

**THALES**



→ **ESUG 2009**  
**Brest**

Thales RWS Brest

Reference - date

Aéronautique



History : Smalltalk in Thales Brest

Domain Context

Modelling and mockup with Smock

Component Testing with PicUnit

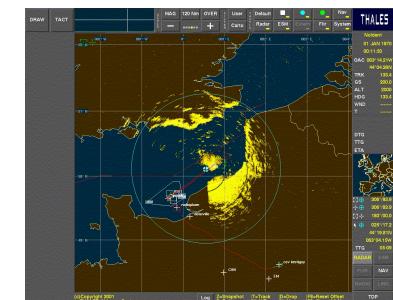
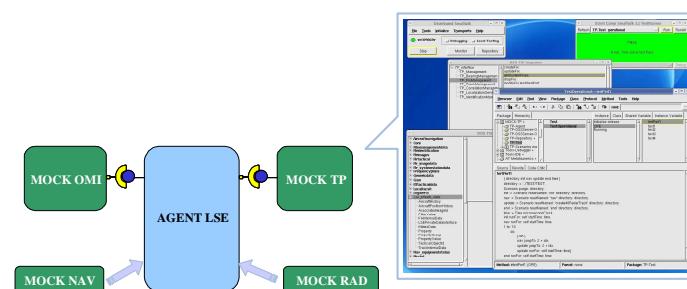
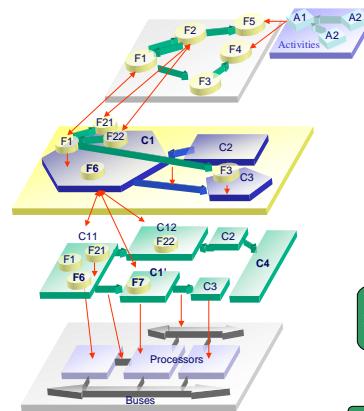
Conclusions



## A story of twenty years:

- 1989-1997: Sensor software development
  - MMI development on real time operating system (VRTX), C (TNI) code generator
  - MMI development for embedded workstation, Static typing, C++ (Thales) code generator
  - Automatic test workbench (IEEE488, VxWorks)
- 1996-2000: Training centers
- 1996-2003: MMI workstation for Maritime patrol aircraft demonstrator
- 2002-2009:
  - System Modeling and Mockup
  - Component testing

Reference - date





## Why Smalltalk

- MMI RAD
- Efficient solution proved by TNI feedbacks

## Which Smalltalk

- Parc Place version & Cincom versions
  - The only multiplatform version available in the early 80's.
  - From Smalltalk 2.5 up to VisualWorks 7i

## Packages:

- Smalltalk Compiler / Refactoring browser → Code generation
- UI → MMI building with dedicated look & feel
- DLLCC → External access
- DST, Opentalk → OMG Corba
- Internal package:
  - SCM → Component Model CCM Like
  - DOS → Distributed Object System
  - DSS → DST tools and addOn



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# Domain : Patmar, Surmar and EWC2



Reference - date

- **Civilian Missions (SURMAR)**
  - Assistance and support to police & customs
  - Detection & control of pollution
  - Assistance to scientific observations
  - Surveillance of maritime traffic and offshore oil fields
  - Search & Rescue medical evacuation
  - Control & monitoring of fisheries
  - Antipollution
- **Military Missions (PATMAR)**
  - Anti-Submarine Warfare (ASW)
  - Anti-Surface Unit Warfare (ASUW)
  - EEZ Surveillance(Exclusive Economic Zone)
  - Maritime Traffic Control
  - Surveillance of off shore oil fields
  - Search and Rescue
  - Fishing Surveillance
- **Electronic Warfare C2 Functions + RESM**
  - EW Picture elaboration
  - EW engagement management
  - On-board Combat Management System interface



Cockpit  
Display



MSA LE



MPA UE

Laptop  
Computer  
(training)



Ocean Master  
Radar



FLIR



AIS



Anti-pollution  
Sensors



Self  
protection



COMINT  
(option)



Sonobuoy &  
marker launchers



Mission  
Data  
Recorder



Navigation  
System



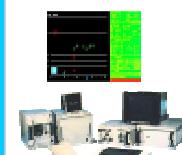
IFF



Comms  
Data Links  
Satcom



ESM



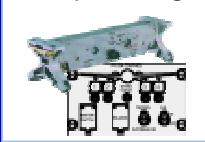
Acoustic  
(TMS 2000)



MAD

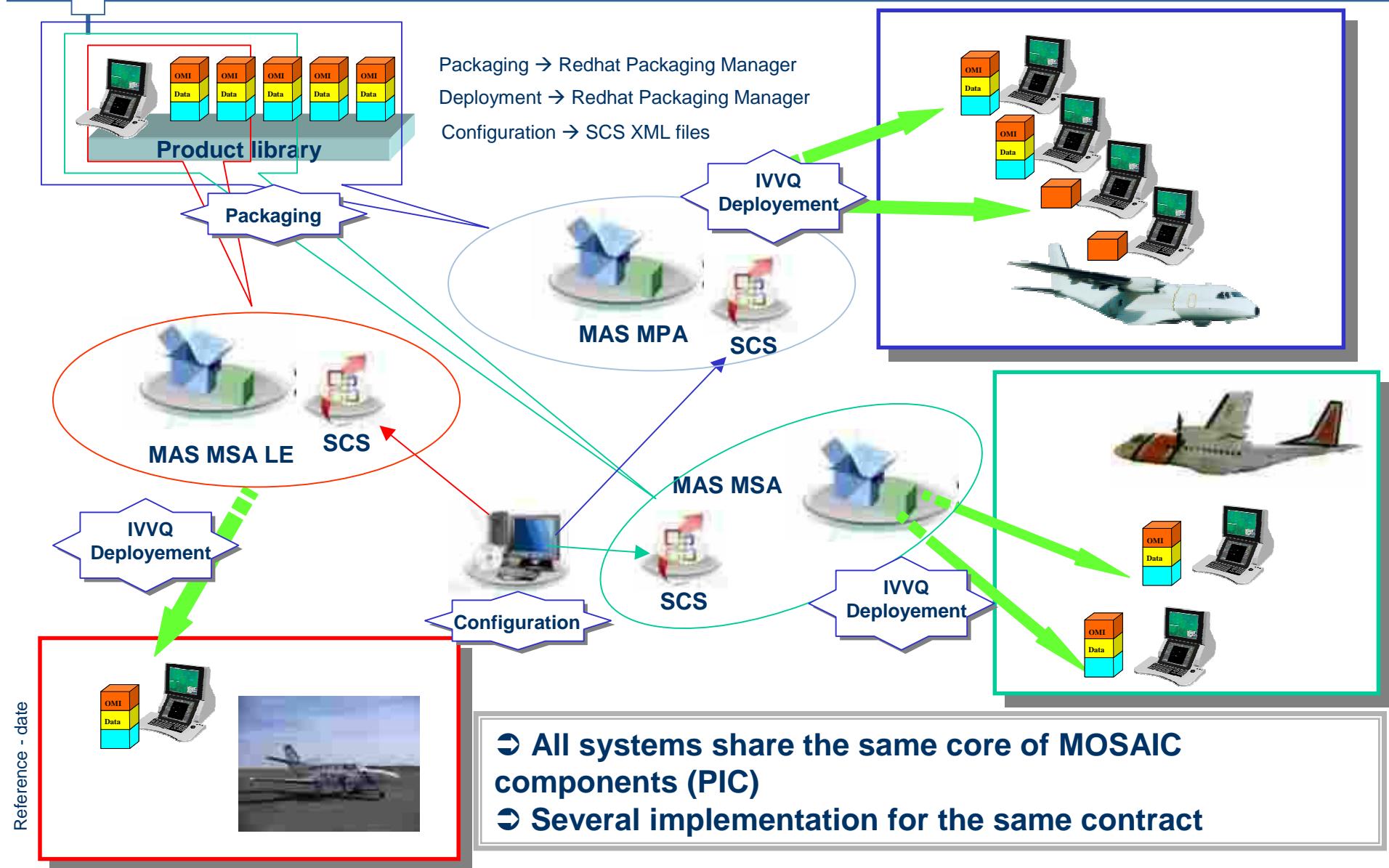


Torpedoes &  
Depth charges



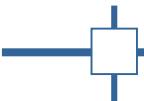
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# Product line : a configurable system

