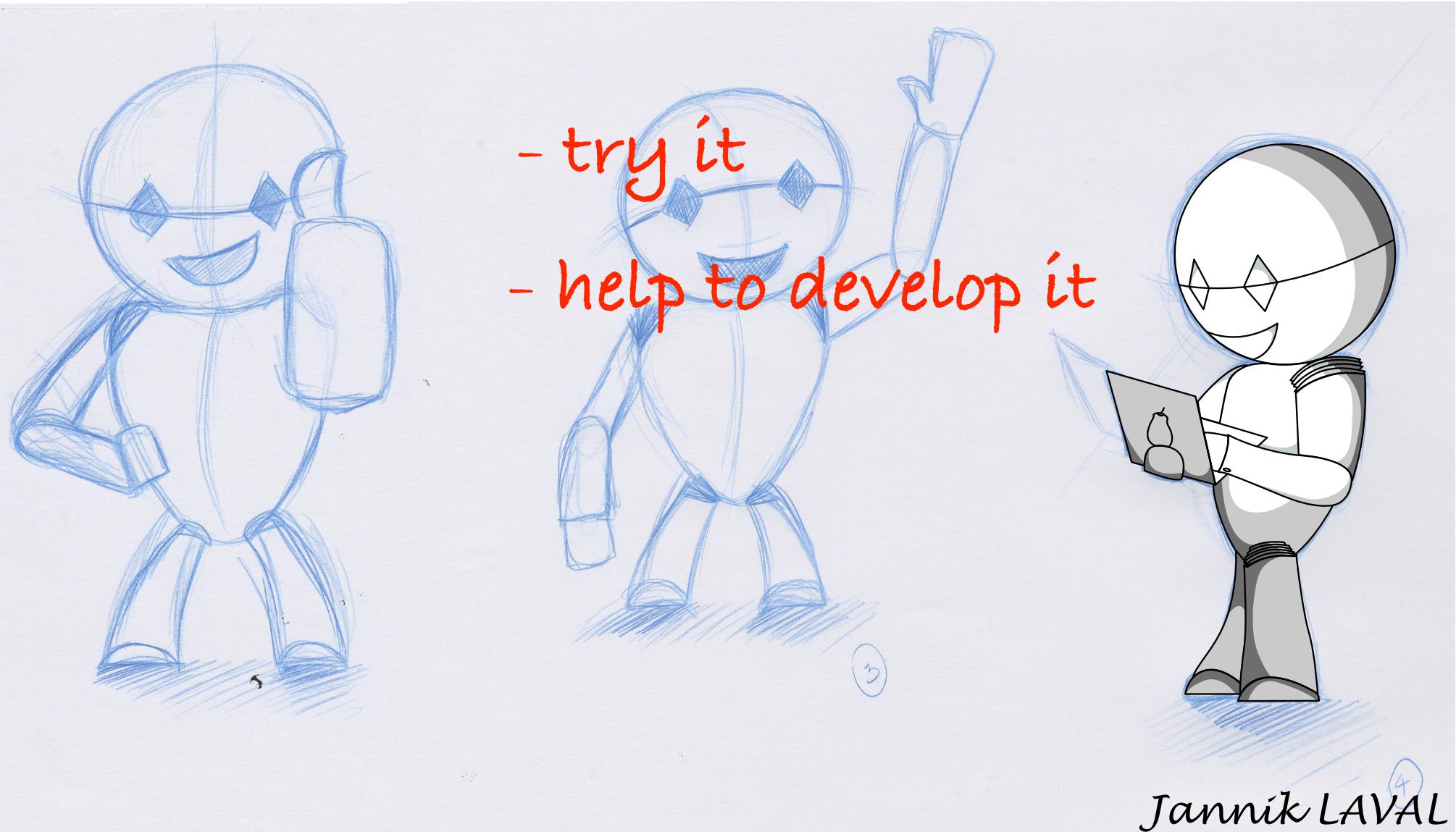
We need you



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<http://www.phratch.com>