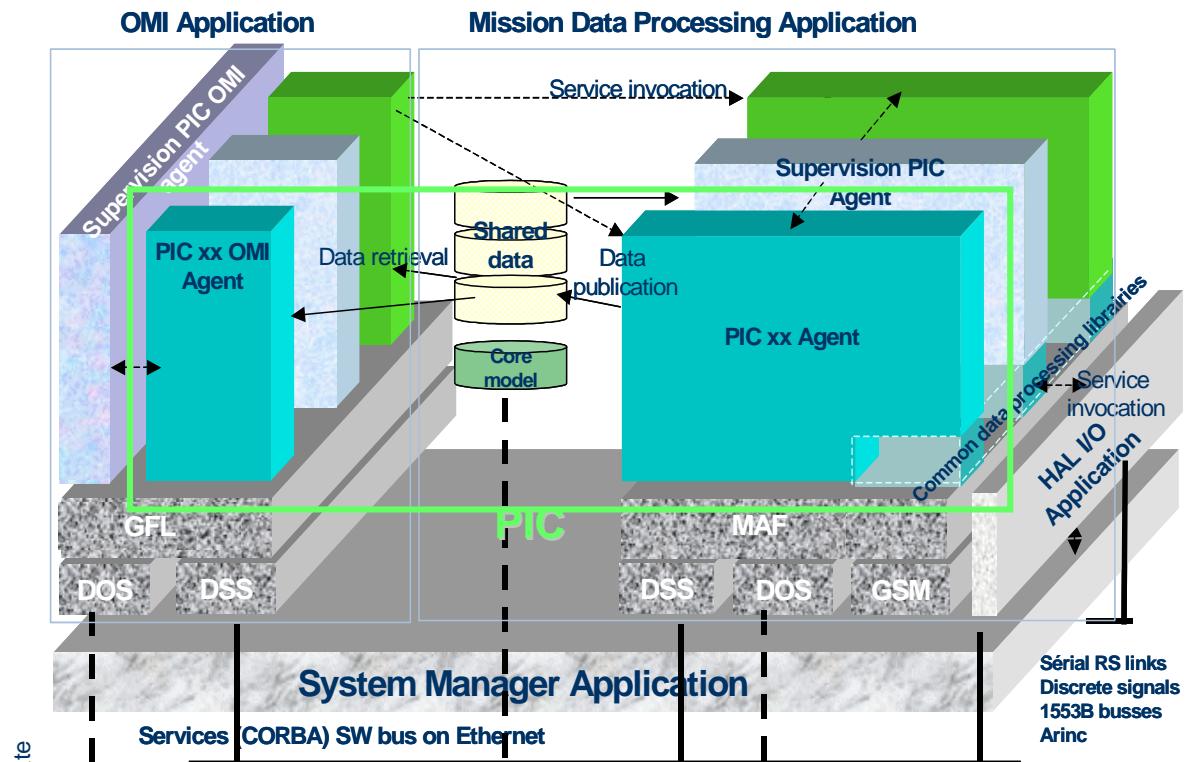


- ⇒ All systems share the same core of MOSAIC components (PIC)
- ⇒ Several implementation for the same contract

# MOSAIC Architecture



# MOSAIC



**MOSAIC**  
« Data Centric » Architecture

- To provide mechanism to share the Tactical Situation
- To provide Command & Control functions
- To minimize integration Risks
- To allow System Product Evolution & Adaptation
- To give a Common Framework to multi-company projects
- Scalability & performances (through data base caching, data and agents distribution...)
- Reliability (when an agent crashes, others can survive)
- Interoperability through Corba standard compliant services
- Extensibility (ability to add / modify agents, equipment, with no / few modification)
- High software and system integration productivity
- Openness (to various languages, hardware platforms, COTS software products integration...)
- Long term availability (through standard based, COTS independence and market driven COTS / technologies choices)

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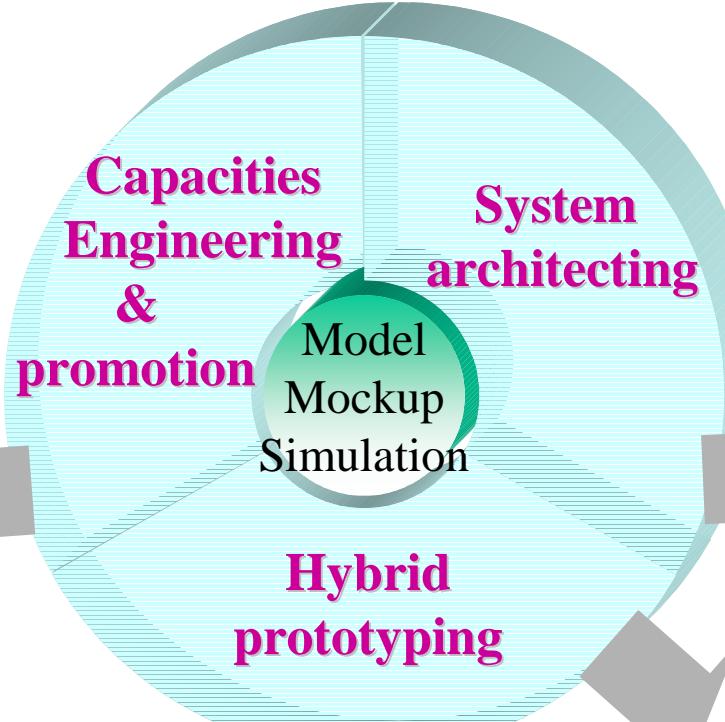
# Modeling, Mockup and Simulation



## New concepts engineering

- Operational concept mining
- Usage concept mining
- Human factors
- Value analysis
- Demonstrator for show room

Innovate  
Define the right offer & promote it



## System solutions engineering

- Technical system parameters identification
- System sizing
- Performance engineering
- TRL assessment
- Design solution assessment
- Impact analysis (new function/ new technology)

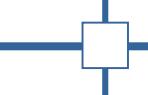
Define the right architecture

Secure the development

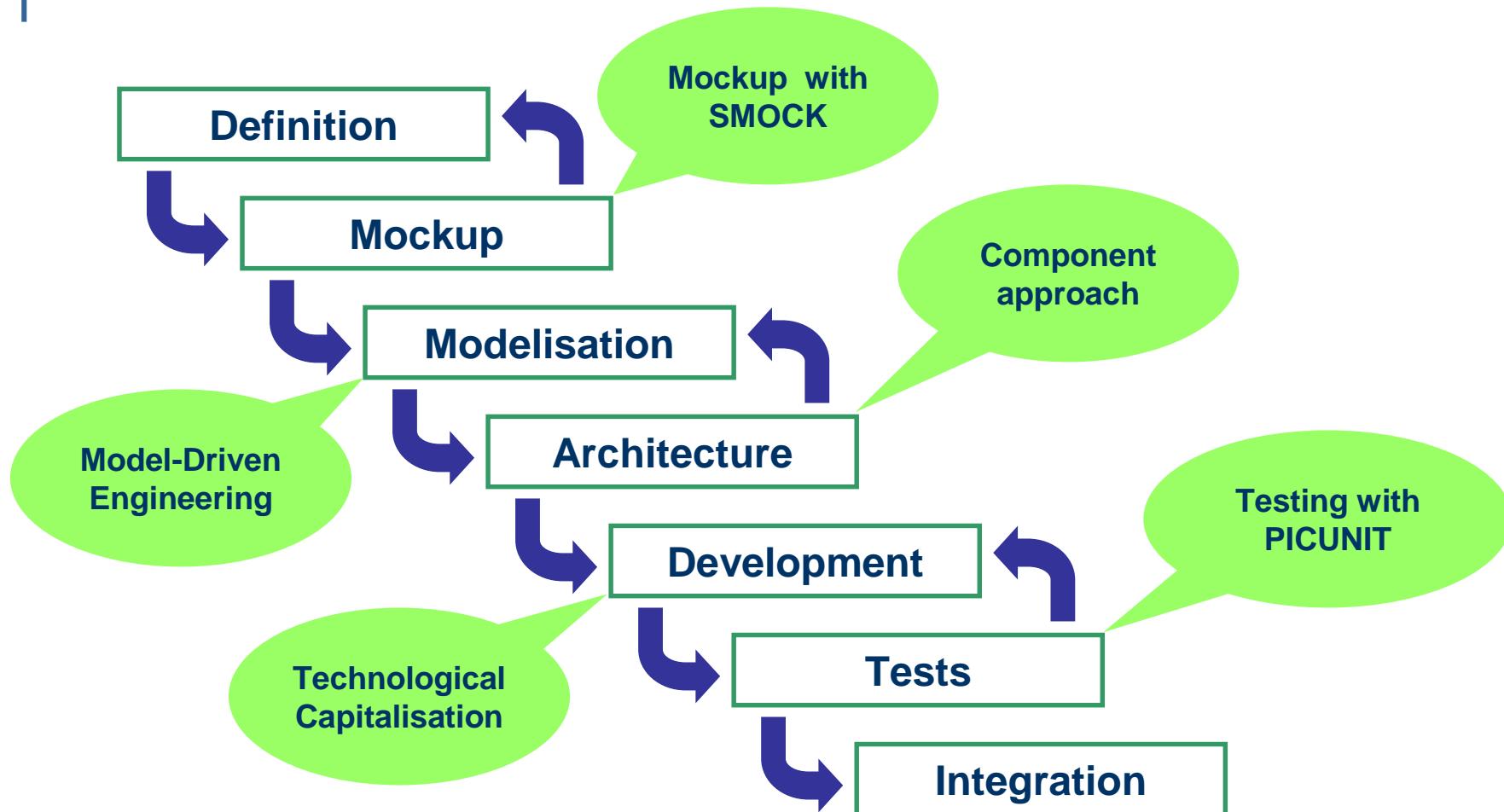
## Technical solutions engineering

- Prototyping
- Pilot development
- **Development support:**
  - Specifications validation
  - Pre integration & verification (host)

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# Software production process



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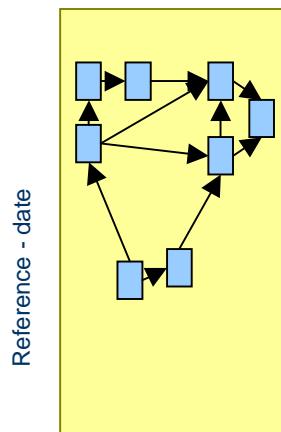
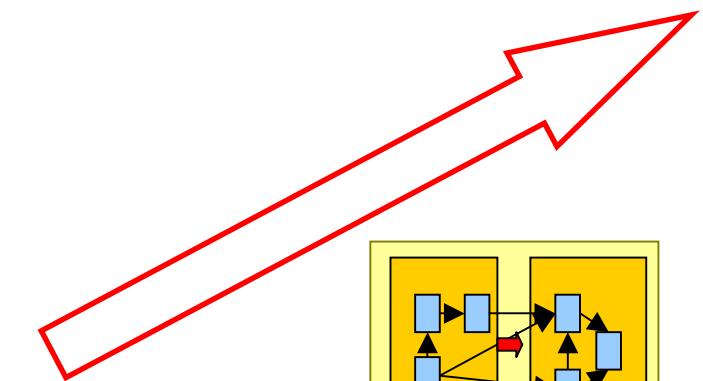
Component Testing with PicUnit

Conclusions

# Component: Aim Architecture



Component approach structures the system and the development



- Object
  - Architecture appear
  - Packaged
  - No contract
- 
- Object
  - No architecture
  - No contract
  - flat

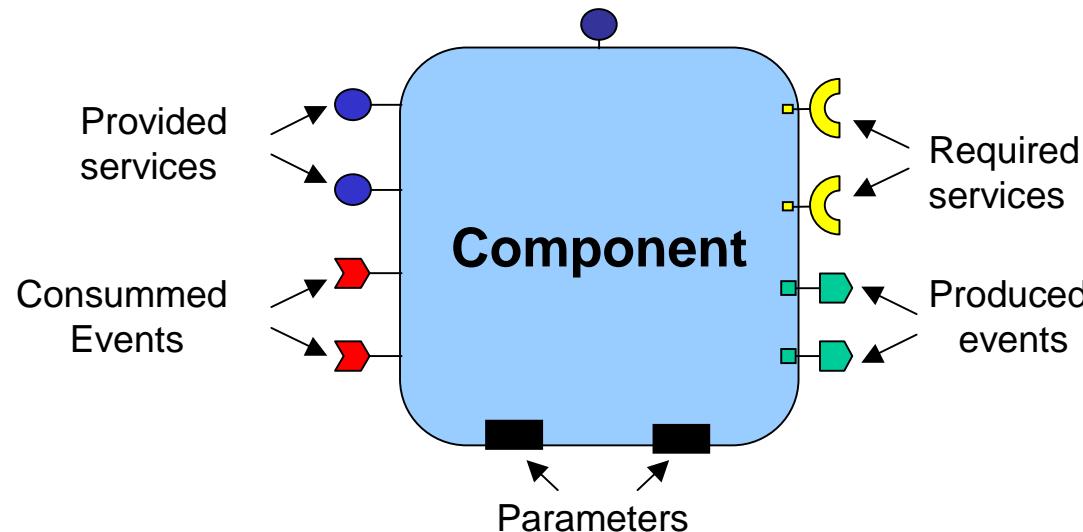


## Smalltalk Component Model

- CCM Like Component approach inherited from Jaguar (Thales/DCNS Java Framework)

Introduction of interface in Smalltalk

Notion of component manager, deployment services home services, locator services, ...



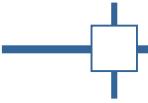


## Interface definition

```
MyNameSpace
    defineInterface: #MyServices
    super: nil
    with: #(serviceOne: serviceTwo )
```

## Component definition

```
defineComponent
    self
        providedServices: #(#{MyNameSpace.MyServices})
        requiredServices: #()
        consumedEvents: #()
        producedEvents: #(#{MyNameSpace.MyEvents})
```



# Mockup environment : SMOCK



## Agile development environment:

- Full operator workstation mockup
- Component based architecture modeling
- Interaction behaviour simulation
- Multi workstation on a simple laptop
- Easy sharing between all actors including customer:
  - easy packaging
  - easy deployment on a simple laptop
- Early evaluation of relevant scenario
- Integrated development cost model

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- ⇒ Few days to one month for a new mockup
- ⇒ Significant evolution in real time
- ⇒ Collaborative work





## Architecture modeling

- From system architecture to executable model in Smalltalk

## Link from Mockup to System and Software tools

- Models and Requirements definition
- Product line management
- Configuration management
- Code generation

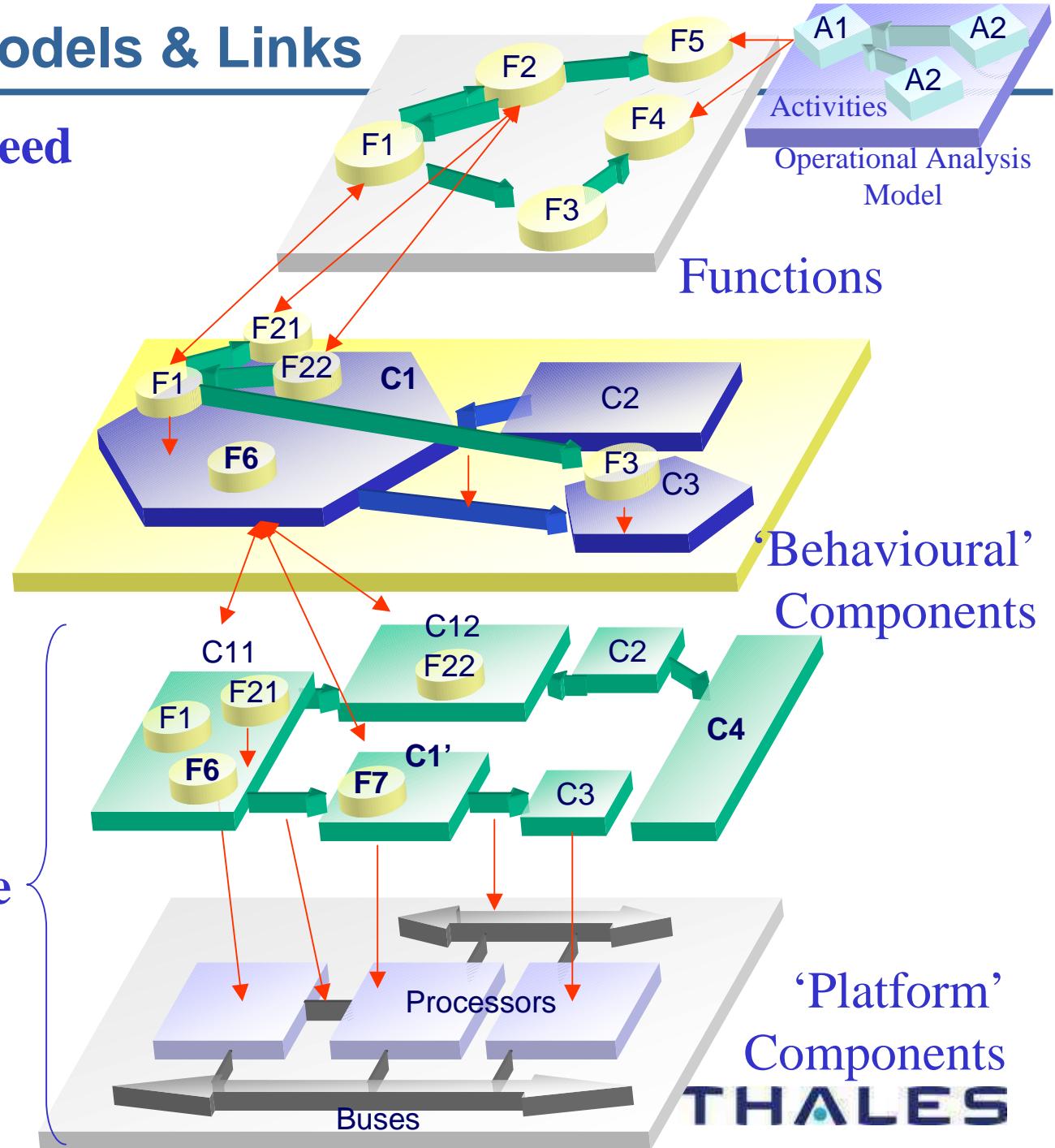
# Global View of Models & Links

## System Functional Need Model

## Logical Architecture Model

## Physical Architecture Model

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History : Smalltalk in Thales Brest

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Modelling and mockup with Smock

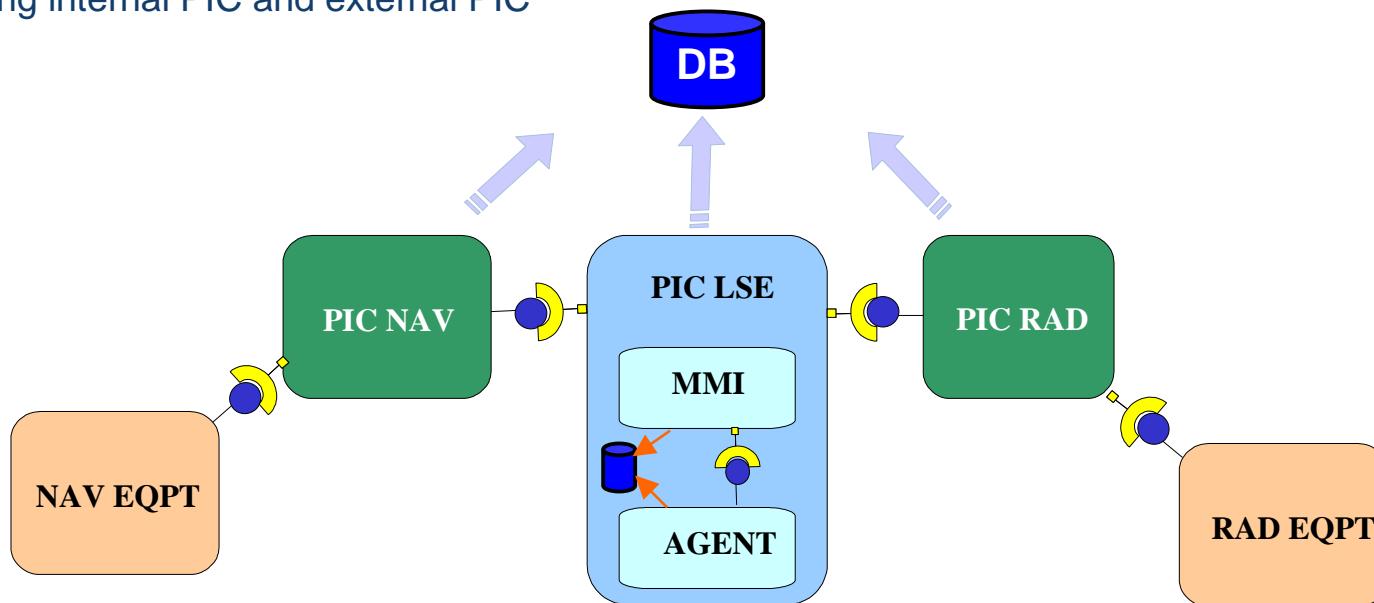
Component Testing with PicUnit

Conclusions

# PicUnit tool in which context?

## Context :

- Component architecture with few levels
- Service interfaces : Corba
- Datamodel interface : Database
- Dev context : other components not yet available when developing a component
- Testing internal PIC and external PIC