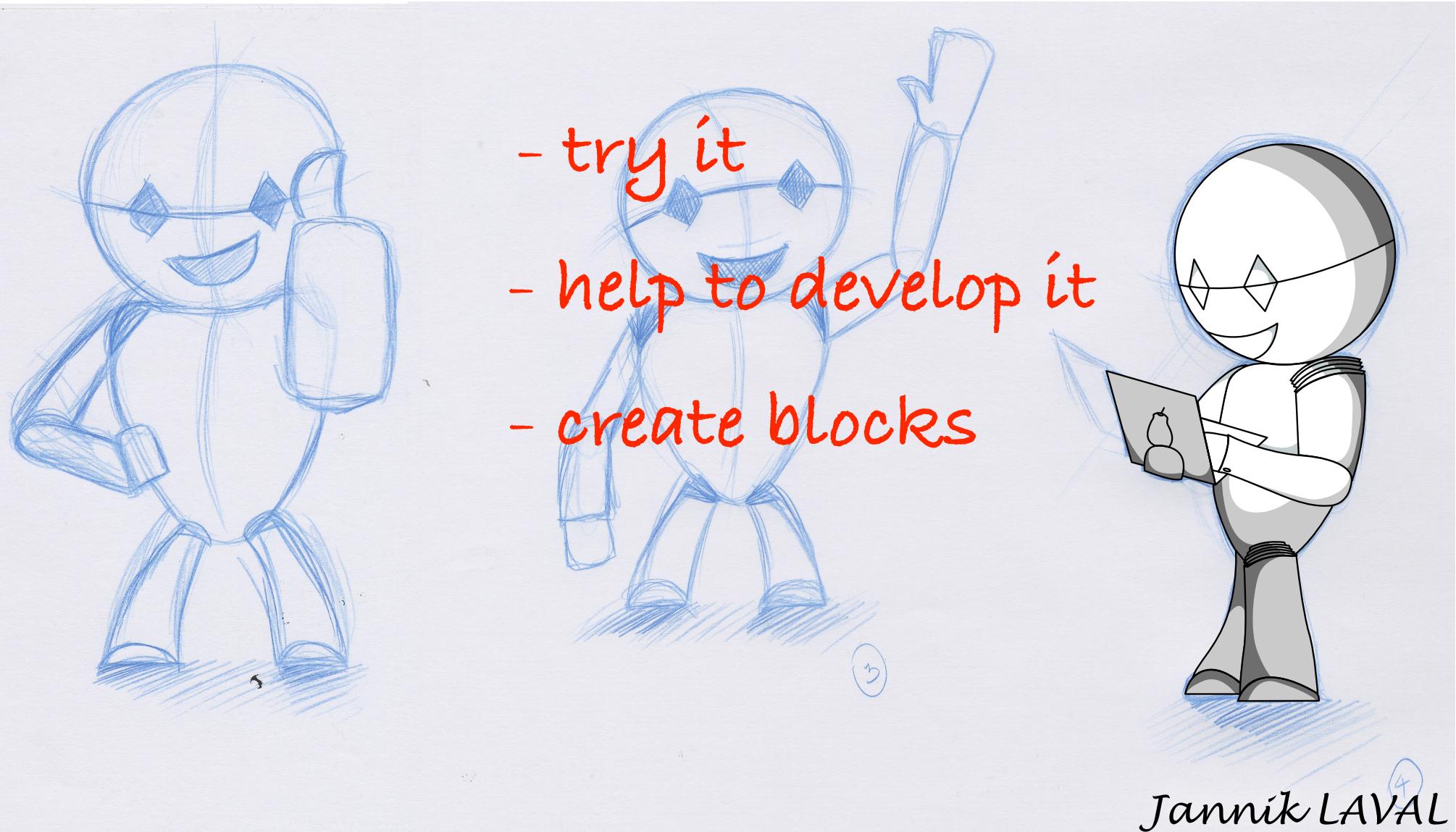
We need you



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<http://www.phratch.com>