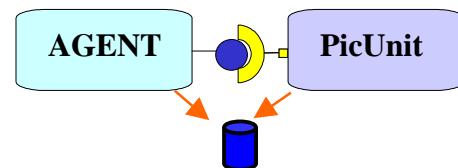
**Validate component itself and also communication with other components around**

# PicUnit tool for which usages?

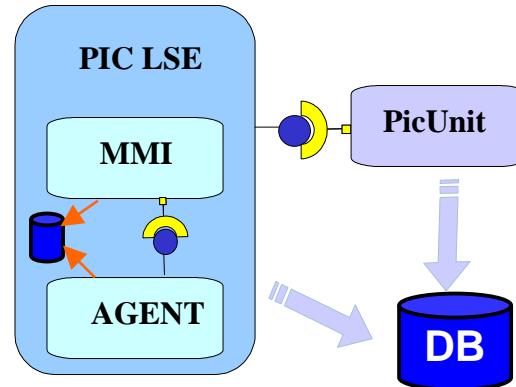
## Usages :

- Unit test for component
- Simulate middleware interfaces
- Simulate other components
- Swiss knife for problem investigation
- Prepare a defined state
- Simulators

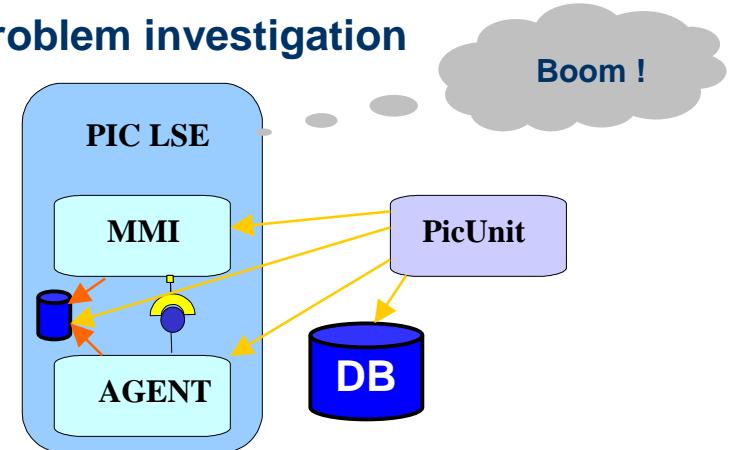
## Testing a standalone component



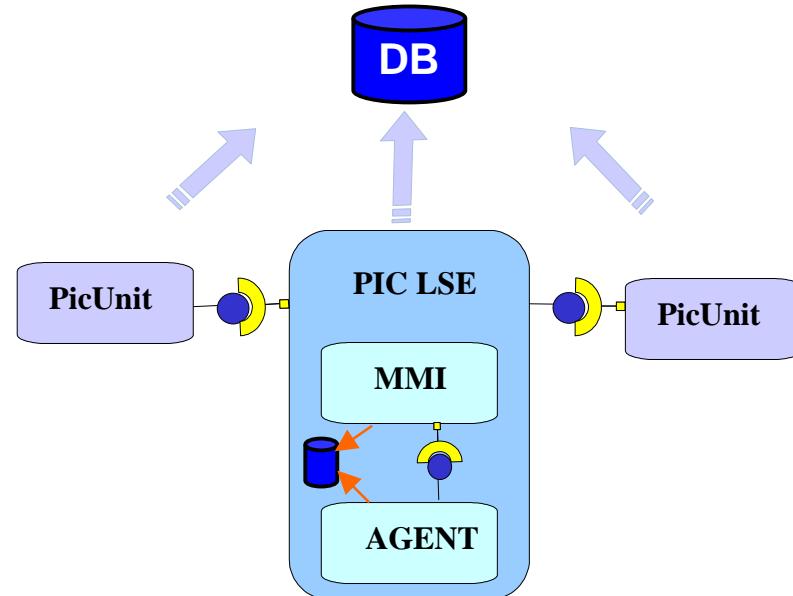
## Testing a Standalone PIC



## Problem investigation

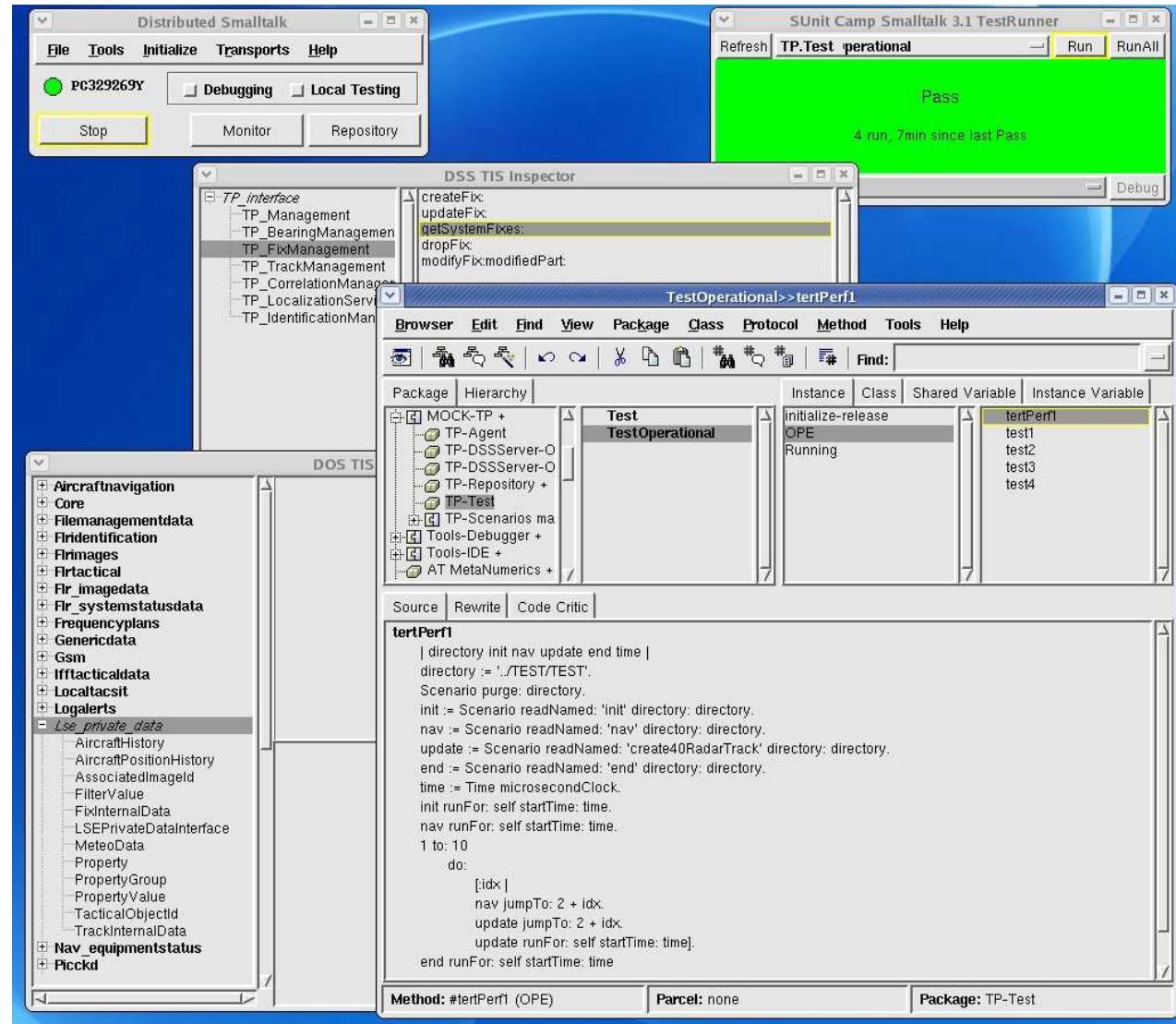


## Simulate other components

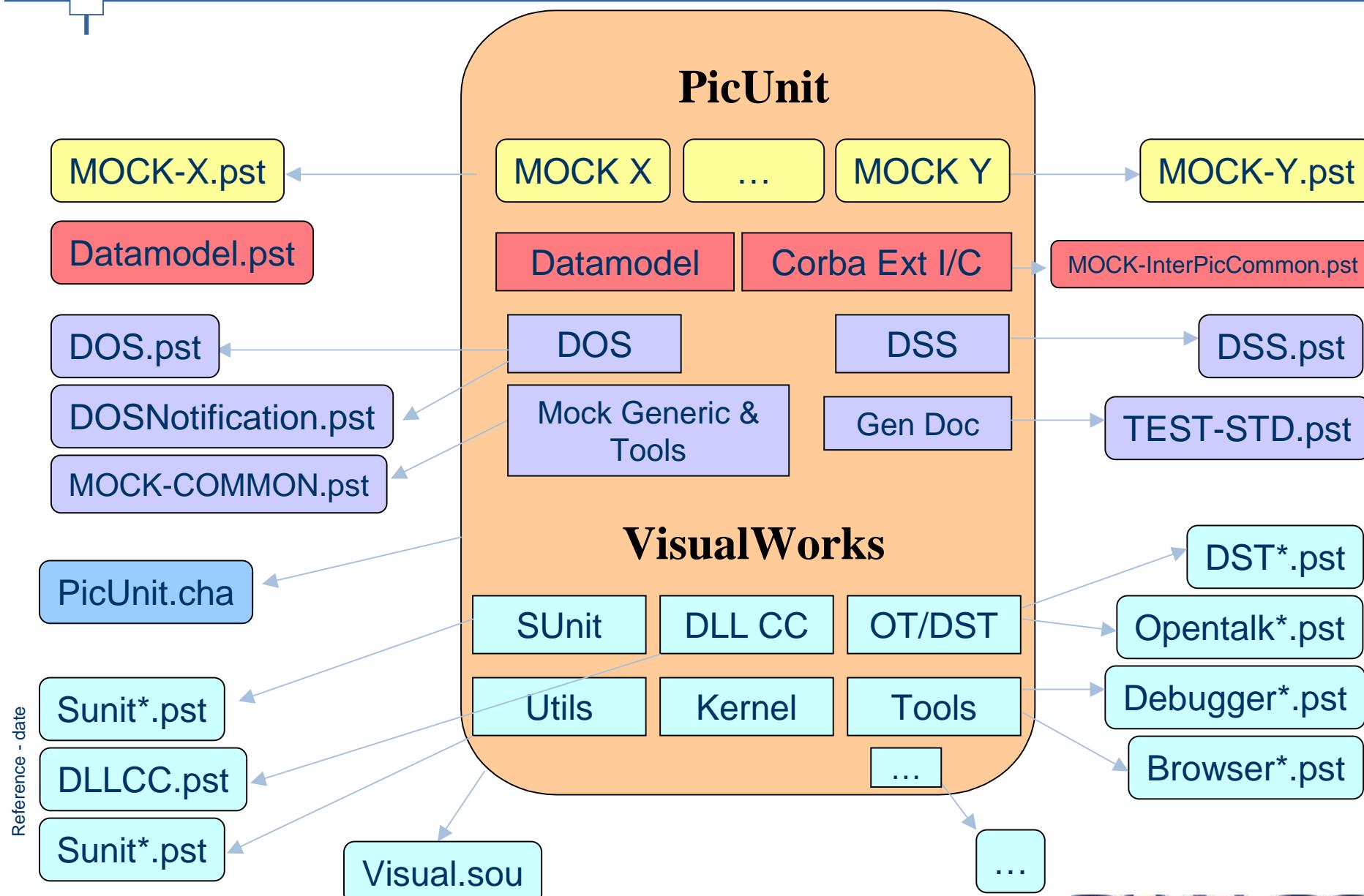


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# PicUnit Screenshot



# PicUnit Map



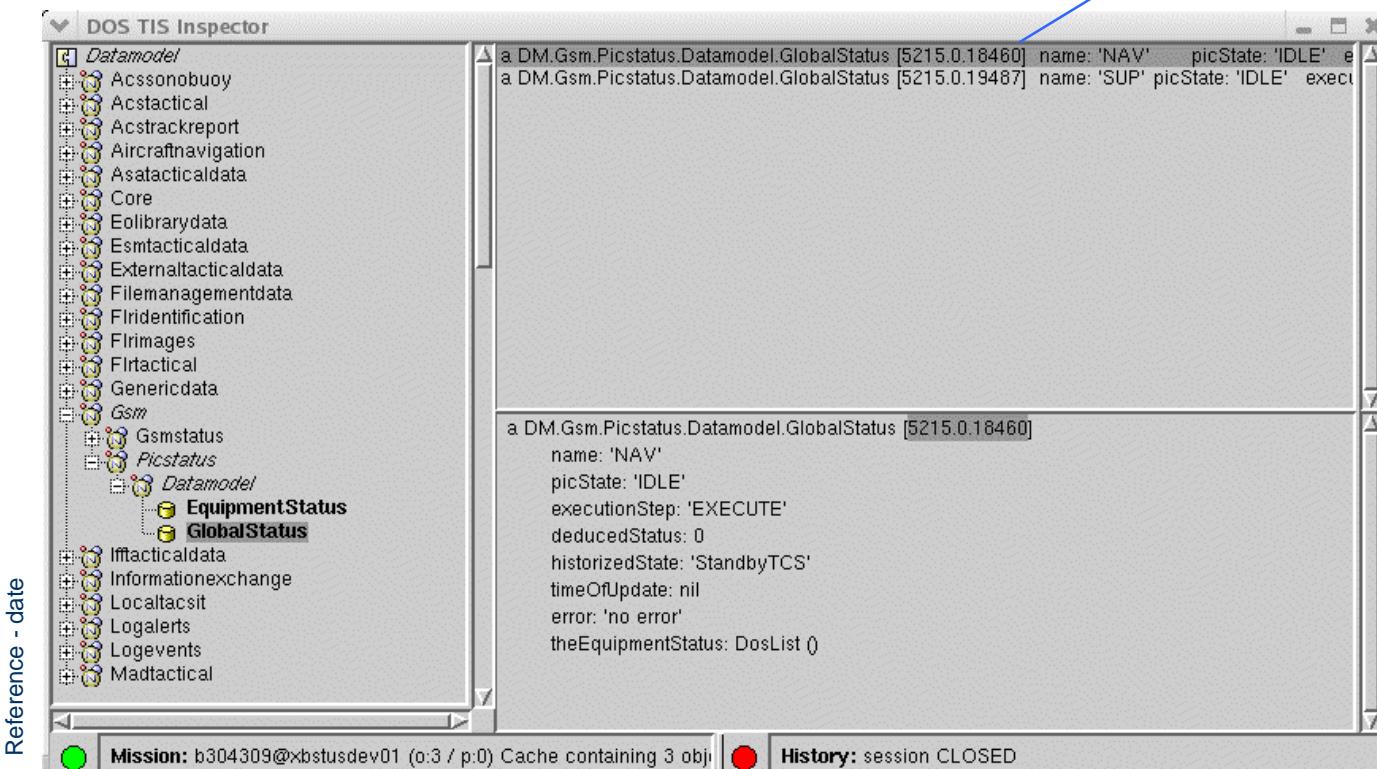
## DB Inspector

- Browse the database objects
- Generate Datamodel smalltalk classes
- Create / Delete / Modify object
- Same features available in the Tests via an API

Inspect it

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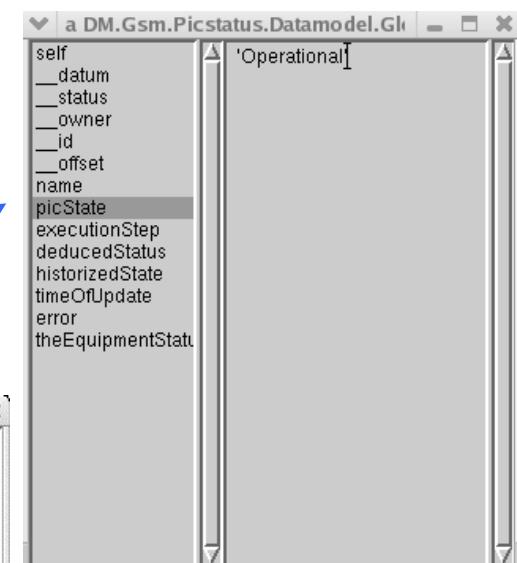
**DOS TIS Inspector**



The interface shows a tree view on the left with categories like Datamodel, Gsm, and Gsmstatus. A specific 'EquipmentStatus' node under Gsmstatus is selected. On the right, a detailed view of a 'GlobalStatus' object is shown with its properties: name ('NAV'), picState ('IDLE'), executionStep ('EXECUTE'), deducedStatus (0), historizedState ('StandbyTCS'), timeOfUpdate (nil), error ('no error'), and theEquipmentStatus (DosList()).

Mission: b304309@xbstusdev01 (o:3 / p:0) Cache containing 3 obj | History: session CLOSED

'Operational'

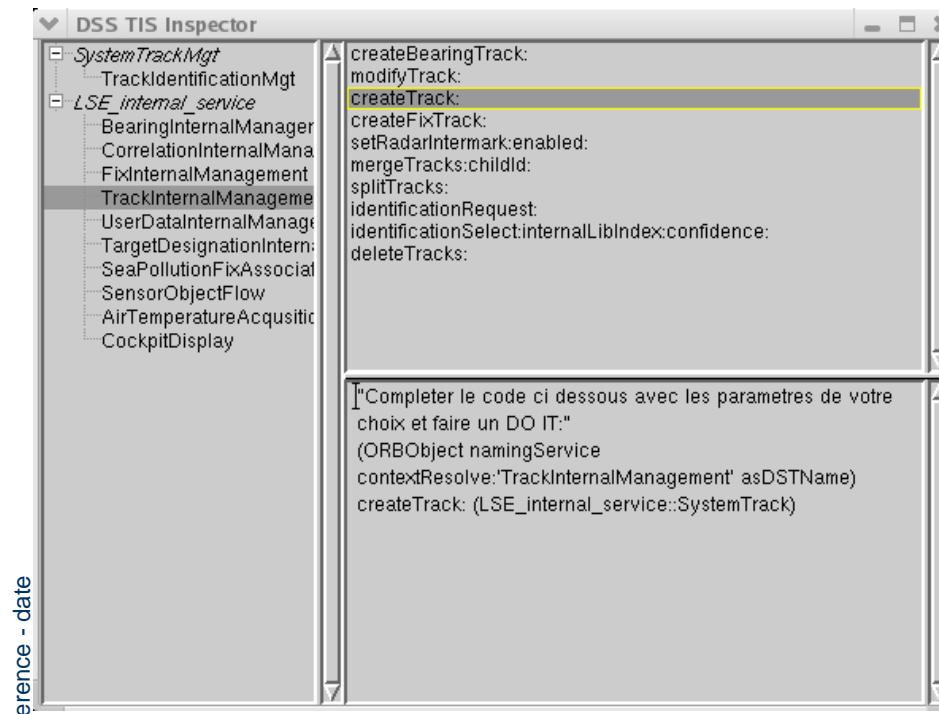


The interface shows a list of GlobalStatus objects with their names and picStates. One object is selected, showing its details: name ('NAV'), picState ('IDLE'), executionStep ('EXECUTE'), deducedStatus (0), historizedState ('StandbyTCS'), timeOfUpdate (nil), error ('no error'), and theEquipmentStatus (DosList()).