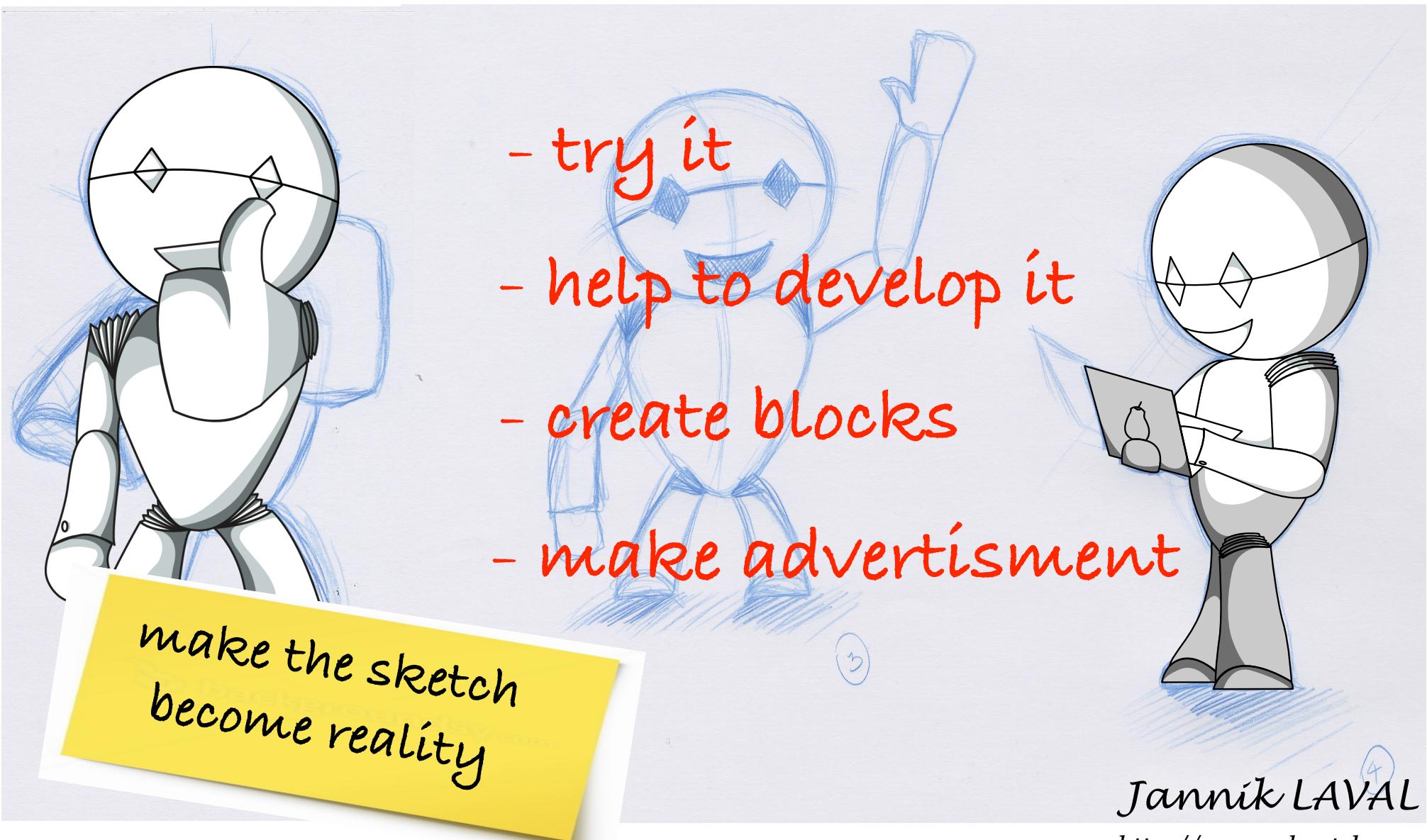
We need you



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