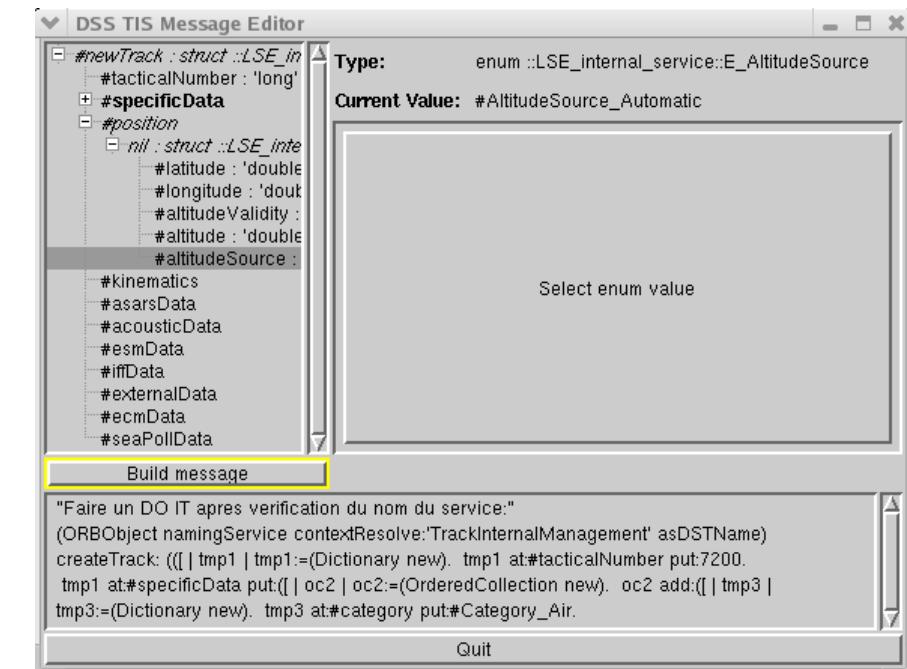
Modify object  
and Accept

## DSS Tool

- Load an IDL file or an already recorded module in Repository
- Corba modules tree view : Module > Interfaces > services
- Generate services (a Module = a Package + a namespace)
- Simple usage : register I/C in NS, call service by Dolt, unregister I/C
- Service argument editor



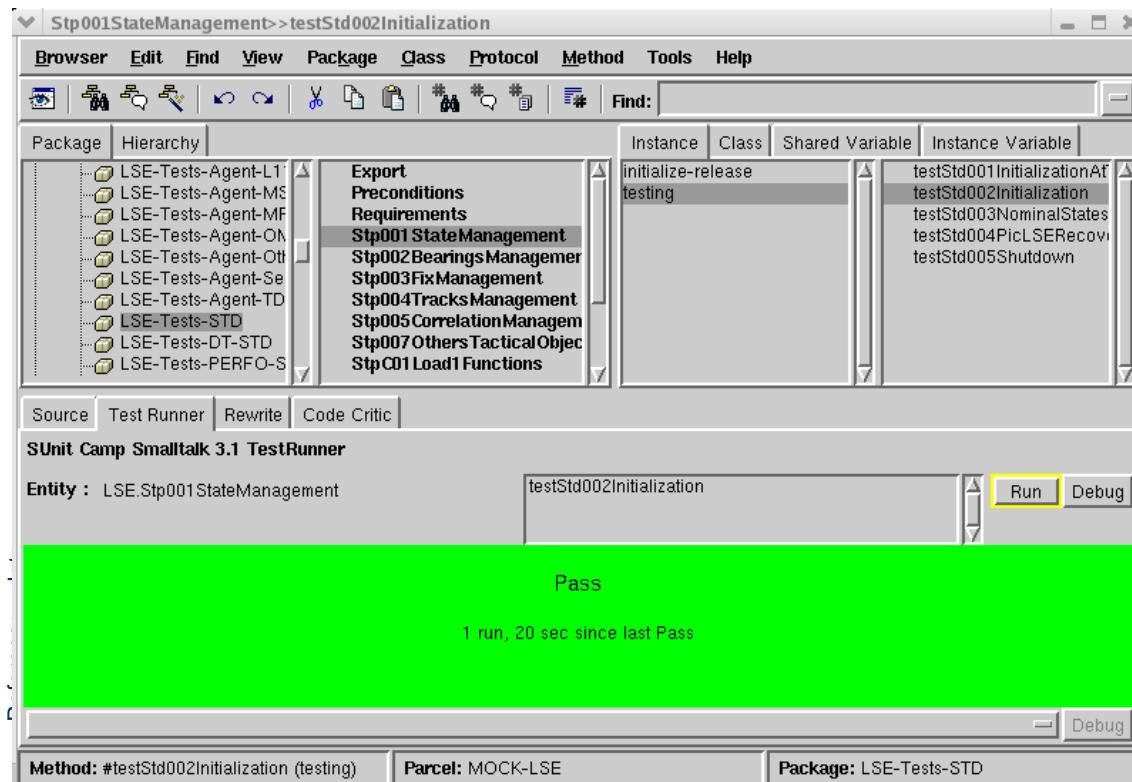
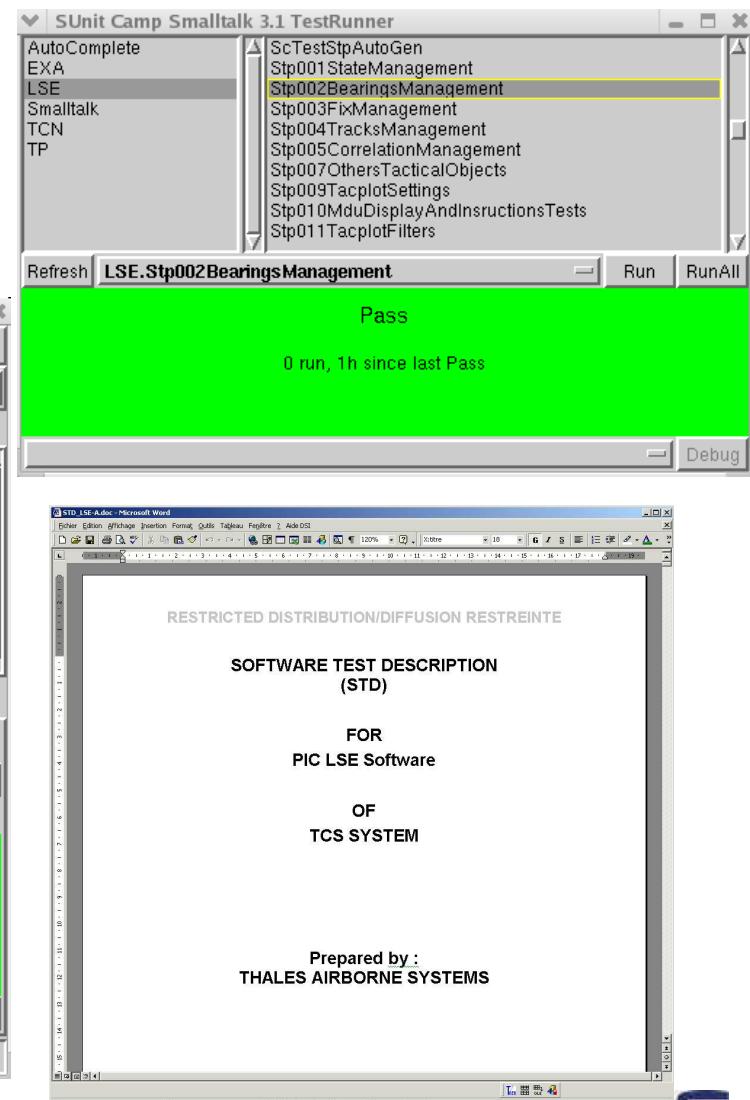
**Browse modules / (un)register in NS / services call**



**Edit complex arguments / service call**

## SUnit

- Famous xUnit framework
- Dev context : launch a test and debug it in the browser
- Qualification context: launch all tests in TestRunner
- Generate Test Description document (STD)

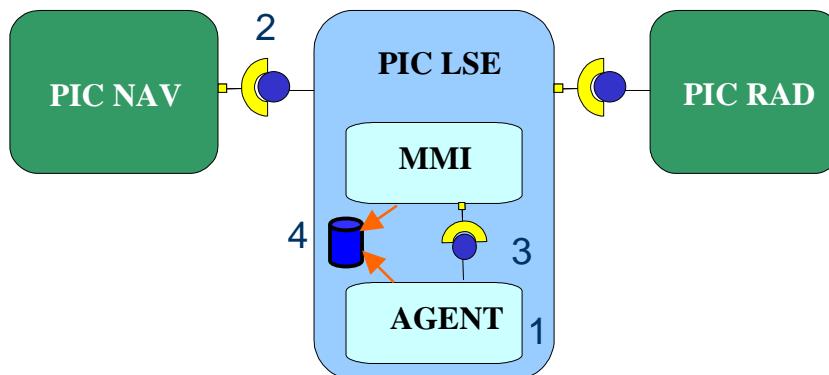



The screenshot shows the SUnit Camp Smalltalk 3.1 TestRunner interface with a different entity selected: LSE.Stp002BearingsManagement. The test method 'testStd002Initialization' is shown, and the status bar indicates 'Pass' and '0 run, 1h since last Pass'. Below the interface, a Microsoft Word document titled 'STD LSE-A.doc' is open, displaying a 'Software Test Description (STD)' for the 'TCS SYSTEM' prepared by THALES AIRBORNE SYSTEMS.

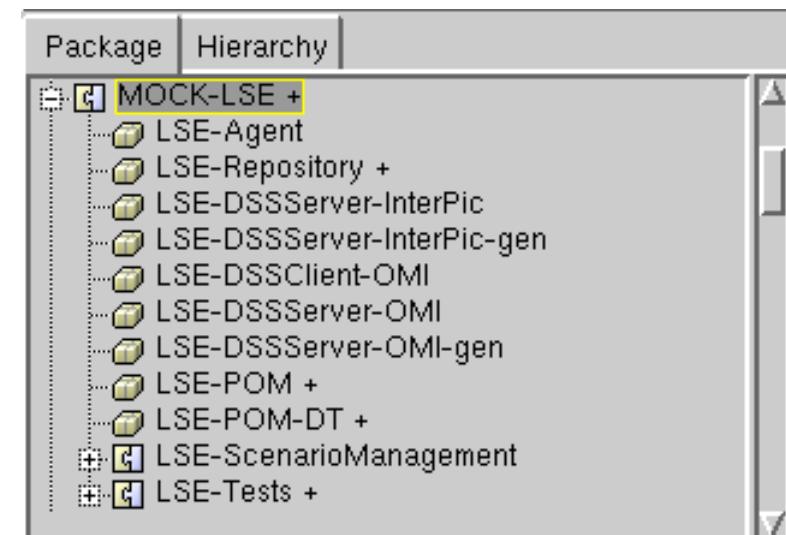
## a Mock = a smalltalk bundle than represents a PIC

- Same interfaces
- Replace the PIC and/or control the PIC
- DSS server (generated + implementation)
- DSS client
- PIC Datamodel (generated + customization)
- Tests

The LSE PIC



The LSE Mock





## Link between PicUnit and Smock :

- Define Model in Smock and Generate it in PicUnit
- Generate source code for PIC Developement
- Generate tests for PIC

## Integration with Continuous Integration Platform :

- Output TestResults in XMLUnit format
- Automaticaly test launching for each PIC changes (each commit in SCM)
- Instant Map of the project



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## Why we love it :

- RAD with regular and high quality language
- Efficient IDE
- Model oriented
- Easy code generation
- Very improved Debugger
- Swiss knife

but :

- Image concept in training context
- Important psychological first step
- Not widespread language

→ Is it the first model centric workshop ?



# Questions ?

# Engineering phase : the TFC



Technical Foundation Classes

=

components interfaces

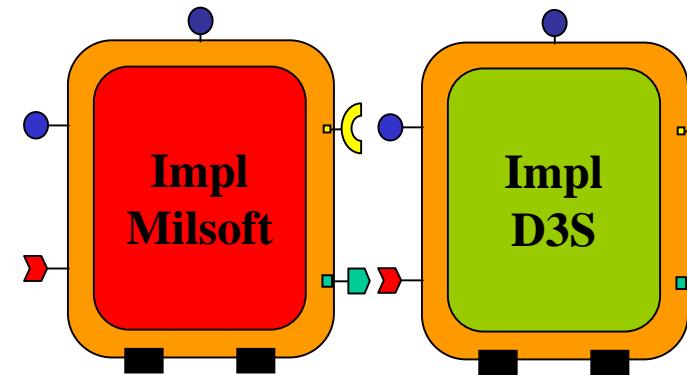
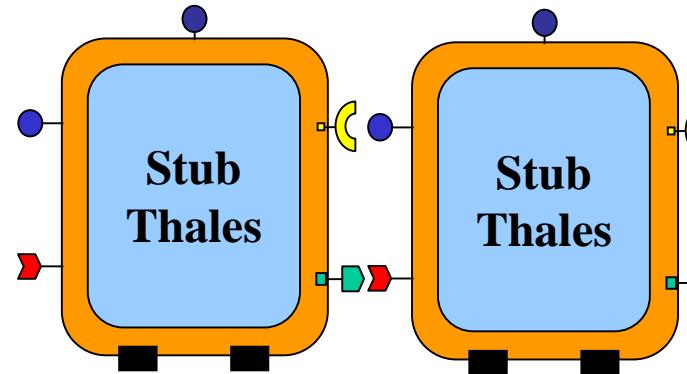
+

components stubs

+

components description

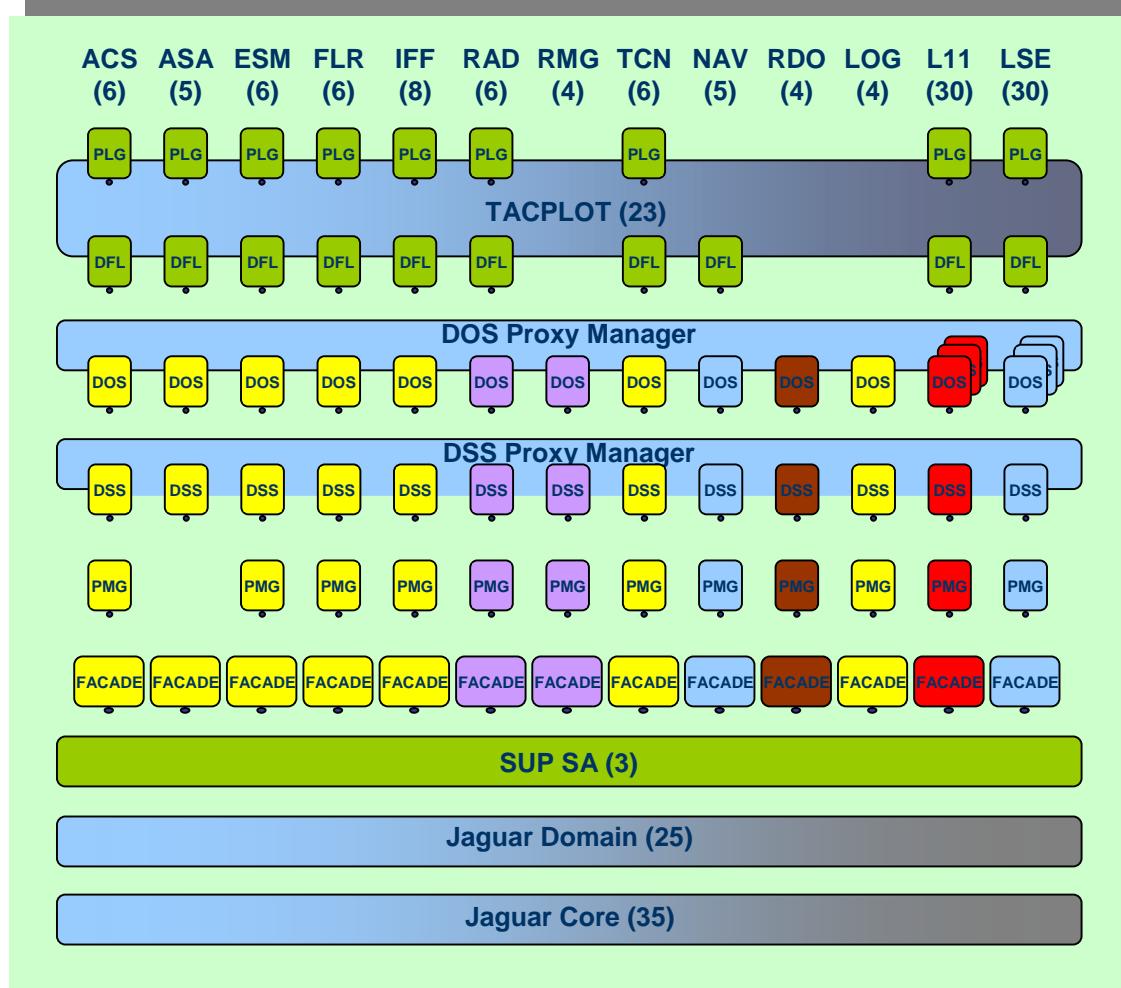
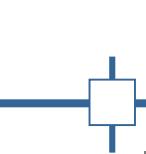
Component 1      Component 2



⇒ TFC provides a full contract (model, interface, stub, test)

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# Component cartography (partial)



PLG: Action On Selection Plugging

DFL: Data Flow

DOS: DOS Proxy

DOS: DSS Proxy

PMG: Panels Manager

Facade: SUP Facade

- Thales
- Havelsan
- Milsoft
- Silicomp
- Coframi
- D3S

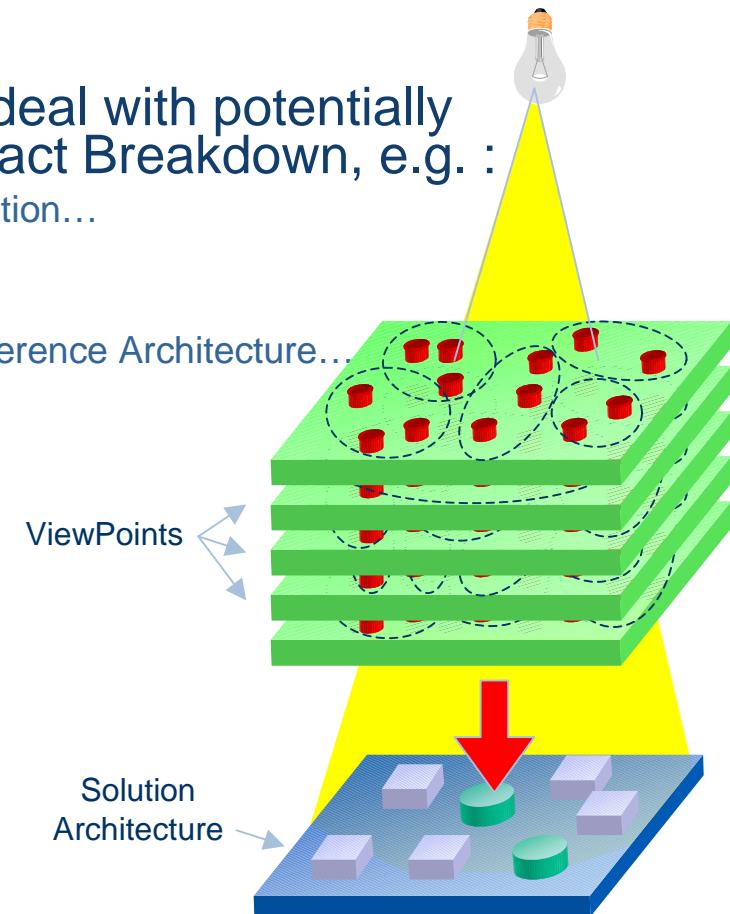
⇒ Total of more than 25 PICs and 300 Components

# Architecture Design: the Art of Compromise



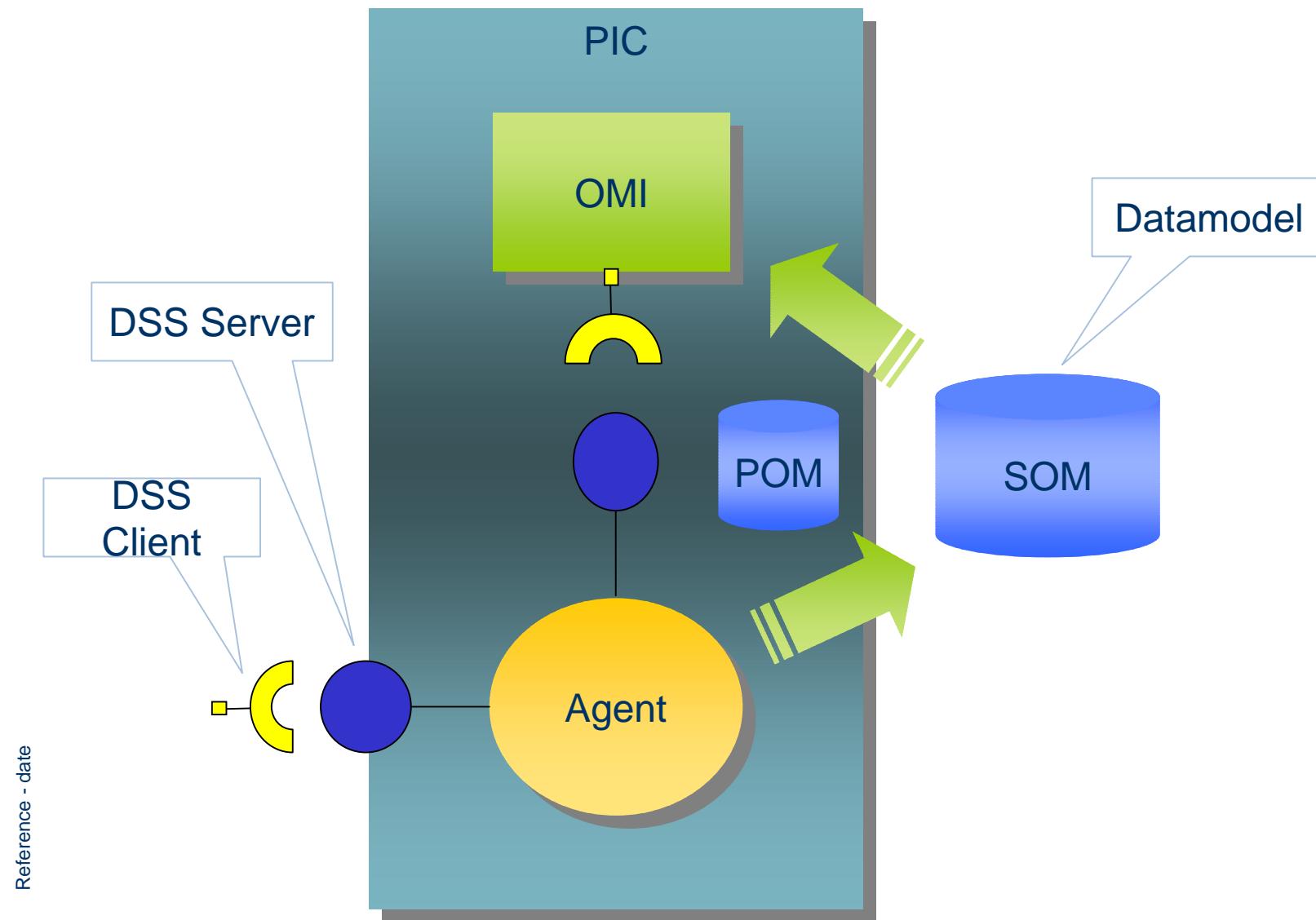
- The final Product Architecture must deal with potentially contradictory Constraints, which impact Breakdown, e.g. :

- Safety, Dependability / Fault Tolerance, Certification...
- Time-critical functional Paths
- Performances & required [hardware] Resources
- Mapping on [existing] hardware, middleware, reference Architecture...
- Functional grouping Consistency
- Dynamic Behaviour
- System Modes & States
- Complexity of internal interfaces
- Human Factors
- Dependency in System Integration
- Security
- Ease of sub-contracting
- Reuse, existing Legacy, Product Line Policy
- Modularity, Ability to evolve
- Available technologies, COTS...

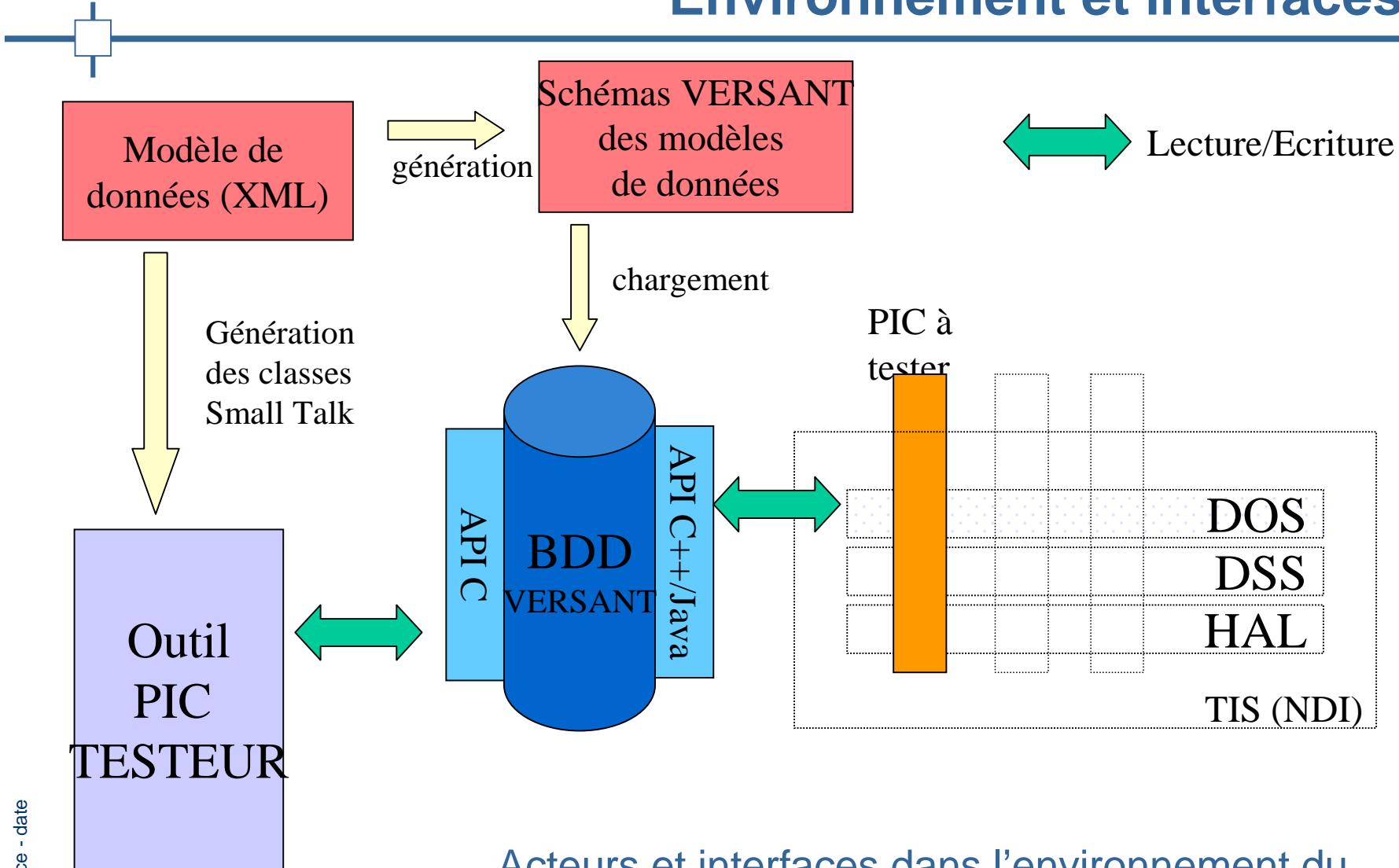


⇒ Building an appropriate Architecture means finding the most acceptable Compromise between these Viewpoints

# PIC structure



# Environnement et interfaces



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